Old Dominion University ODU Digital Commons

Engineering Management & Systems Engineering Theses & Dissertations

Engineering Management & Systems Engineering

Spring 1996

Dynamic Lot Sizing and Scheduling in a Multi-Item Production System

Padmanabhan Soundar Old Dominion University

Follow this and additional works at: https://digitalcommons.odu.edu/emse_etds

Part of the Industrial Engineering Commons, and the Operational Research Commons

Recommended Citation

Soundar, Padmanabhan. "Dynamic Lot Sizing and Scheduling in a Multi-Item Production System" (1996). Doctor of Philosophy (PhD), dissertation, Engineering Management, Old Dominion University, DOI: 10.25777/jqpq-dc44 https://digitalcommons.odu.edu/emse_etds/126

This Dissertation is brought to you for free and open access by the Engineering Management & Systems Engineering at ODU Digital Commons. It has been accepted for inclusion in Engineering Management & Systems Engineering Theses & Dissertations by an authorized administrator of ODU Digital Commons. For more information, please contact digitalcommons@odu.edu.



DYNAMIC LOT SIZING AND SCHEDULING IN A MULTI-ITEM PRODUCTION SYSTEM

by

PADMANABHAN SOUNDAR

B. Tech. July 1989, Indian Institute of Technology M.S. December 1991, University of Missouri-Columbia

A Dissertation submitted to the Faculty of Old Dominion University in Partial Fulfillment of the Requirements for the Degree of

DOCTOR OF PHILOSOPHY

ENGINEERING MANAGEMENT

OLD DOMINION UNIVERSITY May 1996

Approved by:
Han P. Bao (Director)
Billie M. Reed (Member)
Derya A. Jacobs (Member)
Ravi Mukkamala (Member)

ABSTRACT

DYNAMIC LOT SIZING AND SCHEDULING IN A MULTI-ITEM PRODUCTION SYSTEM

Padmanabhan Soundar Old Dominion University, 1996 Director: Dr. Han P. Bao

In this research, algorithms are developed to address the problem of dynamic lot sizing and scheduling in a single level (or single operation) production system. This research deviates from previous research in this area in that it does **not** have the kind of assumptions regarding the real world production system that normally were made to reduce the complexity of the problem. Specifically, this research explicitly considers finite capacity, multiple items, known deterministic dynamic demand, sequence dependent setup times and setup costs, setup carryover and variable backlogging. The objective is to simultaneously determine the lot size and the sequence of production runs in each period to minimize the sum of setup, inventory, and backlogging costs.

The research here is motivated by observations of a real world production system that has a highly automated operation with sequence dependent setup times. For problems of this kind, optimal solution algorithms do not yet exist and, therefore, heuristic solution algorithms are of interest. Two distinct approaches are proposed to address the problem. The first is a greedy approach that eliminates setups while potential savings are greater than the increase in inventory or backlogging costs incurred. The second approach solves the much easier single item problem optimally for each item and then adapts the solution to account for capacity constraints. An intelligent modification to the second approach is also tried where a "overload penalty" is used between

successive runs of the single product optimization algorithms. A common component of each approach is a dynamic programming algorithm implemented to determine the optimal sequence of production within each period and across the scheduling horizon. The addition of sequence dependent considerations introduces a traveling salesman type problem to the lot sizing and sequencing decisions.

The algorithms have been tested over several combinations of demand and inventory related cost factors. Specifically the following factors at two levels each have been used: problem size, demand type, utilization, setup cost, backlogging cost, and backlogging limit. The test results indicate that, while the performance of the proposed algorithms appear to be affected by all the factors listed above, overall the regeneration algorithm with "overload penalty" outperforms all of the other algorithms at all factor level combinations.

In summary, the contribution of this research has been the development of three new algorithms for dynamic lot sizing and scheduling of multiple items in a single level production system. Through extensive statistical analysis, it has been shown that these algorithms, in particular the regeneration algorithm with "overload penalty", outperform the conventional scheduling techniques such as no lot sizing and economic manufacturing quantity.

ACKNOWLEDGEMENTS

My thanks are extended to all the faculty and staff of the Department of Engineering Management for their kind support during my course of study. I extend my gratitude to my dissertation committee chair Dr. Han P. Bao for providing guidance and encouragement throughout my research. I also wish to express my thanks to the other members of my dissertation committee: Dr. Billie Reed, Dr. Derya Jacobs and Dr. Ravi Mukkamala, for their help in putting together the final document.

TABLE OF CONTENTS

		Page
LIST	OF TABLES	ix
Chapte	er	
I.	INTRODUCTION	
	Background	2 3 6 9
	Problem Attributes	10
	Conventions Statement of the Research Problem Objective of the Research Summary	12 14 18 19
II.	LITERATURE REVIEW	21
	Classification and Representation One Item Problems Multi-Item Uniform Demand Problems Multi-Item Dynamic Demand Problems Extensions of Original Formulations of Multi-Item Dynamic Demand Problems Summary	22 24 26 28 35 37
III.	THEORETICAL FOUNDATION	40
	Computational Complexity of Research Problem Single Item Problem with Backlogging. Traveling Salesman Problem (TSP). Summary	40 42 46 48
IV.	RESEARCH METHODOLOGY	50
	The Sequencing Problem Calculating Capacity Requirements Calculating Cost Changes Caused by Production Shifting	52 58 60

Chapte	r	Page
	Solution Improvement Techniques	71
	A Lot Shifting Algorithm (LS)	73
	A Regeneration Algorithm (RA)	76
	Regeneration Algorithm with "Overload Penalty" (ROP)	77
	Summary	83
V.	EXPERIMENTAL PROCEDURE	86
	Experimentation Goals	87
	Experimental Factors	89
	Performance Measure and Data Sets	95
	Computational Experience	98
	Analysis of Variance (ANOVA)	101
	Summary	106
VI.	ANALYSIS OF RESULTS	107
	Feasibility Results	107
	Test for Hypothesis 2	112
	Test for Hypothesis 1	114
	Other Results	120
	Summary	121
VII.	CONCLUSIONS, CONTRIBUTIONS AND FUTURE RESEARCH	123
	Conclusions	123
	Contributions	125
	Directions for Future Research.	127
	Summary	128
NOME	NCLATURE	130
REFER	RENCES	134
APPEN	NDICES	
A	NUMERICAL EXAMPLE	140
В	DEMAND AND SETUP DATA SETS	160
ט		100
С	OUTPUT GENERATED BY THE ALGORITHMS	189
D	DESIGN TO OF THE VETTE FOR SIGNIFICANCE	212

LIST OF TABLES

Γable		Page
1	Factors and factor levels used in experiments	94
2	Demand data sets	98
3	Complete list of inventory costs and maximum delay factors	99
4	Solution approaches	99
5	Some sample sizes for type 1 error = 0.05 and number of levels = 10 (Bratcher et al 1970)	104
6	Feasibility results for the LS algorithm	108
7	Feasibility results for the RA algorithm	109
8	Feasibility results for the ROP algorithm	110
9	ANOVA results for test of hypothesis 2	113
10	Best solution approach for each demand and inventory cost combination.	117
11	Relative performance of solution approaches	125

CHAPTER I

INTRODUCTION

This research deals with generation of production schedules that are used by manufacturing personnel to control the flow of material through a production system. Production schedules contain information on timing, sequencing, and sizing decisions for production lots in a manufacturing environment. Specifically, this thesis applies mathematical and operations research techniques to obtain good solutions to a particular class of real world production scheduling problems called dynamic lot sizing and scheduling problems.

Currently manufacturing resources planning (MRP II) is a very popular approach used by manufacturing enterprises to perform their scheduling operations. However when MRP II is used, it does not always give the best schedule. This is because it does not take into consideration all the factors that influence the operations in the production system. While consideration of more factors improves the quality of schedules generated, it also increases the complexity of the scheduling problem. Scheduling problems are differentiated from one another based on number of demand and production factors that are included in problem formulation.

Scheduling task in a real world production system is a complex endeavor and has been used as an important tool to control production costs. Potential benefits resulting from good schedules have made production scheduling a hot topic for research in the

International Journal of Production Research is the journal model used in this dissertation for references, figures and tables.

area of production and operations management. The nature of scheduling problems and the important role they play in controlling manufacturing costs is discussed next.

Background

For a manufacturing enterprise to succeed, it must keep production costs low and also deliver its customer orders on time. Production costs can be classified into basic production costs and inventory related production costs. Basic production costs include material costs, labor costs, machine setup costs, and overhead costs. Inventory related cost consists of inventory costs and backlogging cost. Inventory cost is the cost of capital tied up in inventory. Backlogging cost is related to the ability of a production system to meet customer due dates. Customer orders feature product requirements, quantity, and due dates. Meeting customer requirements is the ability to deliver products in the quantity ordered at the agreed upon time. When an organization cannot meet its promised due dates, it backlogs the order (assuming the order is not lost). The costs incurred when customer requirements are not met are not easily expressed in monetary terms. They include loss of customer goodwill and loss of sales revenues resulting from a shortage situation. One way of accounting for these intangibles is to levy a penalty, called backlogging cost, when a promised due date is allowed to slip and order is backlogged.

Basic production costs and ability to meet customer orders work as opposing forces, i.e., as the flexibility of the system is increased to meet customer requirements more setups are required, this causes an increase in the basic production costs and a

decrease in inventory related production costs. Performing operations in a way that minimizes production costs while meeting customer requirements is a non-trivial endeavor. Scheduling is an important tool available to management to obtain an optimum balance between trying to satisfy customer requirements and increasing production costs. Schedules control setup costs, inventory costs and backlogging costs incurred in a given situation. Since costs like material costs and labor costs are not directly affected by schedules, given two schedules the better one is the one that results in a lower sum of setup, inventory and backlogging costs.

In essence, the scheduling problem reduces to meeting several customer requirements for multiple products by the requested dates while keeping production costs to a minimum. Inputs to the schedule consist of information on demands, production rates, setup time and setup costs, and inventory and backlogging costs. The schedule generates information regarding the timing, size, and sequences of production lots. A real world batch production system where a non trivial scheduling problem exists is described next.

Motivating Case

This research follows observations made by the author at a batch production facility. To protect the proprietary information of the company involved, only a general overview of the production facility is described. However, sufficient detail is provided to grasp the essence of the scheduling problem. The facility consists of two stages, the first being a highly automated coating stage, and the second being a mostly manual packaging

stage. The facility serves the needs of about forty customers who place orders for one of the seventy or so finished products. There are about fifteen different coated products, some packaged in several styles to obtain the greater number of finished products.

Figure 1 illustrates the structure of the products produced in this facility. All products produced in the facility pass through the first stage before they get to stage 2.

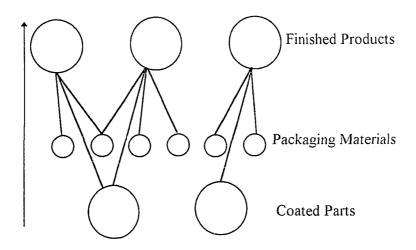


Figure 1: Product Structure Produced in the Facility

Raw material is brought into the first stage on motorized pallets which can accommodate various number of pieces based on the size of the product. A robot arm picks up pieces from the pallet and dips them in a chemical bath. The size of the product and the type of chemicals used determine the speed of the dipping process. Hence, the production rate of the product being coated is a function of its size and chemical coating applied. When production is switched from one product to another, one or more of the following has to be changed:

1. pallet carrying the tubes,

- 2. gripper of the robot arm used to dip the tubes, and/or
- 3. chemical solution in bath.

These changes result in significant setup times when production is switched from one product to another. Since the changes involved are not always the same, the setup time is dependent on the sequence of production. For example, switching between two products of the same size but different chemicals in the bath would require time for just changing the chemical in the bath. However, when switching between two products of different sizes and bath chemicals the pallet, gripper, and chemical solution have to be changed. Therefore, the second switch would take a longer duration.

Coated products are stored for up to five days, depending on product, before they are moved to the packaging department. Packaging is a team based operation. Packaging requirements, and thus team size, task assignment and production rate are product dependent. Packaging personnel are assigned to teams at the beginning of each shift. The composition and size of teams may vary between shifts, however they are not changed during shifts. The setup required to start packaging is minimal and even this is performed by a single lead operator before the start of each shift for all workstations. Hence, the setup time required for packaging operations is not significant.

Proper coordination of schedules between the two stages is required to meet the twin targets of reducing basic production costs and adequately satisfying customer requirements. However, the scheduling problem in the two stages are not of equal importance. For the following reasons proper scheduling in stage 1 is more important than scheduling in stage 2.

- Stage 1 adds more value to the product than stage 2 and hence must be more closely monitored.
- 2. Stage 1 is the sole internal source of semi finished products in stage 2, hence it is possible that stage 2 merely mimics the schedule in stage 1.
- 3. Stage 2 has greater flexibility, in that multiple products can be packaged simultaneously and production rate can be controlled by changing the number of teams allocated to a particular product. The rate of production is constant for a given product in stage 1. This allows stage 2 to quickly adapt to changes in stage 1.
- 4. Capacity available in stage 2 is greater than stage 1 and this absorbs inequalities in rates of production between stages.

In the above described production system customer requirements are tracked and schedules are generated using a MRP II system. The first stage is certainly the more critical of the two stages and the MRP II system focuses on production in this stage to determine the flow of products through the facility. The modus operandi of MRP II systems is discussed in the next section.

Production Control Using MRP II

MRP II systems are basically an extension of the original material requirements planning (MRP) systems that were first used in the fifties. In addition to MRP, modern MRP II systems help the manufacturing enterprise integrate all of its manufacturing support operations like accounting, quality control, sales, etc. For further description of MRP II functionalities and methodologies readers are referred to Turbide (1995) and

Wallace (1990) and references therein. MRP II is indispensable in a multi-stage production environment where proper coordination of material flow between stages is required. For this reason, they are used by a large number of manufacturing organizations to perform this task. Salomon (1991) has identified two important types of decisions that MRP II systems support:

- 1. Given the demand requirements in the final stage and the production information in each stage, MRP II coordinates the production of each item at each stage.
- Computation of lot sizes at each stage to meet demand requirements and minimize the inventory and setup costs.

MRP II systems use a hierarchical two phase approach to the scheduling problem. Initially, MRP II systems use economic manufacturing quantity (EMQ) calculations to compute the size of the production runs. This is followed by sequencing and timing decisions (the economic lot sizing problem) based on EMQ computations for each product. EMQ calculations are based on the average demand rate per period, production rate per period, setup cost, and inventory holding cost factor for each product. EMQ computations determine the cycle time for each product, the production time required and the cost of the schedule. Cycle time determines the lot size for the product and is essentially the duration of demand that is satisfied by a single lot. Elmaghraby (1978) presents a method to calculate the cycle time for each product. This procedure is repeated below.

The average cost per unit time for each setup when product i is produced in cycles of length τ_i is given by the equation:

$$SC_i = \frac{A_i}{\tau_i} + \frac{h_i r_i (1 - \rho_i) \tau_i}{2} \tag{1}$$

the value of τ_i^* the optimal value of τ_i can be obtained from the equation $\frac{dSC_i}{d\tau_i} = 0$

which yields the minimum cost cycle given by

$$\tau_i^* = \sqrt{\frac{2A_i}{h_i r_i (1 - \rho_i)}} \tag{2}$$

and a minimum cost of

$$SC_i^* = \sqrt{2A_i h_i r_i (1 - \rho_i)}$$
 (3)

From equation (2), optimal lot size is obtained as $Q_i^* = r_i \tau_i^*$, using these lot sizes for each product a economic lot size problem (ELSP) is solved to determine the sequence and the timing of production. EMQ calculations determine the lot sizes that minimize the inventory related production costs represented in equation (1) and this minimum cost value is given in equation (3). However, this method of calculating lot size is based on several assumptions which are not true in the production system that motivated this research. These assumptions oversimplify the problem by ignoring important aspects of the production environment and demand environment. This raises several issues when MRP II generated schedules are used in the motivating case. These issues are addressed next.

Shortcomings of Current Production Control System

Equation (1) which is minimized by the cycle time in equation (2) does not account for two important aspects of the inventory related production cost that exists in the motivating case:

- 1. sequence dependent nature of the setup costs, and
- 2. backlogging costs when customer due dates are missed.

Consideration of the first aspect would superimpose a traveling salesman type problem on the EMQ calculations, this issue has been addressed by Taha (1975).

However, ignoring the customer due date requirements is a fundamental flaw of the EMQ calculations. This limitation is imposed by equation (1) which artificially imposes a static demand rate over a infinite horizon in what is essentially a dynamic demand environment.

In the specific production system described above the customer orders and forecasts are used to convert date specific orders to average monthly demand values.

MRP II then calculates the lot sizes of the products from these static demand values and determines the timing of the production runs without regard to customer requested due dates. The products are shipped to customers as they are produced and the dates requested by customers are not adhered to.

In these cost calculations, backlogging cost aspects are ignored (customer due dates are ignored) while calculating both lot sizes and timing of production runs. In this particular facility, ignoring delivery dates requested by the customers has resulted in perennial backlogging for some orders. Even worse the potential loss to the

organization due to this loss of customer goodwill is not considered in scheduling decisions. The reason being that coating schedule is based on static demand when the actual demand is dynamic because MRP II systems based on EMQ cycle time computations are incapable of handling dynamic demand.

MRP II systems in facilities that use them contain information that is required to perform the scheduling operation. This fact and other beneficial features of MRP II can be taken advantage of by developing algorithms to work in tandem with MRP II systems. Therefore one popular alternative to address the shortcomings of MRP II systems has been the addition of modules to tackle specific situations. Along this same line, scheduling algorithms have to be incorporated for satisfactory application of MRP II system in the case discussed here. The complexity of the scheduling problems (and therefore complexity of the algorithms used to generate schedules) are influenced by a number of attributes (factors) that exist in the production environment and the demand environment where the schedule is to be applied.

Problem Attributes

The complexity of the scheduling problem increases as more attributes are taken into consideration in the problem formulation. While simplifying assumptions can be made to reduce problem complexity, ignoring one or more of these attributes affects the quality of the solution when it is implemented in a real world production system. The following attributes can be identified in the coating stage of the motivating case and must be properly accounted for:

- Known deterministic dynamic demand: The customers place orders in known
 discrete quantities that can vary with time. This can be linearly transformed into due
 date in the first stage by subtracting number of days required for packaging and the
 wait time between the stages.
- 2. Sequence Dependency: The sequencing of production is critical because setup costs are a function of this sequence. Also sequence of production must be determined to calculate feasibility of a schedule in terms of available capacity.
- 3. Setup Times: A known amount of time is used for setup when production is switched from one product to another. During setup, the resource is not available for production and there is a cost incurred for each setup. These durations are typically expressed in hours.
- 4. Setup Carryover: When a product is coated continuously over a period of several days setup is carried over from one day to the next, i.e. a separate setup is not necessarily required for each day of production.
- 5. Capacity Constraints: Available capacity is finite, and this must be considered in schedule development. When a generated schedule requires capacity in excess of what is available then the schedule is infeasible. Capacity is expressed as number of hours of production available in a day.
- 6. *Multiple Items*: Scheduling decisions must consider the fact that more than one product is competing for limited resources. The algorithm must ensure that only one product is scheduled on the machine at a given time.

7. Backlogging Limit: An upper bound on maximum days allowed for backlogging of orders. In general if customer orders are not met within a certain duration after the due date these orders are lost, i.e. the customer is no longer interested in the order. Therefore it is essential that customer orders are not backlogged for durations greater than that stated in this attribute. A backlogging cost is assessed for each unit of production backlogged for each day between the due date and maximum delay allowed.

All of the above attributes are included in the formulation of the scheduling problem addressed in this research. To facilitate the formulation of the problem and its solution certain conventions are used, these are described next.

Conventions

Before the research problem can be presented conventions required to understand the formulation are listed below.

1. Inventory costs, backlogging costs, and due date specifications are assessed at finite intervals within the scheduling horizon. These intervals differ in magnitude from setup time and capacity availability specifications. To capture this difference two distinct time buckets are used to define the problem. Inventory and backlogging cost computations, and due dates use large time buckets (also called periods). Setup times, and capacity are expressed in small time buckets. For example large time buckets can be days and small time buckets can be hours.

- Scheduling horizon is expressed as number of periods over which demand is to be scheduled.
- 3. Demand is expressed as hours of capacity required to meet the customer requirements. This is achieved by dividing the actual demand units by production rate. For example, if 800 units of a product is required and its coating rate is 400 per hour, then this demand can be expressed as 2 hours.
- 4. Setup costs are calculated as linear multiples of setup times and a setup cost factor.
 This factor can be the labor rate or any other value used to compute setup costs.
- 5. Inventory cost is calculated as the product of an holding cost and number of units of a product (expressed in hours of demand) carried from one large time bucket to the next. Similarly, backlogging cost is the product of a backlogging cost factor and hours of demand backlogged. Typically, backlogging cost factor is greater than holding cost.
- 6. The first product scheduled at the start of the scheduling horizon will require setup based on the last product produced on the day before the scheduling horizon. In the absence of this information the following convention is used. There exists a dummy product which is processed before the start of the scheduling horizon and must be reloaded at the end of the scheduling horizon. Without loss of generality, it is assumed that this product is 0 (zero) and that $s_{i0} = s_{0i} = 0 = S_{i0} = S_{0i}$.
- 7. If idle periods exist in a given schedule then the current setup in the machine is not tampered with during these times. To facilitate modeling a dummy product k is

assumed to be produced during the idle periods in the system \mathbf{a} $\mathbf{s}_{ij} = \mathbf{s}_{ik} + \mathbf{s}_{kj}$ and $\mathbf{s}_{ij} = \mathbf{s}_{ik} + \mathbf{s}_{kj}$ \forall \mathbf{i} , \mathbf{j} .

8. Demand information available has been modified to reflect the post coating waiting time and packaging time. This allows production scheduled for day t to be used to satisfy demand on day t.

With this information, the research problem can be formally stated as a mathematical programming problem.

Statement of the Research Problem

The formulation of the research problem as a mixed integer non-linear programming problem is described in this section. The objective is to determine the production schedule that minimizes the sum of inventory costs, backlogging costs and setup costs. Therefore, the objective function (TC) is

$$MIN \sum_{i} \sum_{t} (u_{it}h_{i} + v_{it}b_{i}) + \sum_{i} \sum_{j} \sum_{t} S_{ij}y_{ijt} + \sum_{i} \sum_{j} \sum_{t} S_{ij} \max(\beta_{it-1} + \lambda_{jt} - 1,0)$$
(4)

Basic production costs are invariant and hence are not included in the objective function. A production schedule is determined to be optimal if equation (4) is optimal for a feasible combination of x_{it} , y_{ijt} , λ_{it} and β_{it} . The feasibility of these variables is determined by their ability to satisfy the following constraints. The first set of constraints model inventory, inventory balance, backlogging, and the relationship between the binary setup variable and production scheduled:

$$u_{it} = \max(I_{it}, 0) \qquad \forall i, t \tag{5}$$

$$v_{it} = max(-I_{it},0) \qquad \forall i,t \tag{6}$$

$$I_{it-1} + x_{it} - I_{it} = d_{it} \qquad \forall i, t$$
 (7)

$$I_{it} \ge -\sum_{k=t-\alpha+1}^{t} d_{ik} \qquad \forall i, t \ge \alpha$$
 (8)

$$x_{jt} - M(\sum_{i} y_{ijt} + \lambda_{jt}) \le 0 \qquad \forall j, t$$
 (9)

Constraints stated in equations (5) and (6) determine whether a positive inventory or a backlogged situation exists at the end of period t. This ensures that proper cost multipliers are assigned to positive and negative inventories. Equation (7) is a typical inventory balance equation. This equation states that the inventory difference between the beginning and end of a period is the difference between the scheduled production in that period and demand in that period. Constraint (8) states that backlogging cannot extend beyond α days or, stated in another way, the amount of production backlogged can at worst be equal to the sum of demand over the past α -1 days. Constraint (9) ensures that if a product is to be produced during a day then it is either produced first in the day or it follows immediately after another product. The next set of constraints handle sequencing issues and avoid more than one setup for a product during a day:

$$\lambda_{it} + \sum_{j} y_{jit} \le 1 \qquad \forall i, t \tag{10}$$

$$\beta_{it} + \sum_{i} y_{ijt} \le 1 \qquad \forall i, t \tag{11}$$

$$\sum_{i} \left(\sum_{j} y_{ijt} - M \lambda_{it} \right) \le 0 \qquad \forall t$$
 (12)

$$\sum_{j} \left(\sum_{i} y_{ijt} - M\beta_{jt} \right) \le 0 \qquad \forall t$$
 (13)

$$\beta_{it} \ge \lambda_{it} - \sum_{j} y_{ijt} \qquad \forall i, t$$
 (14)

$$\sum_{i} \beta_{it} \le 1 \qquad \forall t \tag{15}$$

$$\sum_{i} \lambda_{it} \le 1 \qquad \forall t \tag{16}$$

$$\beta_{it} \ge (1 - \sum_{i} \lambda_{jt}) \times \beta_{it-1} \qquad \forall i, t$$
 (17)

Constraints (10) and (11) avoid cycling of production (multiple lots of the same product) within a period. Constraint (10) ensures that if a product is produced first on a day then it is not sequenced after other products on that day. Similarly, (11) guarantees that if a product is to be produced last in a day then it is not sequenced before other products on that day. Constraints (12) and (13) make sure that on days in which more than one product is produced the sequence is started and ended appropriately.

Constraint (12) states that there must exist at least one starting product if a sequence is to exist on a day. Equation (12) along with (10) guarantees that the first product sequenced on that day is at the head of the sequence. Constraint (13) makes sure that if 2 or more products are coated on a day then at least one of them is the last product.

Constraint (11) along with (13) ensure that the last product sequenced on a day is at the bottom of the sequence.

Constraint (14) states that if only one product is produced on a day then the last product is the same as the first product. Constraints (15) and (16) ensure that at most one first and one last product are sequenced on a day. Constraint (17) handles situations

when there is a whole day in which no production is scheduled, in which case, it ensures that the last product produced is considered as the current product for proper accounting of setup times. The penultimate set of constraints described below is capacity related:

$$\omega_{t} = C_{t} - \sum_{i} x_{it} - \sum_{i} \sum_{j} s_{ij} y_{ijt} - \sum_{i} \sum_{j} (s_{ij} \times max(\beta_{it-1} + \lambda_{jt} - 1, 0)) + min(\omega_{t-1}, \sum_{i} \sum_{j} s_{ij} \times max(\beta_{it-1} + \lambda_{jt} - 1, 0)) \quad \forall t$$
(18)

Constraint (18) imposes the capacity constraint on final schedule developed and also determines the idle time for each period. Idle time is calculated as the initial capacity from which is subtracted the total production scheduled and setup times consumed. It also accounts for setup carryover and makes sure that any excess capacity in the previous period is used for setup in the current period if so desired. Finally, we are left with constraints that determine feasible ranges for the variables used in formulating the problem and their initial conditions.

$$\omega_t, x_{it}, u_{it}, v_{it} \ge 0 \qquad \forall i, t \tag{19}$$

$$M \rightarrow \infty$$
 (20)

$$\beta_{it}, \lambda_{it}, y_{ijt} \in \{0, 1\} \qquad \forall i, j, t$$
 (21)

$$y_{iit} = 0 \qquad \forall i, t \tag{22}$$

$$\omega_0 = 0 \tag{23}$$

$$I_{i0} = I_{iT} = 0 \qquad \forall i \tag{24}$$

$$\beta_{i0} = 0 \qquad \forall i \tag{25}$$

$$\beta_{00} = 1 \tag{26}$$

Constraints (19), (20) and (21) define the ranges for the variables. Constraint (22) precludes two successive spots in a sequence being taken by the same product.

Constraints (23) and (24) initialize the inventory levels and idle capacity at the extremes of the production horizon. Finally, constraints (25) and (26) establish the assumption that a dummy product (product 0) is produced at the beginning of the scheduling horizon.

Objective of the Research

The objective of the research reported in this thesis is to formulate and make a contribution to the solution of a difficult lot sizing problem that exists in the real world. In this study, rigorous algorithms founded in mathematics and operations research are developed to tackle a real world scheduling problem stated in the previous section. Results obtained from this research are expected to lower the cost of schedules generated in manufacturing enterprises when compared to the current MRP II developed schedules. Although the research is motivated by an experience with a single case, this type of scheduling problem is not uncommon in the manufacturing arena.

The problem as formulated in the previous section is a NP complete problem.

This is stated without proof since much simpler problems have been established to be NP complete in the literature. Hence, optimal solutions to problems of the size that exist in the real world cannot be determined with reasonable computational effort. For this reason, this research focuses on obtaining good solutions to the class of problems

addressed here rather than obtaining optimal solution. This research deviates from previous research in the sense that it does not remove from consideration any of attributes in the production system that increases the complexity of the problem. The robustness of the algorithms developed here under various test conditions is studied. From the results of this study it is possible to obtain insight into the behavior of critical problem attributes.

Summary

In this chapter, an introduction was provided to the problem of dynamic lot sizing and scheduling in a capacitated multi-item production environment. The role of scheduling in controlling production costs was described. The motivating case was introduced and the shortfalls of using MRP II generated schedules in such an environment was discussed. The problem attributes that make scheduling in the motivating case a difficult problem were addressed. A formulation of the scheduling problem was discussed in detail and the objective of this research was stated.

The complexity of the simultaneously determining lot size, timing and sequence of production is a very difficult yet, very relevant problem in production and operations management. Several formulations of the problem have been addressed in the past.

Some researchers have attempted to solve problems with several machines in parallel in a single stage and also multi-stage problems. However, most of these attempts involve extensions of the single stage solution approaches. Besides, in a multi-stage system there

usually exists a single stage that acts as a bottleneck to the system. In these situations, schedules at the bottleneck controls the schedules adopted by other resources.

Hence, a vast majority of research efforts have focused on the single stage (level) production system. While some have been solved successfully, optimal solutions to a vast majority of the problems have eluded researchers. Some of these formulations and the approach used to solve the problems are discussed in the next chapter.

CHAPTER II

LITERATURE REVIEW

In this chapter a comprehensive review of past research relevant to the current research problem is presented. The aim is to draw implications from these published results for the solution approach proposed to address the research problem. Research in the area of lot sizing has been on going since before world war I. Hence, a complete review of all literature in this area is beyond the scope of this work. Only the most significant developments in this area and work that is directly relevant to the problem addressed here are reviewed

This chapter reviews previous research into different formulations and solution approaches to the single level lot sizing problems. Single level manufacturing processes are characterized by single level product structures, in which the product is converted from raw materials to a finished product by one machine. The characteristics of the lot sizing problem of the production facility in the motivating case are similar to single level lot sizing problems. In such environments product demands are assessed from customer orders and market forecast.

Past research in the area of single level lot sizing problems have been characterized based on which of the problem attributes described in the previous chapter have been accounted for. As more of those attributes are included in the problem formulation tackled, both the problem and solution complexity increase. In this chapter previous work is presented in order from the simpler problems to more difficult ones.

To facilitate the presentation of previous work, a classification and representation

scheme is used. This scheme is adapted to include attributes that are taken into consideration in the scheduling problem addressed here. A framework for classification and representation of single level lot sizing problems is presented next.

Classification and Representation

To classify and represent research in single level lot sizing problems a 6 field notation is used. This classification differs slightly from the one used by Salomon (1991), in that he does not consider problems that allow for backlogging. Two fields considered by Salomon, inventory cost structure and number of machines in parallel, are dropped from the notation used here. Inventory cost structure is used to classify inventory costs as either time dependent or time independent. All literature reviewed here consider time independent inventory costs as this is also the inventory cost structure of the problem addressed here. However, this does not preclude each product from having different inventory cost factors in multi-item problems. Since only a one machine single stage problem is considered here multi machine single stage problems are not relevant to the problem addressed here. On the other hand, backlogging exists in the motivating case and a field is added to classify research according to their backlogging considerations.

The notation used is D/C/B/N/SC/ST. Each field in this notation and the range of possible values is described below.

Type of Demand (D): This field can take two possible values c or d. c means a constant rate and d means deterministic and dynamic.

Capacity Constraints (C): This field is 0 if the problem does not consider capacity constraints, 1 if capacity constraints are considered.

Backlogging (B): This field can take on three possible values 0, i, v. If no backlogging is allowed then this field takes on a value of 0. If backlogging is allowed and unlimited then this field takes on a value of i for infinite, i.e. backlogging for up to the scheduling horizon is allowed. If backlogging is allowed but limited then this field takes on a value of v, which should be less than the scheduling horizon.

Number of Items (N): This number is equal to 1 if single item problem is considered, otherwise N is the number of items greater than 1.

Setup Cost (SC): This field contains letters A, SD, SI, and TD respectively zero setup costs, sequence dependent, sequence independent, and time dependent setup costs.

Setup Times (ST): If setup times are assumed to be zero then this field takes on a value of A, for absent. If setup times are sequence dependent then this field takes a value of SD. If sequence independent setup times are considered this field has a value of SI. Time dependent setup times are represented using TD.

The classification and representation schema is robust and can be used to represent scheduling problems spanning the entire spectrum from the easiest single item problems to the complex problem addressed here. Most early scheduling problems considered one item production systems, and analytical solutions to these problems were easily developed. Several formulations of the one item problem were addressed. Some of these are reviewed next.

One Item Problems

The easiest class of lot sizing problems is the c/0/0/1/SI/A, i.e. single item uncapacitated problem with no backlogging, sequence independent setup costs and no setup time. A solution to this problem was first proposed by Harris (1913). For an item i the optimal lot size for this problem is given by the equation $Q_i = \sqrt{\frac{2 \times r_i \times A_i}{h_i}}$. This lot size is called the economic order quantity (EOQ) and because of its simplicity is still used in some circles.

d/0/0/1/TD/A is a similar problem to the previous one except that demand is deterministic and changes from period to period. This problem is a slightly more difficult problem than the uniform demand problem. It was first solved optimally by Wagner and Whitin (1958). They proposed a dynamic programming algorithm that can solve problems of any duration. The algorithm optimally determines the periods of zero production and quantity of production in the non-zero periods. The authors used two principles to reduce the solution space searched by their algorithm.

1. Optimal solution would not include a situation where inventory is brought into a period and also non-zero production is scheduled in the period. Because, in the absence of capacity constraints, cost could be reduced by simply adding the inventory to the production in that period. For an arbitrary product i this can also be stated as $I_{it-1}x_{it} = 0$.

2. For a schedule to be optimal, $x_{it} = 0$ or $\sum_{t'=t}^{k} d_{it'}$ for some k, $t \le k \le T$ for \forall t and for an arbitrary product i. Any other value for x_{it} implies that the first principle is violated. This limits the search space for the optimal solution to $\frac{T(T+1)}{2}$.

The two criteria outlined above are popularly referred to as the Wagner-Whitin criteria and have been extensively used to improve the quality of solutions for more complex scheduling problems. An alternate solution approach to the same problem was presented by Silver and Meal (1969). Their procedure is founded on EOQ and provides results comparable to Wagner and Whitin with a reduced computational requirements.

EMQ computations presented in chapter I is another class of single item problems, these are represented by the notation c/1/0/1/SI/SI. This approach deviates from EOQ in that it incorporates production rates as well as demand rates and was reported initially by Koepke (1941).

The single item dynamic lot sizing problem with variable backlogging, d/0/v/1/TD/A, was independently solved optimally in the mid 60's by Zangwill (1966, 1969) and Manne and Veinott (1967). The work presented by these authors is reviewed in detail in chapter III as it forms the basis for one of the approaches to solving the research problem proposed here. A simple heuristic solution that is comparable in solution quality to the more computationally intensive optimal algorithms above is presented by Choo and Chan (1990). Their heuristic is based in a "eyeballing" technique that tries to strike a balance between the inventory, backlogging and setup costs.

In the presence of unlimited capacity single item problems can be successfully applied to multi-item production systems. The unconstrained capacity availability ensures that no conflict arises between schedules for any two or more products. The biggest drawback of the single item problem is that it represents very few real life production systems. On the other hand, the theory developed in solving these problems can be extended and applied to more complicated problems.

Multi-Item Uniform Demand Problems

This class of problems is represented by the notation c/1/0/N/SI/SI, and are popularly known as ELSP. When uniform demand exists and production is cyclical EMQ offers the optimal lot size for a single item problem with uniform demand. However, when this lot size is used in practice it is possible that the resulting schedule is not feasible. Infeasibility arises when the sum of the production times for products is greater than cycle time for one or more of the products in the system. Hsu (1983) proves that determining the lot sizes that are optimal as well as feasible is an NP-hard problem. There are two popular approaches to solving the ELSP problem. One is the common cycle approach first proposed by Hanssmann (1962) and the other is the basic period approach discussed by Bomberger (1963). The problem of determining the feasibility of a given data set is addressed by Davis (1990) and the sequencing issues that arise in ELSP solutions is addressed by Kim and Mabert (1995).

In the common cycle approach the cycle time is assumed to be equal for all products. This cycle time is made long enough to accommodate the production of each

item exactly once. The only remaining problem is to determine the optimal value of this common cycle. However, the solution obtained by common cycle approach is not optimal for the original problem. In the basic period approach each item can have different cycle times, the only restriction being that the cycle time be a integer multiple of a basic period. In this approach values of basic period and the integer multipliers of each product have to be computed. Elmaghraby (1978) has reported that the basic period approach offers better solutions than common cycle approaches.

ELSP is widely used in all MRP II software packages. If the demand pattern is close to uniform then its use can be justified. However, in many situations ELSP solutions are used even in the presence of dynamic demand. A case in point is the production facility described in the motivating case. The aim of the current research is to obtain lower cost schedules than that obtained using MRP II in the presence of dynamic demand. However, the effort involved in generating a feasible ELSP schedule for a given set of demand and production data is beyond the scope of this research. Hence, for comparison purposes the lower bound of the ELSP schedule costs were used.

Elmaghraby (1978) and Davis (1990) have shown that the lower bound to the cost of a schedule is obtained by producing in lot size of EMQ for each item. The cost of the schedule can only increase by adjusting the lot size in an attempt to obtain feasibility (either using common cycle or basic period). Since MRP II systems use ELSP solutions it is more than fair that the schedule costs obtained using EMQ calculations are used to represent the cost of MRP II schedules. This is specially significant because, if the proposed methods produce lower cost schedules than one obtained using EMQ

calculations it can be claimed that the proposed methods provide a better way to handle the scheduling problem than MRP II. The cost calculations and sequencing issues are addressed in detail in chapter IV.

The biggest drawback of the ELSP formulation is that it assumes a uniform daily demand rate. In batch manufacturing environment this assumption is rarely true. To overcome this problem researchers included the actual demand patterns requested by customers into the problem formulation. This category of research is reviewed in the next section.

Multi-Item Dynamic Demand Problems

Dynamic demand problems are also referred to as finite scheduling problems. These problems consider demand occurring over a finite scheduling horizon unlike the uniform demand problems that consider a uniform daily demand occurring over a infinite horizon. The original formulations of these problems are represented by the notation d/1/0/N/SI/A. In a comprehensive review Salomon (1991) found that three types of problems have been addressed in the literature.

- 1. Capacitated Lot Sizing Problem (CLSP): Here multiple items are produced in a period but no setup is allowed to be carried over to the next period.
- 2. Continuous Setup Lot Sizing Problem (CSLP): This problem allows for setup to be carried from one period to another but restricts production to one item per period.
- 3. Discrete Lot Sizing Problem (DLSP): This problem is similar to the CSLP problems except that quantity produced in each period is either zero or equal to the full capacity.

Capacitated Lot Sizing Problem (CLSP)

This is by far the most common type of multi-item dynamic demand problem addressed in the literature. Mathematically, CLSP is formulated as follows:

$$MIN\sum_{i=1}^{N}\sum_{t=1}^{T}(A_{i}w_{it} + h_{i}I_{it})$$
(27)

subject to

$$I_{it-1} + x_{it} - d_{it} = I_{it}$$
 $\forall i, t$ (28)

$$\sum_{i=1}^{N} x_{it} \le C_t \qquad \forall \ t \tag{29}$$

$$x_{it} \le \left(\sum_{k=t}^{T} d_{ik}\right) w_{it} \qquad \forall i, t \tag{30}$$

$$x_{it}, I_{it} \ge 0 \qquad \forall i, t \tag{31}$$

$$w_{it} \in \{0, 1\} \qquad \forall i, t \tag{32}$$

The objective function, expressed by equation (27), minimizes the sum of setup and inventory costs across all products and all periods. Equation (28) is the same as equation (7) and is the inventory balance equation. Equation (29) introduces capacity constraints and equation (30) limits production in a period to only the future requirements. Equations (31) and (32) place limits on the range of acceptable values for the variables. Chen and Thizy (1987) have proven that CLSP is an NP-Hard problem except when all setup costs are assumed to be zero. Two approaches have been used to obtain good solutions to the problem. These are:

- 1. mathematical programming based approach, and
- 2. heuristic "common sense" approach.

The problem reduces to a single item problem if capacity constraint expressed by equation (29) can be relaxed. Elimination of this constraint allows the problem to be solved as a series of inter linked single item problems. A Lagrangean relaxation based approach is used by Thizy and Van Wassenhove (1985) to reduce the problem to a transportation problem which can be solved optimally. However, in order to ensure the feasibility of the final solution they use a sub-gradient optimization technique to calculate the values of the Lagrangean multipliers. While their approach does not guarantee optimality the primary contribution of their work is to suggest a method to obtain good lower bounds to the original problem. A similar relaxation approach that relaxes the demand constraints is presented by Chen and Thizy (1987). An approach that relaxes the integer requirements of the solution is suggested by Maes and Van Wassenhove (1986). The decimal solutions are rounded off using different techniques to attain feasibility. Another approach based on column generation is discussed by Cattrysse et al. (1990). Finally, a procedure that solves the problem for few products at a time is presented by Kirca and Kokten (1994). Subsequent subsets are limited in capacity availability and their inventory carrying capability, and this ensures feasibility of solution over the entire set of products.

Most of "common sense" approaches involve the following features:

- 1. a method to prioritize products,
- 2. a rule to allocate limited production capacity, and
- 3. a feasibility routine.

A forward pass algorithm is presented by Eisenhut (1975). Production lots for period I are based on marginal cost coefficients, determined using equation (33) shown below.

$$U_{i}(t) = \frac{A_{i} - h_{i} \sum_{k=1}^{t} (k-1)d_{ik}}{t^{2} \times d_{it}}$$
(33)

Equation (33) represents the rate of change in per period costs incurred by including demand in period t into the current lot. At lower values of t large reductions in per period costs can be expected however, as t increases the per period costs decrease at a lesser rate and finally begin to increase. The lot sizes for period 1 are found by increasing t one period for that product which shows the greatest potential savings for each additional unit pulled into the current lot. This is repeated until capacity constraints are violated or no additional cost savings are possible for any product. Then the time axis is re-labeled so that the current period is period 1. The drawback of this approach is that it may assign small lots for production in the earlier period and this leads to infeasibility in the latter periods. A feasibility check provided by Dixon and Silver (1981) for this approach is limited by the fact that it only specifies total production in each period but does not determine the size of lots for individual products for feasibility.

A forward pass algorithm with a backtrack routine for feasibility is discussed by Lambrecht and Venderveken (1979). They use a different equation for calculating the marginal cost coefficients which is represented by the equation shown below

$$U_{i}(t) = \frac{A_{i} + h_{i} \sum_{k=1}^{t-1} (k-1)d_{ik} - h_{i} \times (t-1)^{2} \times d_{it}}{t(t-1) \times d_{it}}$$
(34)

Equation (34) is obtained by comparing the marginal cost of including demand in period t into current production to the cost of including demand in period (t-1). A positive value of $U_i(t)$ indicates that inventory related costs can be reduced by including demand in period t into current production. If at any point in their forward sweep they find that capacity is not sufficient to meet remaining demand they go back to previous periods and increase production lot assignments of earlier periods.

An alternative approach to ensure feasibility is presented by Dixon and Silver (1981). They perform a look ahead computation for cumulative production requirements up to period t (for all t) so that no infeasibility will arise in period t+1. That is, the production in period t must exceed the total amount demand exceeds capacity in all future periods. Their completely unidirectional approach sometimes requires inclusion of production lots that have negative marginal savings coefficients.

Production in the later periods can be straitjacketed by the commitments in earlier periods in the above approaches. To avoid this, an approach that first considers the periods that provide maximum savings is proposed by Dogramaci et al. (1981). Initially the lot sizes are assumed to be equal to demand in that period. This is followed by shifting of production first to reduce costs and then to achieve feasibility. The algorithm is a four step algorithm that will find a feasible solution if one exists.

Comparison of the performance of these heuristics is studied by Maes and Van Wassenhove (1986). The results indicate that the Dogramaci heuristic outperforms the others when tight capacity constraints exist, i.e., capacity utilization of resource is high. When a definite trend in demand can be established then the look ahead approach of

Dixon and Silver out performs the other two. Time variability and lumpiness was found to have little effect on the performance of these heuristics.

Continuous Setup Lot Sizing Problem (CSLP)

Mathematically the CSLP is formulated using the mixed integer program approach:

$$MIN\sum_{i=1}^{N}\sum_{t=1}^{T}(A_{i}\times\max(0, w_{it}-w_{it-1})+h_{i}I_{it})$$
(35)

subject to $I_{it-1} + x_{it} - d_{it} = I_{it} \qquad \forall i, t$ (36)

$$\sum_{i=1}^{N} x_{it} \le C_t \qquad \forall \ t \tag{37}$$

$$x_{it} \le \left(\sum_{k=t}^{T} d_{ik}\right) w_{it} \qquad \forall i, t \tag{38}$$

$$\sum_{i=1}^{N} w_{it} \le 1 \qquad \forall \ t \tag{39}$$

$$x_{it}, I_{it} \ge 0 \qquad \forall i, t \tag{40}$$

$$w_{it} \in \{0, 1\} \qquad \forall i, t \tag{41}$$

The objective function in equation (35) reflects the potential cost savings due to setup carryover. This formulation states that when the same product i is produced in period t-1 and t ($w_{it} = 1$ and $w_{it-1} = 1$) then there is no setup cost incurred for production in period t. Equations (36), (37) and (38) are the by now familiar inventory balance, capacity constraint, and lot size limitation equations respectively. Equation (39) limits production to a single item in a period. Equations (40) and (41) control the possible

range of values for the variables. CSLP has been proved to be an NP-Hard problem by Florian et al. (1980). However, fairly large problems have been solved with reasonable computational effort. This indicates that CSLP is more tractable than CLSP and hence no heuristic approaches are required to solve the standard CSLP problem. The optimal solution is obtained by a heuristic based approach upon on the relaxation of the capacity constraints and is reported by Karmarkar and Schrage (1985).

Discrete Lot Sizing and Scheduling Problem (DLSP)

The only difference between the DLSP problem and CSLP problem is that, in DLSP the quantity produced in each period is either assumed to be zero or equal to the full production capacity.

$$MIN\sum_{i=1}^{N}\sum_{t=1}^{T}(A_{i}\times\max(0,w_{it}-w_{it-1})+h_{i}I_{it})$$
(42)

subject to
$$I_{it-1} + p_i w_{it} - d_{it} = I_{it} \qquad \forall i, t$$
 (43)

$$\sum_{i=1}^{N} w_{it} \le 1 \qquad \forall t \tag{44}$$

$$I_{it} \ge 0 \qquad \forall i, t \tag{45}$$

$$w_{it} \in \{0, 1\} \qquad \forall i, t \tag{46}$$

The objective function (42) is the same as the one used in CSLP formulation. The inventory balance equation (43) is modified to reflect the new restriction on the size of production lots in a period. Equations (44), (45) and (46) are same as (39), (40) and (41). The DLSP formulation does not use the x_{it} decision variable because it considers only all or nothing situations. Fleischmann (1990) presents a branch-and-bound

procedure using Lagrangean relaxation for determining the lower bounds and feasible solutions to a given problem.

The original formulations for multi-item lot sizing under dynamic demand were reviewed in this section. Most of the researchers have focused their attention on the CLSP formulation. This is because a vast majority of real world dynamic lot sizing and scheduling environments reflect the attributes included in this model. To improve the applicability of these solution procedures several extensions have been proposed, and they will be reviewed in the next section.

Extensions of Original Formulations of Multi-Item Dynamic Demand Problems

A combination of CLSP and CSLP problem formulations with setup times, /d/1/0//N/A/SI, is considered by Aras and Swanson (1982). Depending on the sequence of production, if a product is produced in an adjacent period, then it is possible to avoid setups and thereby not lose capacity. The authors propose a "common sense" practical approach to solve the problem. The biggest drawback of this formulation is that it does not consider setup costs and only the cost of inventory is reduced and also sequencing is limited to first and last products in a period. A similar formulation which includes setup costs has been solved for small problems Gopalakrishnan et al. (1995). These authors formulate the problem as a mixed integer linear program (MILP), and solve a problem with five products over 12 periods optimally. The applicability of their approach to much larger problems was not discussed.

The CLSP formulation has been extended to include setup times, d/1/0/N/SI/SI, by Trigeiro et al. (1989) and Trigeiro (1989). Consideration of setup times increases the complexity of the problem, for example determining if a given data set has a feasible solution is NP complete. Trigeiro (1989) has proposed an approach similar to the one used Lambrecht and Vanderveken (1979) with setup time considerations. Then a multipass algorithm is used to shift production for cost reductions and to attain feasibility. Trigeiro et al. (1989) propose a mathematical approach that uses Lagrange multipliers to calculate the lower bound, in the second stage of the algorithm a feasibility routine is implemented. Work done by Trigeiro (1989) and Trigeiro et al. (1989) show that solution approaches that were developed for zero setup time environment can be successfully modified and used in the presence setup times.

A mathematical approach to solving the DLSP problem with setup times is discussed by Cattrysse et al. (1993). Here the DLSP is formulated as a set partitioning problem and a dual ascent column generation heuristic is used to solve the problem. The heuristic generates both lower and upper bounds for the problems which allows for the measurement of solution quality.

The DLSP problem with sequence dependent setup costs, d/1/0/N/SD/A is studied in Fleischmann (1994). Here, the authors use a traveling salesman formulation of the problem with time windows to determine the lower bounds to the problem. An alternative approach to solve the problem involves the use of various estimating methods to convert the sequence dependent setup costs to sequence independent costs. Six such approaches are tested by Dilts and Ramsing (1989) across a spectrum of problem

parameters. The authors found that simple rules to estimate the setup costs are superior to the more complex rules.

This completes the review of literature. The results obtained by previous researchers has a direct bearing on the solution approach proposed for this study. A summary of literature review and implications of this review on the current research are discussed in the following section.

Summary

From the above discussion it can be said that significant advances have been made in accurately solving the simpler problems. However, approaches to obtain good solutions to more complicated problems have not been widely studied. Specifically, none of the researchers have considered all the problem attributes presented in chapter I simultaneously. The assumptions made in the past while proposing solution methods to problems were not always realistic and this hinders the widespread use of finite scheduling methods in the real world. On the other hand this research is focused on a very significant scheduling problem in the real world. Substantial differences exist between the scheduling problem addressed here and those proposed and studied in the past. However, the theory that has been developed by previous researchers can be used to solve the current problem.

The current problem is basically an extension of a combination of the original CLSP and CSLP problem formulations, and can be represented by the notation d/1/v/N/SD/SD with setup carryover. The formulation that comes closest to the one

researched here was presented by Gopalakrishnan et al. (1995). However, there are key differences between their formulation and the one addressed here.

- 1. Variable backlogging is allowed in our formulation, no backlogging is allowed in their formulation.
- 2. Sequence dependent setup costs and setup times are incorporated here. Only sequence independent setup cost and times are used in their formulation.
- 3. Their solution procedure restricts the size of the problem that can be addressed. however, even large problems can be solved using the approach presented here.

Although a more difficult problem is addressed here the method proposed here takes advantage of several theoretical foundations laid by previous researchers. The contributions most relevant to the problem addressed here are:

- 1. research that deals with complexity of different types of dynamic demand problems.
- 2. optimal solution to the single item dynamic demand problem with backlogging, and
- 3. solution approaches to the traveling salesman problem to sequence the production.

While the first two contributions are in the area of finite scheduling the third topic is a difficult open problem in the realm of operations research. Contributions of the first category are important because they provide the basis for showing that the problem addressed here is a difficult problem, and justify the use of heuristics to solve this problem is justified. The second and third categories are important because the algorithms developed to solve the research problem are based on these concepts. Hence, in the next chapter the computational complexity of the research problem is discussed

followed by a review of theory behind essential concepts that form the crux of the algorithms developed to solve the problem.

CHAPTER III

THEORETICAL FOUNDATION

The primary aim of this chapter is to discuss the implications of theoretical concepts developed by previous researchers on the solution approach proposed here. Before a solution approach can be proposed for the research problem it is essential that the computational complexity of the problem be addressed. If it can be shown that the problem addressed here belongs to a class of NP-Complete problems then this justifies the use of heuristics to solve the problem. In the first part of this chapter, it will be shown that the research problem addressed here justifiably belongs to the class of NP-Complete problems. This justifies the use of heuristic algorithms to solve the problem. The algorithms proposed for the solution of the research problem are theoretically grounded on certain principles developed by previous research in the area of lot sizing in dynamic demand environments and other related operations research problems. These principles include the optimal solution to the single item problem with backlogging (d/0/v/1/TD/A) and a heuristic solution to the traveling salesman problem.

Computational Complexity of Research Problem

The computational complexity of a combinatorial problem is related to the computational behavior of most efficient algorithms designed to obtain its optimal solution. This behavior is measured by the running time of the algorithm i.e., that is the number of elementary operations such as additions and comparisons required to solve the problem. This running time is related to the size of the problem addressed i.e., the

number of bytes occupied by the input data. If a problem of size n can be can be solved by an algorithm that is polynomial function of n (example: n, n², n³,...) then the problem can be considered to be well solved. Polynomial algorithms have been developed for a few types of combinatorial optimization problems (Lawler 1976). However, a vast majority of such problems can only be solved by enumerative methods which may require exponential time.

A problem is said to be NP-Complete if it can be proved that no polynomial solution exists for the problem. However, such a proof will not be attempted here. Instead, it is conjectured that the research problem is NP-Complete based on proven results published by others. It has been well established that the single item CLSP is a NP-Complete problem by Florian et al. (1980). This result has been extended to cover multi-item CLSP (Chen and Thizy 1987) and CSLP (Florian et al. 1980). The research problem can be reduced to a combination of CLSP and CSLP problems if no backlogging is assumed ($\alpha = 0$). This means that the reduced problem is at least as hard as CLSP or CSLP. The solution space for the problem is only increased by consideration of backlogging, which does not make the problem any easier. Hence, it can be stated with reasonable certainty that the problem addressed here is NP-Complete and that no polynomial time algorithms exist to determine the optimal solution to the problem.

(48)

Single Item Problem with Backlogging

Optimal solutions to this problem was developed in the mid 60's by Zangwill (1966, 1969) and Manne and Veinott (1967). For an arbitrary product i the problem that they addressed can be formulated by the following equations:

$$MIN\sum_{t=1}^{T} (A_{i}w_{it} + h_{i}u_{it} + b_{i}v_{it})$$
(47)

subject to $u_{it} = \max(I_{it}, 0) \quad \forall t$

$$v_{it} = \max(-I_{it}, 0) \qquad \forall \ t \tag{49}$$

$$I_{it-1} + x_{it} - I_{it} = d_{it}$$
 $\forall t$ (50)

$$I_{it} \ge -\sum_{k=t-\alpha+1}^{t} d_{ik} \qquad \forall \ t \ge \alpha$$
 (51)

$$x_{it} - M(w_{it}) \le 0 \qquad \forall \ t \tag{52}$$

$$I_{i0} = I_{iT} = 0 (53)$$

$$u_{it}$$
, v_{it} , $x_{it} \ge 0 \qquad \forall t$ (54)

$$w_{it} \in \{0, 1\} \qquad \forall \ t \tag{55}$$

The objective function (47) minimizes the sum of setup, inventory and backlogging costs. Equations (48) and (49) ensure that appropriate cost multipliers are used in the objective function. Equation (50) is the familiar inventory balance equation. Equation (51), similar to equation (8), constrains the maximum backlogging allowed. Equation (52) makes certain that a setup cost is assessed every time a production lot is scheduled. Significant differences between this formulation that studied in this research are listed below:

- 1. Single item vs. multi-item.
- 2. Unconstrained capacity availability vs. finite capacity availability.
- 3. No setup time vs. significant sequence dependent setup times.
- 4. No setup carryover vs. setup carryover allowed.
- 5. Pre-defined setup costs (may be time variant) vs. sequence dependent setup costs. The scheduling problem with additional attributes considered in this research can be solved by superimposing the additional attributes on the optimal solution algorithm to the formulation presented above. The authors propose a dynamic program based solution procedure to optimally solve the above formulation. To reduce the solution space that must be searched for the optimal solution, a theorem called the regeneration point theorem is used.

For an arbitrary product i, a period t is called a point of regeneration if inventory at the end of the period is zero ($I_{it} = 0$). A schedule is said to have a regeneration point property if;

- 1. Between any two periods in which production occurs, there exists one and only one regeneration point. This can be formally stated using mathematical terms, for an arbitrary product i; given t<k and $x_{it} > 0$; $x_{it+1} = x_{it+2} = \dots = x_{ik-1} = 0$; and $x_{ik} > 0$ there exists a period t*, $i \le t * \le k \infty$, which is a regeneration point.
- 2. Between any two regeneration points there exists only one period with production greater than 0. Formally for an arbitrary product i, given t < k and $I_{it} = I_{ik} = 0$ there exists a period t', $t \le t' \le k$ such that

$$x_{jt''} = \sum_{k'=t+1}^{k} d_{k'} \quad if \ t'' = t'$$

$$0 \ otherwise$$
(56)

Equation (56) states that all demand between periods t and k is met by production in period t' and that all other periods in that durations have no production. The importance of the regeneration point property lies in the usefulness of the regeneration point theorem which states that "There is an optimal schedule which has the regeneration point property". Proof of this theorem is available in the original papers. The dynamic programming algorithm proposed by the authors works as follows: Step 1. Calculate $c_{tk}^{t'}$ the cost of producing a lot in period t' to meet all demand between the regeneration points of t and k

$$c_{tk}^{t'} = A_i + h_i \sum_{t''=t'+1}^{k} (t''-t')d_{it''} + b_i \sum_{t''=t+1}^{t'-1} (t'-t'')d_{it} \qquad \forall \ t, t', k$$
 (57)

Equation (57) states that the cost of producing a lot in period t' to meet demand for periods (t+1) to k is the sum (1) of setup cost in that period for that product, (2) the inventory cost for producing demand for periods (t+1) to k in period t' and (3) the cost of backlogging demand in periods (t+1) to (t'-1).

Step 2. Calculate $c_{tk} = \min_{t+1 \le t' \le k} c_{ik}^{t'}$ and save the value of t' that provides the lowest cost.

In this step, the best period to produce in order to meet demand between periods (t+1, k) is identified and the cost of the having regeneration points in periods t and k is computed.

Step 3. Determine the next regeneration point that minimizes the cost of going from the current regeneration point to regeneration point T. For this the cost of all possible cost combinations from the current regeneration point to T are computed and compared. Formally stated:

For each regeneration point t equation (58) determines the next regeneration point (k)

that minimizes the inventory related production costs. The duration between two

$$f_t = \min_{t < k \le T} (c_{tk} + f_k)$$
 $t \in (0, T - 1)$ and $f_T = 0$ (58)

successive regeneration points determines the size of the production lot that is produced between the points, and is equal to the total demand in that duration.

Step 4. Forward pass to determine optimal production lots. Given a regeneration point in period 0 then the next best regeneration point can be identified using step 3.

Subsequently regeneration points can now be determined by values saved from step 3.

This is repeated until the regeneration point in T is reached.

The four step algorithm described above determines the best periods of production to meet a known deterministic dynamic demand in the presence of backlogging. This algorithm is at the crux of some of the methods proposed in chapter IV to solve the research problem addressed here. While the above algorithm can be used to determine the size of the production lots, it is also essential to determine the sequence of production. In this regard, the traveling salesman problem addressed in the next section plays a crucial role.

Traveling Salesman Problem (TSP)

TSP is a network problem to determine the least cost sequence of nodes to visit so that each node in the network is visited exactly once and the trip ends in the starting node. The TSP formulation is widely applied in the real world to determine the sequence of travel between cities for people and places. In this context, the cost to be minimized is the travel cost between cities. In this study, TSP formulation is used to minimize the sum setup costs across the horizon incurred when switching production between products. TSP is a NP-Hard problem. However there are several algorithms that take advantage of the nature of the cost matrix to determine optimal solutions to fairly large problems within reasonable computational effort. Two classes of heuristics have been proposed in the literature to solve the TSP problem (Mathur and Solow 1994):

- 1. Tour construction heuristics: build a tour (sequence) by including sequentially one node at a time until all nodes are used.
- 2. Tour improvement heuristics: start with a given tour and attempt to construct better tours with progressively less total cost.

A sequence construction heuristic, also called the cheapest-insertion algorithm, (Mathur and Solow 1994) is used in this research and detailed below. The basic idea is to start with a sequence of products and sequentially create larger sequences by:

- 1. selecting a product to be included into the sequence, and
- 2. determining where to insert the selected product.

For every product that is not yet included in the sequence the algorithm calculates the best point of insertion for that product. The product that provides the

least additional increase in the setup cost of the sequence is selected for insertion at its lowest cost insertion point. The TSP sequencing heuristic is listed below.

Initialize the TSP sequence:

```
\begin{split} & \phi_1 = \mathrm{i}, \ \phi_2 = \mathrm{j} \ni S_{ij} + S_{ji} = \underset{i',i'' \in \psi}{\mathit{MIN}} \left( S_{i'i''} + S_{i''i'} \right) \\ & k = 2 \\ & \psi = \text{all products but i and j} \\ & \psi \text{hile } (\psi \neq \varnothing) \\ & \{ \\ & \phi_{k+1} = \phi_1 \\ & \phi_m = \mathrm{j} \ni S_{\phi_{m-1}j} + S_{j\phi_m} = \underset{i \in \psi}{\mathit{min}} \underset{l \in 2, k+1}{\mathit{min}} \left( S_{\phi_{l-1}i} + S_{i\phi_l} \right) \\ & k + + \\ & \text{remove j from } \psi \\ & \} \end{split}
```

Once the two initial products have been identified there exists two possible insertion points. The third product can either be inserted between ϕ_1 and ϕ_2 or between ϕ_2 and ϕ_1 . Similarly, in subsequent insertion point considerations insertions between the last product and first product must be considered. To accommodate this possibility equation (59) creates a dummy position at (k+1) and sets the product at this position equal to one in position 1. Equation (60) identifies both the best product, that has not been inserted into the cycle yet, and the point of insertion of the product. For each item, it calculates the cost of the sub-sequence consisting of its two adjacent nodes and thus

identifies the best insertion point for the product if it offers the lowest insertion cost amongst all products.

Once the node with the lowest insertion cost is identified then the tour is updated to reflect this new insertion. The tour is updated by merely incrementing the positional value of the nodes after the new insertion points by one. If the insertion point is between k and (k+1) then the new insertion point is reset to 1. The length of the tour is incremented and the selected product removed from the list of un-inserted nodes. The above procedure is repeated until all products are inserted into the sequence. While, this algorithm does not determine the optimal sequence of production, it provides a good approximation to the optimal solution. The context in which the sequencing issue arises in solving the research problem justifies the use of a heuristic.

Summary

In this chapter, three theoretical concepts that play a large part in the functioning final algorithms have been presented. The complexity of the research problem was compared with other lot sizing problems addressed previously. A dynamic programming approach to optimally solve the single item problem with backlogging was described. Finally a TSP heuristic that plays a large role in sequencing production is detailed.

Research methodology consists of determining the heuristic algorithms that can be used to solve the formulated problem. These heuristic algorithms used to generate schedules for research problem must address the issues of lot sizing and sequencing. No solution procedure has been developed yet to determine lot sizes in the presence of

capacity constraints. However, the regeneration theorem can be used to optimally determine lot sizes in the absence of capacity constraints. Therefore, the regeneration theorem is incorporated into the heuristics proposed here. The cost of the final schedule is dependent on the sequence of production (due to sequence dependent setup considerations). The TSP algorithm described in this chapter is used to determine the sequence of production of production lots.

Thus far a foundation has been laid to detail the methodology used to successfully address the research problem. The primary purpose of research methodology is to unequivocally layout the sequence of steps that has been used to solve the research problem. Research methodology developed to solve the research problem is complicated and unique. Chapter IV deals with the details of this methodology.

CHAPTER IV

RESEARCH METHODOLOGY

The research problem addressed here is NP-Complete, which precludes the use of exact approaches to solve problems of the size that exist in the real world. It is for this purpose heuristic approaches are proposed to address the problem. The aim of each heuristic approach is to determine the production lots and sequence of production for each item in each period that minimize the sum of inventory, backlogging and setup costs. For a solution to be accepted, it must be feasible. For a schedule to be feasible, it must satisfy the following two constraints:

- 1. capacity requirements in each period must be less than or equal to capacity available in each period, i.e., equation (18) of chapter I must be satisfied, and
- 2. the maximum delay criteria must be satisfied, this ensures that orders are not backlogged more than α days as represented in equation (8) of chapter I.

The original problem formulation has too many variables and constraints to be effectively considered in tandem. To facilitate solving the problem, the strategy adopted here is to fragment the original problem, solve the individual parts, and then combine the parts to obtain a solution to the original formulation. Any solution approach to the research problem must address three issues:

- 1. determine the size of production lots for each product in each period,
- 2. sequence the production lots within each period and across the schedule horizon, and
- convert an infeasible schedule to a feasible schedule without unduly affecting the schedule costs.

Each of the above is a substantial problem on its own merits. However, the situation is further complicated by the inter-relationships between the problems. These are not three separate problems; on the contrary, they are intertwined because:

- the feasibility of a schedule is linked to the size of the production lot for each item in each period and the setup time required for each item (this is dependent on the sequence of production),
- the determination of lot sizes depends on capacity considerations (a feasibility requirement), and since setup times are sequence dependent, capacity requirements cannot be accurately determined until the sequencing issue is resolved, and
- sequencing is a function of non zero production lots scheduled in each period which in turn depends on the capacity availability in each period.

Hence, any approach to solving the research problem must iteratively solve the lot sizing problem, the sequencing problem and also address the feasibility issue. In the past, when a new formulation of a dynamic demand lot sizing problem had been addressed two broad ways have been proposed to handle the problem:

- 1. develop a "common sense" approach to solve the problem, and
- 2. use optimal solutions to sub-problems and adapt these solutions to obtain feasible solutions to the current problem.

In this research, one extension of the first approach and two variations of the second approach have been developed resulting in a total of three new algorithms. The three algorithms essentially differ in their approach to addressing the lot sizing issue. The initial lot sizing problem is handled in one of the following ways.

- The "common sense" approach is a lot shifting procedure similar to one used by Dogramaci et al. (1981).
- The first variation of optimal solutions for sub-problems uses the regeneration theorem to solve the single item lot sizing problem with backlogging optimally for each item.
- 3. The second variation, of optimal solutions for sub-problems, solves the single item lot sizing problem with backlogging for each item with a "overload penalty" between successive items to reduce infeasibility of the final solution. This is a more intelligent application of this approach than algorithm 2.

The three algorithms differ primarily in the way in which they approach the initial lot sizing problem. Other parts of the algorithms are similar in the three cases, and for this reason the overlapping features of the algorithms will be addressed first. The overlapping features are; sequencing method, capacity requirement calculations, procedure to eliminate infeasibility, and a optimality condition test. The solution to the sequencing problem is founded upon the TSP heuristic discussed in the previous chapter. The details of the sequencing problem and the solution to the problem are described in the next section.

The Sequencing Problem

The sequencing problem consists of determining the optimal sequence for production of lots within each period and across the scheduling horizon. A dynamic programming methodology adopted to solve the sequencing problem is detailed here. A

dynamic program is defined by stages, states and policy costs. The cost of a sequence is only dependent on sequence dependent setup costs, and not inventory/backlogging costs. In this case, each day is a stage, and states within a stage are uniquely defined by the first and last products produced on that day. For example, if there are n products scheduled on a day then there are $\frac{n}{2}P$ possible states in that stage. While the 2 products produced first and last identify the state there are, (n-2) other products that have to be incorporated into the state between the first and last products. Each item incurs a setup cost based on the sequence of production. The policy cost for a state is the minimum cumulative setup cost associated with the state. Furthermore, this cost depends on the sequence of production of the (n-2) products between the first product and last product.

For example, if items a, b, c and d have non zero lots scheduled in a day. Then, there are $\frac{4}{2}P = 12$ possible states in that stage. Representing each state by the pair of first and last items produced in the stage we get twelve pairs as follows; { (a,b), (a,c), (a,d), (b,a), (b,c), (b,d), (c,a), (c,b), (c,d), (d,a), (d,b), (d,c) }. For the state represented by the pair (a,b), two possible sequences are possible (1) $a \rightarrow c \rightarrow d \rightarrow b$ and (2) $a \rightarrow d \rightarrow c \rightarrow b$. The cost of sequence 1 is $S_{ac} + S_{cd} + S_{db}$ and the cost of sequence 2 is $S_{ad} + S_{dc} + S_{cb}$. The cost of the state (a,b) is the one that gives the lowest cost of all possible sequences. Hence, for each state in each stage the best sequence between the first and last items must be solved to determine the cost of the state.

This problem is similar to a TSP introduced in chapter III, except that we have our starting and ending nodes pre-defined. A TSP like problem addressed here is called the pseudo TSP. Pseudo TSP, like the original problem, is a NP complete problem

(Lawler et al. 1985) and optimal solution is difficult to calculate when the number of products becomes large. Typically, very few products are scheduled for production in a day. In such instances, the pseudo TSP can be solved by complete enumeration. n! possible solutions must be compared if complete enumeration is used. However, as n becomes large, n! becomes untractable and a heuristic procedure is used to solve the problem. In this research, the sequencing issues within each state are addressed as follows:

- 1. when the number of products scheduled for a day is ≤ 7 , the TSP problem is solved optimally using complete enumeration, and
- 2. when the number of products scheduled for a day is > 7, the TSP problem is solved using a tour construction heuristic described in chapter III.

To solve a TSP problem of size n by complete enumeration the cost of all n! possible combinations must be computed and compared. Thus, when 7 products are scheduled in a day the size of the TSP problem is 5, since the first and last products are already defined. This calls for 5! = 120 sequences to be compared and selection of the lowest sequence amongst all possibilities.

The use of a heuristic for larger problems is justified because, in a real life batch production environment, seldom does one encounter more than 7 products scheduled for production in a day. This is true even if the total number of products in the system is much greater than 7. However, sequencing greater number of products may be required in the early stages of problem solving. It is for this purpose that the heuristic approach is mostly used. The sequencing algorithm detailed below is a two phase algorithm. In the

first phase the cost of all possible states are calculated by solving a pseudo TSP. The second phase invokes a dynamic programming algorithm to calculate the lowest cost sequence across the scheduling horizon.

Phase 1: Cost of States

A state is defined by the first and last products sequenced in a period. These two products are passed to this phase of the algorithm by the dynamic programming procedure described in phase 2. Now the pseudo TSP is reduced to determining o_{kt} for $k = 2, ..., n_{t-1}$ given o_{1t} and o_{n_tt} . The TSP solution procedure used is based on the value of n_t . One of the following procedures is used to determine the sequence and cost of the sequence.

- 1. If $n_t \in [0, 1]^1$ then $C_{TSP} = 0$
- 2. If $n_t = 2$ then $C_{TSP} = S_{o_{1t} o_{2t}}$
- 3. If $n_t > 2$ and $n_t < 8$ then $C_{TSP} = \min_{k}(\Theta_k)$ where $k = 1, 2, \ldots, \frac{n_t}{2}P$,

$$\Theta_k = \sum_{i=2}^{n_t} S_{m_{i-1}^k m_i^k} \text{ where } m_i^k \text{ is the ith product on the kth tour, also } m_1^k = o_{1t} \text{ and }$$

 $m_{n_t}^k = o_{n_t t} \ \forall \ k$, t. All possible values of m_i^k are pre-computed. The complete enumeration routine determines all possible sequences of production. The procedure then compares the cost of each of these sequences with others to find a minimum cost sequence.

 $[\]begin{array}{l} ^{1} \ \ if \ n_{t}=0 \ then \ dummy \ product=o_{1t}=o_{n_{t}^{t}} \ \ (indicating \ a \ idle \ period) \\ if \ n_{t}=1 \ then \ o_{1t}=o_{n_{t}^{t}}=i \ \textbf{3} \ x_{it}>0 \end{array}$

4. If $n_t \ge 8$ then a modified tour construction heuristic similar to the one described in chapter 3 is used. Certain modifications are required to accommodate the fact that the initial and the final nodes are pre-determined. The basic idea however remains the same.

Initialize:
$$l=2$$
; $\phi_1 = o_{1t}$; $\phi_2 = o_{n_t t}$ (61)

while $(\psi \neq \emptyset)$

$$\{ \phi_m = j \ni S_{\phi_{m-1} j} + S_{j \phi_m} = \min_{i \in \psi} \min_{k \in 2, l} (S_{\phi_{k-1} i} + S_{i \phi_k})$$

$$l++$$
remove j from ψ

$$\}$$

Equation (61) initializes the starting point and ending point of the sequence to the pair products that define the first and last products in period t. Equation (62) inserts a product j at position m such that this insertion causes the lowest possible increase in the sequence. This equation differs from equation (60) in that it does not allow insertion of products after the last product in the period. The procedure is repeated until all products have been positioned. The cost of the sequence is obtained using the equation (63) shown below.

$$C_{TSP} = \sum_{k=2}^{n_t} S_{\phi_{k-1}\phi_k} \tag{63}$$

Phase 2: Dynamic Programming Algorithm

This phase of the sequencing algorithm incorporates the TSP procedure described above into a much broader dynamic programming algorithm. In this algorithm, the states within each period that provide the optimal sequence for the entire scheduling horizon are identified.

Initialize:
$$n_{T+1} = 1$$
, $n_0 = 1$, $PC_{T+1}^1 = 0$, $fp_{T+1}^1 = 0$, $lp_0^1 = 0$, $\theta_{T+1} = 1$
for $(t = T \text{ to } t = 0)$

$$\{ \sigma_t^k \ni PC_t^k = \min_{m \in [1, \theta_{t+1}]} PC_{t+1}^m + S_{lp_t^k} fp_{t+1}^m + C_t^k \quad \forall \ k \in [1, \theta_t]$$

$$\{ (64) \}$$

The initializations provide transition between the current scheduling horizon and adjacent horizons and also add completeness to dynamic programming algorithm at its boundaries. Equation (64) identifies, for each state k in the current stage t, the state in the next stage that gives the lowest cost sequence between the current stage and T. For example, if this state is m then m is the state that minimizes the sum of:

- 1. the lowest cost of getting from that state m in stage (t+1) to T,
- 2. the setup cost to switch production between the last product that defines state k and the first product that defines the state m in stage (t+1), and
- cost of the sequence returned by the pseudo TSP algorithm between the items that define the first and last products of the sequence.

By progressing from the last stage to the first stage the algorithm successively finds the lowest cost between all the intermediate states and the final stage. Once the

best state in the next stage has been identified, for each state, the problem now reduces to one of retrieving the best sequence. This is achieved as follows.

for
$$(t = 1 \text{ to } t \le T)$$

$$\{k \leftarrow \sigma_{t-1}^{k} \qquad (65)$$

$$\sigma_{jt} = \xi_{t}^{k} \ \forall j \qquad (66)$$

In equation (65) the state k in period 1 that gives the lowest cost sequence between periods 1 and T is identified. Equation (66) then saves the sequence of items that defines state k. The algorithm successively identifies the best sequence in the next stage until stage T is reached. This algorithm is versatile in that it even accommodates intermediate periods during which no production lots are scheduled, using one of the conventions stated in chapter I.

The most important aim of the sequencing algorithm is to reduce the setup cost component of the inventory related production costs. Also, accurate sequencing is required to exactly calculate the capacity requirements for each day. Calculation of these capacity requirements once a sequence has been identified is detailed in the next section.

Calculating Capacity Requirements

With information available on production lot sizes for each product in each day and the best possible way to sequence the production, both across the horizon and within each day the capacity requirements to meet the schedule can be determined. If the

capacity required is greater than capacity available then this indicates that the schedule is infeasible and modifications are required to make it feasible. The method used to calculate slack capacity and overloading is detailed below:

for (t=1 to t<=T)

$$q_{t} = C_{t}$$

$$q_{t} \leftarrow q_{t} - \sum_{i=1}^{n_{t}} x_{it}$$

$$q_{t} \leftarrow q_{t} = \sum_{i=1}^{n_{t}} x_{it}$$
(67)

 $q_{t} \leftarrow q_{t} - s_{o_{n_{t-1}t-1}o_{1t}} - \sum_{j=2}^{n_{t}} s_{o_{j-1t}o_{jt}}$ (68)

Initially the slack on each day is set equal to capacity available. Equation (67) then reduces this value by an amount equal to the sum of all the production lots scheduled in that period. Equation (68) uses the sequences generated by the sequencing algorithm to further deduct setup time requirements to meet the schedule. Besides the setup time required for the products produced on that day the equation also takes into account the setup time required between the last product in the previous period and the first product in the current period. However, if the same product is produced on two successive days then it is possible that the same product is sequenced last on the previous day and first on the next day and thus avoid a setup. Once the capacity requirements are computed, it can be determined if the schedule is feasible or infeasible. An infeasible schedule is one in which there exists at least one period in which $q_1 < 0$.

To achieve feasibility either entire lots or parts thereof can be transferred to other periods with positive slack. This shifting of lots may affect both the setup cost and the inventory/backlogging costs of the schedule. Given a multiplicity of lot shifting options an infeasibility elimination procedure must try to achieve feasibility with lowest increase in the total schedule cost. Therefore, it is necessary to calculate the change in the total cost caused by shifting a lot to achieve feasibility. However, the change in setup costs cannot be calculated accurately because setup cost for a lot is dependent on the previous product in the sequence and when production is shifted the sequence changes which in turn changes the cost of the setup. To avoid this infinite looping the setup cost savings can be estimated. A similar problem arises for setup times when lots are shifted from one period to another. Capacity in the target period is checked for its ability to accommodate the lot. In addition, to lot size sufficient capacity must exist to allow for setup. Since sequence is not known an estimate of the setup time must be used. These estimating techniques and a method to accurately calculate the change in inventory/backlogging cost is described in the next section.

Calculating Cost Changes Caused by Production Shifting

First, the problem of estimating the changes in setup costs is addressed. To overcome the problem described in the previous section it is necessary to convert the sequence dependent setup costs and times for a product to sequence independent costs and times. Dilts and Ramsing (1989) describe various ways in which this might be achieved and also report that simple methods prove to be most effective. Especially,

those that deviate most from the expected value of setup provide the best results.

Accordingly, two estimating methods to be tried here.

- MIN: assigns the minimum of all setup values possible for the product. This technique grossly underestimates the cost and time required for setup. Since the potential setup cost savings are underestimated, this technique tends to reduce the size of the initial lots. However, lower setup time requirements allow for greater mobility of lots in the feasibility elimination routine. s_i = min s_{ji} ∀ j ≠ i and S_i = min S_{ji} ∀ j ≠ i.
- 2. MAX: assigns the maximum of all setup values for the product. This technique grossly over estimates the cost and time required for setups. Since the potential setup cost savings are greater than actual more lots are clubbed together initially producing large lot sizes. However, large setup time requirements affect the possibility of moving lots to other periods to achieve feasibility.

$$s_i = \max_j s_{ji} \quad \forall \ j \neq i \text{ and } S_i = \max_j S_{ji} \quad \forall \ j \neq i.$$

While the changes in the setup cost can only be estimated the changes in the inventory/backlogging cost can be determined accurately. This change in cost must be computed with respect to the original demand requirements. Before the inventory/backlogging cost for product μ (H $_{\mu}$) can be calculated inventory/backlogging for μ for each period (I $_{tt}$) must be calculated.

$$I_{\mu t} = I_{\mu t - 1} + x_{\mu t} - d_{\mu t} \quad \forall \ t \in (1, T) \ and \ I_{\mu 0} = 0$$
 (69)

Equation (69) is obtained directly from constraint (7). This equation merely states that inventory at the end of a period is essentially the sum of inventory at end of previous period and production in the current period from which is subtracted demand in the current period. The inventory/backlogging cost for the product is calculated using equation (70) shown below. This equation is similar to the inventor/backlogging cost component of the objective function described in equation (4).

$$H_{\mu} = \sum_{t'=1}^{T} k h_{\mu} I_{\mu t'} - (1-k) b_{\mu} I_{\mu t'} \quad \text{where } k = \frac{1 \text{ if } I_{\mu t'} > 0}{0, \text{ otherwise}}$$
 (70)

When production is shifted from an overloaded period t to a period with slack capacity tg, the production lots of the affected periods are re-computed as $x'_{\mu t} \leftarrow x_{\mu t} - \eta$ and $x'_{\mu t g} \leftarrow x_{\mu t g} + \eta$. Now the inventory in each period is recomputed using the new production lots as $I'_{\mu t}$ using equation (69). Following which the new inventory/backlogging cost is re-computed as H'_{μ} using equation (70). Finally, the change in inventory/backlogging cost is given by equation (71).

$$\Delta H_{\mu} = H'_{\mu} - H_{\mu} \tag{71}$$

In this section, the methods used to calculate the changes in setup costs and inventory/backlogging costs caused by production shifting was described. These computations are widely used when lot shifting is considered to eliminate infeasibilities. To overcome infeasibilities either the setup for the first product must be moved to the previous period or production must be shifted to another period; this can be done in several ways. All possible options are evaluated before one is selected, the routine that eliminates infeasibility is discussed in the next section.

Eliminating Infeasibilities

Overloading may be detected in a period as a result capacity requirement calculations. These must be eliminated to make the schedule feasible. Sometimes this can be achieved without incurring extra costs or even at some savings however, in most occasions additional costs must be incurred. The production lot selected is the one that contributes most to eliminate overtime at the lowest cost or maximum savings. To achieve feasibility:

- (1) setup time for the first product sequenced in that day can be moved to the previous period,
- (2) production can be moved backward, or
- (3) production can be moved forward.

Options (2) and (3) can be achieved in more than one way. All combinations are tried before selecting the option that provides the move with the lowest cost (maximum savings) per unit of overload eliminated. A brief overview followed by the complete details of the algorithm is presented below.

Overview of Algorithm to Eliminate Infeasibilities

Eliminating infeasibilities is a complex task because of a number of options have to be tried to determine the lowest cost option. A general overview of the approach adopted here is shown below. This approach first attempts to eliminate infeasibilities without additional costs if possible.

```
Initialize: \nabla = \infty
for (t=2 \text{ to } t \leq T)
{
      if \ (q_t < 0 \ \& \ q_{t\text{-}1} \ge |q_t| \ \& \ s_{o_{n_{t\text{-}1}t\text{-}1}o_{1t}} \ \ge |q_t|)
                                                                                                                                       (72)
      {
            q_{t-1} \leftarrow q_{t-1} + q_t
                                                                                                                                       (73)
           q_t = 0
                                                                                                                                       (74)
for (t=1 \text{ to } t \leq T)
{
      while (q_t \le 0)
            \nabla = \infty
            for (i \in \Pi_t)
                  \mu, \eta, \nabla, tg = MIN(production shifting)
                                                                                                                                       (75)
            if (\nabla = \infty)
                                                                                                                                       (76)
                   exit()
             else
             {
                  x_{\mu t} \leftarrow x_{\mu t} - \eta
                                                                                                                                        (77)
```

```
x_{\mu tg} \leftarrow x_{\mu tg} + \eta (78)

re-sequence and calculate capacity
}
```

First an attempt is made to move the setup for the first product sequenced on a day to the previous period. Equation (72) ensures that this move is made only if infeasibility in the current period is eliminated. This makes certain that the setup time for the first product in the current period is not accounted for twice when the algorithm enters the while loop. An infeasibility in a period can be eliminated in this step only if two conditions are satisfied:

- slack is available in the previous period, and this is at least as large as the overloading in the current period, and
- 2. the setup time required for the first product is at least as large as the overloading in the current period.

Once it is determined that infeasibility can be eliminated by shifting setup time, equation (73) recalculates slack in previous period and (74) eliminates the overloading in the current period. This method achieves feasibility without additional costs and is tried first for all periods with infeasibilities, there is no need to re-sequence after this step. If infeasibilities persist then the best combination of target period, quantity and item to move is determined by executing equation (75) for each item with a production lot in the overloaded period. If there exists a feasible target period in either the forward or

backward direction production shifting function will find them, when no feasible target periods exist equation (76) provides escape condition that prevents infinite looping. The size of the lots are reassigned in equations (77) and (78). This may require that the sequence and capacity availabilities to be re-computed. The production shifting function, tries both forward and backward shifts, is at the heart of eliminating infeasibility and it is described in complete detail next.

The Production Shifting Function

}

This function determines the item and the quantity to shift to the target period in the scheduling horizon that produces the lowest cost per unit of infeasibility eliminated.

The routine is implemented for all t with infeasibility and all i.

for
$$(t' = 1 \text{ to } t' \le T \&\& t' \ne t)$$
{

if $(x_{it'} > 0 \& q_{t'} \ge x_{it})$
{

$$z = \frac{\Delta H_i - S_i}{x_{it}} \tag{80}$$

$$if(z < \nabla) \tag{81}$$

$$\nabla = \mathbf{z}; \ \mu = \mathbf{i}; \ \eta = \mathbf{x}_{it}; \ \mathbf{tg} = \mathbf{t}'; \tag{82}$$

if
$$(q_{i'} \ge (x_{it} + s_i))$$
 (83)

$$z = \frac{\Delta H_i}{x_{it}}$$
 (84)
$$if (z < \nabla)$$
 (85)
$$\nabla = z; \mu = i; \eta = x_{ii}; tg = t';$$
 (86)
$$\}$$

$$if (x_{it} > 0 \& q_t > 0)$$
 (87)
$$\{ v = \min(|q_t|, x_{ii}, q_t)$$
 (88)
$$z = \frac{\Delta H_i}{v}$$
 (89)
$$if (z < \nabla)$$
 (90)
$$\nabla = z; \mu = i; \eta = v; tg = t';$$
 (91)
$$\}$$

$$if (q_t > s_i)$$
 (92)
$$\{ v = \min(|q_i|, (q_{t'} - s_i), x_{it})$$
 (93)
$$z = \frac{S_i + \Delta H_i}{v}$$
 (94)
$$if (z < \nabla)$$
 (95)
$$\nabla = z; \mu = i; \eta = v; tg = t';$$
 (96)

}

The algorithm detailed above shows four different alternatives available for shifting production. Each one is described in detail in the following paragraphs.

- 1. Move the entire lot to another period where the product is already produced; this eliminates a setup. Equation (79) ensures that this lot shift occurs only if there is sufficient capacity in the target period and that the product has a lot already scheduled in that period. As is illustrated in equation (80), the per unit cost is based on the difference between the change in the inventory cost calculated using equation (71) and the estimated reduction in the setup cost caused by the elimination of the setup in the current period. To encourage the shifting of the whole lot rather just enough to eliminate infeasibility the divisor in equation (80) is lot size for the product in the current period. Two scenarios are possible for relationship between lot size and overload in the period. In the first scenario, lot size is greater than overload in period. In this case, by having a greater divisor the cost of the lot shift appears more attractive in comparison with other alternatives. In the second scenario, lot size is less than overload capacity. In this case, lot size accurately reflects the overload eliminated. Equation (81) ensures that this lot shift occurs only if there is a cost reduction over the best combination so far. Equation (82) replaces the current values of cost, item, quantity and target period with values that provide a lower cost.
- 2. Move the entire lot to a day on which no production is scheduled for the product.
 Equation (83) makes sure that there is sufficient capacity in the target period to shift the entire lot and for the estimated setup time. In this shift, there is a setup eliminated and a setup added therefore the effect of the setup cost is nullified, while

- the change in inventory costs is reflected in equation (84). Once again, this equation encourages the movement of an entire lot. Equation (85) ensures that this is the least expensive alternative before reassignments in equation (86) are made.
- 3. This and the next option might end up breaking the lot to achieve feasibility.

 Breaking a lot is not an attractive alternative because there is no potential for setup elimination. In this option, an attempt is made to move part of the lot to another period in which the item is produced, this is assured by the if condition in (87).

 Equation (88) ensures that the quantity moved does not exceed either; the lot size of the item in the current period, what must be moved to achieve feasibility, or slack in the target period. Once again, no setup is added or eliminated and hence the incurred cost is just the change in inventory cost per unit of quantity shifted as stated in (89). Equation (90) ensures that this option is only selected if it is less expensive than other combinations and equation (91) reassigns the variables if this is true.
- 4. Finally, part of the lot can be moved to another period in which the product is not produced and where the slack is not sufficient to accommodate the entire lot and the setup time estimate. Equation (92) ensures that there is more than enough capacity in the target period to accommodate at least estimated setup time. Since larger lots tend to increase costs equation (93) makes sure that only a minimum of; (1) what is required to be moved to eliminate infeasibility, (2) amount of production the target period can accommodate, and (3) the size of the production lot for that product in that period is moved. The unit cost of the move given in equation (94) accounts for the added setup in the target period and the change in inventory cost. Equation (95)

makes sure that this option is selected only if this is the lowest cost feasible option available. If this is true variables are updated as shown in equation (96).

A lot can be moved as far back as desired without violating any conditions, however, even if a single unit of production is moved to the next period the algorithm must ensure that the move does not violate the maximum delay constraint. If the maximum delay for backlogging is equal to the scheduling horizon ($\alpha = T$) then this constraint check can be ignored. Every time production is shifted forward a procedure is executed to determine if it violates the maximum delay constraint; this procedure is described next.

Maximum Delay Criterion Checking Procedure

The validity of a forward move depends not only on the number of periods between the current period and the target period but also on the current inventory for the product in the periods in between. Given t^* , the target period, $(t^*>t)$ a partial or entire lot of size m can be moved from t to t^* only if $\pi = 0$ after the following loop is executed.

$$\pi = 0$$
for (t' = t to t' = t*-1)

{

if $(I_{it'} - m < - \sum_{t''=t'-\alpha+1}^{t'} d_{it''})$ (97)

 $\pi = 1 \tag{98}$

Equation (97) checks if constraint (8) of the formulation presented in chapter I is violated by shifting m units from t to t*. If this violated for any period between the source and the target periods then equation (98) marks this move as an infeasible move. This checking routine is executed before any forward movement is considered and when the criteria is violated the lot shifting not considered.

The feasibility elimination routine does not always produce a feasible solution to an infeasible problem. However, when a feasible schedule can be attained by moving by shifting entire lots or parts thereof this routine ensures that this is attained in the most economical manner. Once a feasible schedule is determined then a simple solution improvement technique can be used to obtain a better solution this is discussed in the next section.

Solution Improvement Technique

For single product dynamic demand problem without capacity constraints the extreme point property of the Wagner-Whitin (Wagner and Whitin 1958) dynamic program algorithm is a necessary condition for optimality. Here, this property is extended for capacitated multi-item dynamic problem that allows for backlogging using the regeneration point theorem discussed in chapter III.

For the situation in which no backlogging is allowed, the extreme point property states that for any product i $I_{it-1}x_{it} = 0 \ \forall \ t$ for a solution to be optimal. Here two extensions are proposed to the extreme point property theorem. These theorems hold

good for a single item uncapacitated problem with backlogging. And with suitable modification can be applied to multi-item capacitated problems.

<u>Theorem</u> 1: There exists an optimal schedule such that $I_{it-1}x_{it} \le 0$ for all t.

<u>Proof</u>: From the regeneration point theorem we know that given $t \le k$ and

 $x_{it} > 0$; $x_{it+1} = x_{it+2} = \dots = x_{ik-1} = 0$; and $x_{ik} > 0$ there exists a period t',

 $t \le t' \le k-1$ such that t' is a regeneration point. Without loss of generality let us assume that t', $t \le t' \le k-1$, is a point of regeneration, i.e. $I_{ii'} = 0$. Also the following

capacity balancing equation is true $I_{ik-1} = I_{it'} + \sum_{t''=t'+1}^{k-1} (x_{it''} - d_{it''})$. Since we already

know that, $\sum_{t''=t'+1}^{k-1} x_{t''} = 0$ and $I_{it} = 0$, the capacity balancing equation reduces to

$$I_{ik-1} = \sum_{t''=t'+1}^{k-1} -d_{it''}.$$
 Therefore, $I_{ik-1} \le 0$. We also know that $x_{ik} > 0$. Hence,

 $\ni I_{k-1}x_k \le 0$ which gives an optimal solution.

<u>Theorem 2</u>: There exists an optimal schedule such that $I_{it}x_{it} \ge 0$ for all t.

<u>Proof:</u> This theorem will be proved by contradiction. Assume, without loss of generalization, that $I_{it}x_{it} < 0$ is part of an optimal solution. The proof is complete if we can show that a better solution exists where this condition is not true. $I_{it}x_{it} < 0$ is only possible if $I_{it} < 0$ (since $x_{it} \ge 0 \ \forall t$). The production lot can be increased from x_{it} to $x_{it} + |I_{it}|$ at no extra cost. This results in a reduced cost schedule equal to the cost of backlogging I_{it} . Obviously, this is a better solution than the schedule where $I_{it}x_{it} < 0$,

hence the cost of the original schedule was not optimal. Since no restriction was placed on the value of t the above discussion is true for all values of t.

The final solution is tested for the above properties and if there exists a situation such that $I_{it-1}x_{it} > 0$ or $I_{it}x_{it} < 0$ for any item and $q_t > 0$ then production lot is shifted from the closest period to the current period. If more than one item has the above criterion then the one that reduces the cost most is selected. In the next three sections, the three algorithms to solve the research problem will be detailed.

A Lot Shifting Algorithm (LS)

In this approach, the entire problem is considered as a whole and a greedy algorithm is used to reduce costs by eliminating setups. The algorithm works as follows.

Step 1. Assign schedule = demand on each day

$$x_{it} = d_{it} \forall i,t$$

Step 2. Use the sequencing routine to sequence production in each day. Calculate available capacities on each day. A positive value indicates slack and negative value indicates overloading.

Step 3. Move entire lots if the costs resulting from increased inventory or backlogging costs is less than the potential setup cost savings. Potential setup cost savings are estimated using one of the methods described previously. The estimated cost reduction is computed from the following equations:

$$E_{tk}^{i} = S_{i} - h_{i} \times (t - k) \times x_{it} \quad if \ t > k$$
(99)

$$E_{tk}^{i} = S_{i} - b_{i} \times (k - t) \times x_{it} \quad if \ t < k$$

$$\tag{100}$$

Equation (99) determines the estimated cost saving when production is moved backward. Equation (100) estimates the cost savings when production is moved forward. Any cost saving move can only be considered if there is sufficient capacity in the target period. When production is moved forward an additional criteria described in the previous section must be satisfied. The lot shifting part of the algorithm works as follows:

```
while (.T.)
{
    if (x_{ik} > 0 \text{ and } q_k \ge x_{it})
                                                                                                               (101)
         save j, t', t" \ni E_{t't''}^{j} = max(E_{tk}^{i}) \ \forall \ i \in [1, N]; t, k \in [1, T]; t \neq k;
                                                                                                               (102)
    if (E_{t't''}^j > 0)
                                                                                                               (103)
         x_{jt''} \leftarrow x_{jt''} + x_{jt'}
                                                                                                               (104)
         x_{it'} = 0
                                                                                                               (105)
         calculate capacity
     }
    else
          .F.
```

Equation (101) makes sure that the target period has a non zero production lot for the product in question and also capacity availability in the target period. Equation

}

(102) executes a sequence of loops to identify the product and the source and target periods that provide the maximum estimated savings. The "if" condition in equation (103) checks if the potential setup cost savings are greater than increased inventory costs. If maximum savings are less than 0 then no more cost saving moves are possible and the while loop is exited. Equations (104) and (105) reassign the size of the production lots in the source and target periods.

The lot shifting algorithm is similar to the one used by Dogramaci et al. (1981) except that, here both forward as well as backward movement of lots are considered.

The salient features of this method are listed below.

- Only the lot that promises the maximum savings, across all items and all periods, is moved each time.
- 2. The moves do not create infeasibilities, however infeasibilities may persist due to the nature of the original demand pattern.
- 3. All potential profitable moves are made before the lot shifting is stopped.
- Step 4. Eliminate overloading using algorithm detailed earlier in this chapter.
- Step 5. Improve the quality of solution using the methods described earlier.

The five step algorithm produces a low cost feasible schedule using a myopic lot shifting algorithm. By addressing the feasibility issue at every move the algorithm is restrictive in its movements of lots. An alternative approach would be to relax the capacity constraints initially to allow for the unrestricted movements of lots. This is the essence of the next two approaches to solving the problem.

A Regeneration Algorithm (RA)

This algorithm is founded upon the regeneration point principle developed originally by Manne and Veinott (1967). Two issues have to be addressed before their solution procedure can be used as part of the algorithm proposed here:

- formulation of the original research problem as a collection of single item problems,
 and
- adaptation of the solutions of the single item problems to the constraints of the original problem.

The single item problem is formulated and a solution procedure is provided in chapter III. The single item formulation is targeted at accommodating a time variant setup cost however, setup in the research problem is sequence dependent and time invariant. Hence, the time variant setup costs are replaced by the setup cost estimates while solving the single item problem. All the rest of the information is available in the original formulation.

When the production lots resulting from the single item solutions are combined, the resulting schedule is likely to be infeasible due to capacity overloading. Hence, it is important that the solution be modified at the lowest possible cost to achieve feasibility. Now the five step algorithm used in this approach is described below.

- Step 1. Determine the optimal production lots in each period for one product at a time.
- Step 2. Sequence the production and calculate capacity requirements.
- Step 3. If the solution is feasible then stop further execution, else go to step 4.
- Step 4. Use the infeasibility elimination algorithm to determine a feasible schedule.

Step 5. Improve solution quality using methods described earlier in this chapter.

A potential problem with the above approach is that the lot size allocation may be unwieldy in some periods and negligible in others. This may require that the infeasibility elimination routine undo most of the lot assignments determined in step 1 of the algorithm resulting in the final solution being far from the optimal one generated in step 1. This problem can be overcome if some sense of capacity limitations is introduced in step 1. This is achieved through an intelligent modification of the above approach and is described in the next section.

Regeneration Algorithm with "Overload penalty" (ROP)

The biggest drawback of the approach described in the previous section is that it solves each item completely independent of others as if it were the only product in the system. In this approach, between successive solutions to the single item problem a "overload penalty" is added to the problem formulation. "Overload penalty" is a measure that conveys to the successive formulations of the single item problems information on the capacity usage of the previous items. The idea is to discourage vastly overloading any period in the horizon. Since the lot sizing decisions in the later problems will be affected by those made in the earlier problems, the sequence in which the items are solved affects the final solution. For a successful implementation of this approach, three issues must be addressed:

- 1. the sequence in which the items are lot sized
- 2. quantification of the "overload penalty"

including the "overload penalty" into the single item problems Sequencing of Items

Here, we have to determine a ranking schema for the items so that the ones with a higher rank can be lot sized first when there are fewer capacity restrictions to consider. Faced with a similar ranking problem Kirca and Kokten (1994) report that a ranking system based on the total cost per unit demand is superior. For each item i, V_i is estimated using the economic order quantity (EOQ) concept. The average cost per unit for an item is computed by dividing the EOQ cost per period by the mean demand per period for that item. Then the item that has the largest average cost per unit is given a higher ranking. V_i is calculated using the equation (106).

$$V_i = \frac{\sqrt{2 \times S_i \times r_i}}{r_i} \qquad \forall i$$
 (106)

Quantification of the "Overload penalty"

The purpose of "overload penalty" is to discourage the single item regeneration algorithm from scheduling production lots in periods during which other items are already scheduled if inclusion of these additional lots is likely violate capacity constraints. This can be achieved by adding the cost of eliminating infeasibility, caused by these additional lots, to the policy costs in those periods in the single item dynamic programming algorithm. This additional cost increases the cost of adding production lots in overloaded periods, and the dynamic programming algorithm is likely to select other alternatives to schedule the lots. However, the exact cost of eliminating infeasibility is difficult to compute. Therefore, it is desirable that a algebraic relationship

be established to a easily computed measure for calculating the cost of eliminating infeasibility.

Infeasibility manifests itself as overloading, and cost of eliminating infeasibility is the cost of eliminating overloading. Therefore, there is likely to be a relationship between infeasibility elimination costs and overloading. Using capacity requirements, calculation procedure described earlier overloading in each period can be easily computed. Hence, establishing a algebraic relationship between cost of eliminating infeasibility and overloading in a period is of interest here. Once this relationship is established a "overload penalty" can be computed that is equal in order (linear, quadratic, cubic, etc.) to the cost of eliminating infeasibility. Determining the order of the polynomial relationship between cost of eliminating infeasibility and overloading is discussed in the next few paragraphs.

When overloading occurs in a period, the infeasibility elimination procedure eliminates overloading by shifting production to other periods with positive slack. The procedure moves production to the period which results in least cost increase. When overloading is much greater than capacity available, several lots or parts thereof have to be shifted from the overloaded period. When multiple shifts are required to achieve feasibility, initial lot shifts are made at much lower costs than later lot shifts. This is because as lot shifts are made the best target periods are occupied by initial lots thereby reducing or eliminating slack capacity in those periods. This causes later lots to be moved to less desirable periods, much farther away from current period, to achieve feasibility.

The above argument supports the conjecture that the marginal cost (cost of eliminating one additional unit of overloading) increases as overloading increases. This can be explained with an example, consider two overloaded periods t' and t''. The overloading in these periods are denoted by $q_{t'}$ and $q_{t''}$ such that $q_{t'} > q_{t''}$. This means overloading in period t'' is greater than overloading in period t', since both $q_{t'}$ and $q_{t''}$ are negative. In addition, let us assume that an additional lot of 1 unit (hour) is to be added to production in these periods. It is conjectured here that the cost of eliminating infeasibility caused by additional unit in period t'' is greater than the cost of eliminating infeasibility in caused by additional unit in period t'.

Marginal cost is nothing but the sum of additional setup, inventory and backlogging costs incurred to eliminate 1 unit of infeasibility. Setup costs are a constant irrespective of the size of lot shifted and the target period. Increases in inventory costs and backlogging are proportional to the number of periods between the target period and the current overloaded period. Therefore, marginal cost is proportional to number of periods between the current period and target period. However, from earlier discussion, we know that the target period is likely to be further away as the overloading in a period increases. The above discussion reinforces the conjecture that marginal costs increases as overloading increases. This discussion can be captured by the following inference sequence.

marginal cost ∞ change in inventory backlogging cost change in inventory/backlogging cost ∞ overloading therefore, marginal cost ∞ overloading

As already stated marginal cost is nothing but the cost of eliminating one additional unit of infeasibility. One unit of infeasibility is same as one unit of overloading. Therefore, the above inference chain can be extended by an additional link as follows:

$$\frac{Infeasibility\ cos\ t}{overloading} \propto overloading$$

from which the relationship between infeasibility cost and overloading is readily obtained

Infeasibility
$$\cos t \propto (\text{overloading})^2$$

By simple extension the above relationship is also true for "overload penalty" computations. In conclusion, "overload penalty" is proportional to the square of number of hours of overloading. Assuming a constant of proportionality of 1 equation (107) states the equation that is used to compute the "overload penalty".

overload penalty =
$$(overloading)^2$$
 (107)

A mathematically complete equation for calculating the "overload penalty" is described below. Let

 x_{it} = lot size for item i in period t \forall i $\in \Delta$, and

 $x_{jt} = is \ a \ production \ lot \ for \ product \ j \ being \ considered \ for \ inclusion \ in \ period \ t$ then

$$\zeta = \begin{cases} \left(\sum_{i \in \Delta} (x_{it} + s_i) + x_{jt} + s_j - C_t\right)^2 & \text{if } \sum_{i \in \Delta} (x_{it} + s_i) + x_{jt} + s_j - C_t \ge 0\\ 0 & \text{otherwise} \end{cases}$$

$$(108)$$

Equation (108) calculates the magnitude of the "overload penalty' using the actual sizes of the production lots and estimated setup times. Setup times are estimated because, sequencing issues are not addressed at this point, and therefore it is not possible to calculate the exact time requirements for setups. The "overload penalty" as computed above affects the quality of the optimal solutions to a lesser extent when magnitude of overloading is low. However, the impact is more drastic if overloading is high. Issues involved in incorporating the "overload penalty" into the dynamic programming algorithm used to solve the single item problem with backlogging costs are described next.

Inclusion of the "Overload penalty"

As stated in the previous section, "overload penalty" is included into the policy costs of the dynamic programming algorithm. Equation (57) in chapter III is used to calculate the cost of producing a lot in period t' to meet all demand between two successive regeneration points t and k. This equation is modified as follows to account for the "overload penalty"

$$c_{ik}^{t'} = S_i + \zeta + h_i \sum_{t''=t'+1}^{k} (t''-t') d_{it''} + b_i \sum_{t''=t+1}^{t'-1} (t'-t'') d_{it} \qquad \forall t, t', k$$
 (109)

The if condition in equation (108) ensures that the modified equation (109) is used only when capacity limit is exceeded. The rest of the algorithm remains the same. At this point, the complete regeneration algorithm with "overload penalty" is presented.

Regeneration Algorithm with "Overload penalty"

The six step algorithm proceeds as follows.

- Step 1. Determine the order in which the single item problems are tackled.
- Step 2. Determine the production lots in each period for one product at a time by including the overload penalty in each period for each item.
- Step 3. Sequence the production and calculate capacity requirements.
- Step 4. If the solution is feasible then stop further execution, else go to step 5.
- Step 5. Use the infeasibility elimination algorithm to determine a feasible schedule.
- Step 6. Improve solution using methods described earlier in this chapter.

While this approach does not guarantee a feasible solution after step 2, it reduces the scope of the infeasibility problem addressed in step 5 at the cost of modifications to the optimal production lot allocations in step 2. It is expected that this additional computational investment made in step 2 will be rewarded with an overall reduction in the cost of schedules generated by this algorithm.

Summary

In this chapter, the approaches used to solve the research problem are described. Before the algorithms were presented, the sequencing, capacity determination, infeasibility elimination, and solution improvement methods which are present in each approach were described in detail. These issues are closely interlocked; their considerations lend richness to the algorithms developed here. This richness

distinguishes these algorithms from other techniques that are currently used to solve the problem.

One of the goals of this research was to show that the computationally rich algorithms developed here are superior to current methods used to solve the research problem. One such technique is the EMQ calculations based technique that is used in MRP II, and described in chapter II. Another base case that is used for comparison purposes is the no lot size algorithm. The no lot size approach is a naive approach which essentially boils down to producing all demand requirements in a single lot.

A potential problem with EMQ calculations is that integer multiples of the lot size are not necessarily equal to the to total demand for the product. If this happens it is handled as follows.

- 1. Only what is required to meet demand during the finite scheduling horizon is produced, this might mean that the final lot is shorter than the EMQ calculations or might be completely eliminated. For example, if the lot size for product A has been calculated to be 8. The total demand for the product is 30. Hence, during the fourth cycle of production the lot size of product A is reduced to 6 so that no excess production occurs. And if some other products in the system require more than 4 cycles product A is not produced in those cycles because its cumulative demand has already been satisfied.
- 2. Under some circumstances EMQ lot sizes may be rather small. More cycles are required to meet demand in these instances. In these cases, relatively higher proportion of time is spent on setup. For this reason, at the end of the scheduling

horizon the quantity of production scheduled is less than cumulative demand for that product. In these situations production lot allocation is continued till all the demand is satisfied.

To provide further understanding of the workings of each algorithm, a sample problem is solved using each of the algorithms. A numerical example is generated and a step by step solution is provided for each algorithm in Appendix A. However, no inferences can be made regarding the performance of the algorithms from these solutions. Experimentation is necessary to evaluate the performance of algorithms. In the next chapter, computational experience with these approaches is presented, and experimentation is performed to determine the validity and robustness of the algorithms.

CHAPTER V

EXPERIMENTAL PROCEDURE

This chapter focuses on the design and implementation of computational experiments to test the performance of algorithms developed in this research. An experiment consists of solving a series of problem instances that represent a wide variety of factors that may influence the performance of the algorithms. Experimentation is the process of setting goals for the experiments, identifying factors that influence the performance of algorithms, conducting experiments in a controlled environment, and analyzing the results using a statistical tool. The first step in experimentation is the setting of goals for experiments. Goals of an experimentation process are expressed by the hypotheses to be tested. Once the goals of the experiments have been determined, the next step is to identify factors that can potentially influence the results of the experiments. To determine whether a factor significantly affects the outcome of the experiments, more than one instance value, or factor level, of the factor must be experimented with.

Once the factors are identified, and before the algorithms are run over several problem instances, it is necessary to identify the measurement tool used to study the outcome of the experiments. In this research, the outcome is analyzed for the ability of the algorithms to find a feasible and cost efficient schedule. The solution quality of an algorithm is measured by the cost value of the schedule generated by the algorithm. After the models are run on the complete data set, usually some kind of statistical procedure is used to analyze the results of experiments. An introduction to the full

factorial analysis of variance statistical procedure used in this study is presented later in this chapter. First the goals of the experimentation process are reviewed.

Experimentation Goals

In this research, three heuristic algorithms have been developed to solve a class of real world manufacturing scheduling problems. Barr et al. (1995) have identified two requirements that must be satisfied when heuristic approaches are evaluated with computational experiments. The experiments must be able to:

- test the relative effectiveness of algorithms in comparison with one another and with currently available solution techniques, and
- 2. describe the performance of the algorithms across several factor level combinations.

The goal of relative effectiveness experimentation is to test the quality of solutions obtained by the algorithms proposed in this research with one another and with current methods to solve the problem. The methods are tested against two base cases discussed in chapter IV. The hypothesis to be tested in this regard is presented below.

Hypothesis 1: On the basis of the total schedule cost, at least one of the lot sizing algorithms proposed here would out perform both the no lot sizing method and the one based on EMQ calculations.

The logic behind this hypothesis is that the more computationally intensive algorithms proposed here consider the more complete problem picture in solving the problem. On the other hand the simpler methods do not consider all the information that directly affect

the quality of the final solution. Which methods perform better than the other methods proposed here is difficult to predict.

Test of hypothesis 1 is the primary goal of this study. A broad comparison based on typical measure of central tendency, such as means and variance, could be made given a set of problem instances. However, this may not necessarily indicate whether one algorithm is better than another in a specific category of problem instance. Hence, a new hypothesis must be composed to test the latter issue.

The aim of descriptive experiments is to gain understanding about performance of algorithms and the factors that influence their performance. The factors could either influence the performance individually or in combination. The hypothesis to be tested in this regard is presented as follows.

Hypothesis 2: The performance of the algorithms proposed here will be affected by the combination of factors that determine the inventory related production costs and demand environment.

The reasoning behind hypothesis 2 is that, each method is so information intensive that the quality of the final solution is affected by the multitude of factors involved. The factors that influence inventory related production costs are, inventory holding factor (h_i), setup cost per hour and backlogging cost factor (b_i). Demand environment is determined by the pattern of customer requirements and the utilization of resources in the production system.

A strategy is adopted to test for the two hypotheses stated above. Hypothesis 2 is first tested. If the results indicate that the factors have no influence on the quality of

solutions then hypothesis 1 can be tested directly. However, even if a semblance of significance is detected then hypothesis 1 must be tested at each factor (or factor combination) that influences the quality of solution. The above strategy ensures that the quality of ANOVA results obtained by test of hypothesis 2 is not affected by extraneous factors that may affect the outcome of the algorithms. A complete discussion of these factors is presented in the next section.

Experimental Factors

In the past, as a result of research in the area of lot sizing in a dynamic demand environment, certain factors have been identified as having an effect on the performance of heuristics (Dilts and Ramsing 1989, Maes and Van Wassenhove 1986). These experimental factors can be divided into one of the following three categories:

- 1. nature of demand,
- 2. inventory related production costs, and
- 3. solution approach.

Nature of Demand

The factors in this category model the demand environment in which the production system is trying to meet customer requirements. Four factors determine the nature of the demand.

1. Size of the problem: This is determined by the number of products produced in the system and the duration of the schedule horizon. When there are very few products

and scheduling horizon is short, the performance of more complex algorithms deteriorates in comparison with optimal solutions (Dogramaci et al. 1981). This is because even the smallest changes in schedules causes a relatively large change in the cost of the schedule. For this reason, it is necessary to test the influence of problem size on the performance of algorithms. Here two sizes are considered: small and large. Small problem instances are those that have 6 items and a scheduling horizon of 10 days. Large problem instances have 15 products and a scheduling horizon of 30 days. Large problems are similar to the size of the problem faced in the motivating case.

- 2. Type of demand: EMQ lot size calculations are based on average daily demand. Hence, it is likely that the quality of its solutions are sensitive to the deviations of actual daily demands from average values. For this reason, two types of demand patterns are to be tested. Smooth demand patterns are those in which every product has almost similar demand in each period. Lumpy demand is the case when all the demand for the product over the scheduling horizon occurs in a few periods.
- 3. Capacity requirements: The ability of algorithms to find feasible solution is affected by the utilization of the constrained resource. This factor measures the capacity requirements of the demand for all items in each period. Loose capacity and tight capacity are to be tried. Loose capacity is when the demand in a period is equal to 50% of capacity available and tight capacity is when demand in each period is 75% of capacity available. This is acceptable as these utilization values do not take into account the time required for setup. Setup times, when switching from one product

to another, are sequence dependent and vary between 4% and 25% of the capacity available in each period. These values are similar to one encountered in the motivating case.

4. Backlogging limit: This factor controls the maximum delay allowed in meeting customer due dates and is the same as the α value used in the problem formulation. The tightness of the backlogging constraint potentially controls the ability of the algorithms to find a feasible solution. Here this value is to be varied over two levels, 10% and 50%, of the scheduling horizon. For small problems, this works out to values of 1 and 5 periods and for large problems it is 3 and 15 periods.

Inventory Related Production Cost Factors

The factors included in this category are setup cost factor, holding cost factor, and backlogging cost factor. It has been reported in the literature (Dogramaci et al. 1981, Dilts and Ramsing 1989, among others) that more than the actual values the ratios amongst these various cost factors are more important. Hence, in generating the data sets for this study the holding cost factor is assumed to be one and the setup and backlogging cost factors are varied as follows.

Backlogging cost factors: Hsieh et al. (1992) conducted an experimental study in
which they found the ratio between backlogging cost factor and inventory cost factor
to be significant. The two factor levels used in their study was 1.2 and 2. To show a
greater importance for due date performance, the two levels of backlogging to
inventory cost ratios studied here are 2 and 5.

2. Setup cost factors: Setup times are generated randomly and are in the range of 1 to 6 hours. In this study, the setup costs are also sequence dependent for each product and are computed from setup time requirements for that sequence. Here, two factors are used as multipliers to convert setup time into setup cost. They are 2 and 8. This means that setup cost/holding cost factor could be as low as 2 or as high as 48 (this occurs when the setup time between two products is 6 hours and a setup cost factor of 8 is used).

Solution Approach

Given a set of demand and setup data this category of factors determine the method used to solve the problem. The solution approach is determined by the algorithm used to solve the problem and the setup estimating technique used. The factor levels for these factors are detailed below.

- 1. Algorithm: this factor is varied over 5 levels, which include the three methods proposed here and the two base cases. These are, lot shifting algorithm (LS), a regeneration algorithm (RA), regeneration algorithm with "overload penalty" (ROP), economic manufacturing quantity (EMQ), and no lot sizing method (NL).
- 2. Setup estimator: this factor is varied over two levels namely MIN and MAX. MIN uses the minimum of all possible setup for the product and MAX uses maximum possible setup for the product.

To study the independent influence of experimental factors in the three categories listed above, it is essential to eliminate other external factors that can influence the results. To control the experimental conditions the following assumptions are made.

- 1. The holding cost factors are equal for all products. Holding cost factor for an item is proportional to space required to store one hour of production for that item and cost of producing one hour of that item. Typically, in a manufacturing environment larger products are more expensive to produce, and also their production rate is lower than smaller products. Hence, on balance space requirements and cost of production tend to be similar for all items. This justifies the assumption of equal holding cost factors for all items. However, in some production systems the above argument does not hold. In such cases, holding cost factor differences cannot be ignored and an additional factor must be included in the experimentation.
- 2. Backlogging cost factors are equal for all items. This cost is the penalty levied for late delivery of items. This penalty is usually used to indicate a preference for which products to be backlogged. Here, it is assumed that all orders are of equal importance, therefore backlogging cost factor is equal for all products.
- 3. Maximum delay (backlogging limit) is equal for all products. This factor controls the duration of backlogging allowed. Backlogging requirements are dependent on the demand pattern for a product and utilization of the system resource. Variations amongst products would affect factors already included in the study. For this reason different delay values for different items is not studied.

4. Capacity availability is maintained constant. In a typical system, the day to day capacity availability remains constant, unless affected by breakdowns and other downtimes. It is assumed that the influence of these factors on capacity availability is minimal. In the motivating case three shifts are run on the coating machine per day. To reflect this situation capacity availability is held constant at 24 hours per day throughout the study.

Each of the factors and their levels included in this study has been determined after careful consideration of the prevailing values in the motivating case and from published literature. Table 1 summarizes the factors to be used in the experiments. For each factor name, it identifies a factor symbol used represent the factor in the experiments, the number of factor levels for each factor and the instance value of each factor level. Once the factors and factor levels have been identified the next step is to determine the performance measure and the methodology adopted to generate the data sets for the experiments.

Factor Name	Factor Symbol	Number of Levels	Factor Level Values
Algorithm	A	5	a1 = LS; a2 = RA; a3 = ROP;
			a4 = EMQ; $a5 = NL$
Setup estimator	В	2	b1 = MAX; $b2 = MIN$
Size	C	2	c1 = 6 products 10 periods (small)
			c2 = 15 products 30 periods (large)
Demand type	D	2	d1 = smooth; d2 = lumpy
Capacity utilization	E	2	e1 = 50% (low); $e2 = 75%$ (high)
Setup cost factor	F	2	f1 = 2 (low); f2 = 8 (high)
Backlog cost factor	G	2	g1 = 2 (low); g2 = 5 (high)
Backlogging limit	H	2	h1 = 10% (low); $h2 = 50%$ (high)

Table 1. Factors and factor levels used in experiments

Performance Measure and Data Sets

While the most important performance yardstick is the cost of schedules generated, it is also important to compare the algorithms in terms of their ability to find feasible solution to a given problem set. Hence, the first performance measure merely counts the number of feasible solutions determined by the algorithm under consideration. Regarding the conventional methods, because of the fact that they neglect backlogging limit, the likelihood of an infeasible solution is quite high. Nevertheless in this research, they are given the benefit of doubt, and an assumption is made to consider all solutions as far as conventional methods are concerned. For this reason, feasibility analysis is only performed on the algorithms developed in this research. There are two aspects to the feasibility of a schedule.

- Capacity feasibility: The ability of an algorithm to generate a schedule whose
 capacity requirements are less than or equal to capacity available on each day.

 Capacity infeasibilities are indicated by a negative slack value at the end of
 infeasibility elimination routine in any of the periods.
- 2. Backlogging limit feasibility: The ability of algorithms to find a schedule in which customer requirements are satisfied within the maximum delay duration from the due date. Each algorithm considers this constraint in the lot shifting procedure and also in the capacity infeasibility elimination procedure. Therefore, this requirement is embedded into every schedule that is generated by the algorithms. For this reason maximum delay feasibility need not be checked.

Therefore, a solution is termed feasible only if the final solution determined by the algorithm does not violate capacity requirements in any period of the scheduling horizon. The second performance measure is based on the total schedule costs which is the sum of inventory, setup, and backlogging costs. However, the absolute cost depends on the demand data and setup data input into the algorithm. To eliminate the effect of data, a comparative performance measure is used. Ideally, the performance measure would be based on the optimal value for a problem instance but, in the absence of such information, the lowest feasible cost generated amongst all combinations of algorithms and setup estimator is used. The performance measure is calculated as follows:

- 1. each data set is run with all solution approaches,
- 2. the lowest cost amongst them is determined, and
- 3. this lowest cost is then divided into the cost determined by each solution approach.

For each data set the performance measure is calculated using equation (110):

$$PM_{ab} = \frac{TC_{ab}}{\min\limits_{\forall \ a,b} (TC_{ab})}$$
 $a = 1,2,3,4,5 \ and \ b = 1,2$ (110)

where PM_{ab} is the performance measure for algorithm a using setup estimator b, and TC_{ab} is the total cost of the schedule generated by that combination. The advantage of using a relative performance measure is that it eliminates the inherent variances in the cost between data sets for a given treatment, i.e. the performance of a solution approach is more likely to be stable for a certain combination of demand and inventory cost factors.

The data sets, demand, and setup values, are generated randomly to fit the profile of the demand treatment being considered. The following procedures are adopted for generating smooth and lumpy demand patterns of desired capacity utilization. In any event, negative values are not allowed for any product on any day. For smooth demand pattern, initially set $d_{it} = rand(1,4)$ for all i,t, where the function rand(m, n) generates a random number between m and n, both inclusive. If capacity requirement is not what is desired then, in the period in which requirements are not satisfied, do the following:

- 1. randomly select a product and adjust (increase or decrease) its demand by 1 unit,
- 2. if requirements satisfied then EXIT else repeat 1.

In the case of lumpy demand pattern, initially set $d_{it} = rand(1.8)$ for all i,t. Now for each product set $d_{it} = 0$ for 0.6*T randomly selected days. Ensuring capacity utilization is handled using different approaches based on whether there is a shortfall or excess. If capacity requirement is less than what is desired then:

- 1. randomly select a product with non-zero demand and increase its demand by 1 unit,
- 2. if requirements satisfied then EXIT else repeat.

If capacity requirement is greater than what is desired then:

- 1. randomly select a product and reduce its demand by 1 unit,
- 2. if requirements satisfied then EXIT else repeat 1.

Using the procedure described above, it is possible to generate multiple sets of data that meet the demand pattern requirements. The number of data sets that should be generated for each demand pattern depends on the statistical procedure used to analyze the results and confidence desired in the results. These issues are discussed in the

"Analysis of Variance" section later in this chapter. At this point, it suffices to state that 10 data sets are generated for each demand pattern.

A complete listing of the demand data and the setup data used for experimentation in this study is listed in Appendix B. Essentially, eight sets of demand data are generated. The eight demand data sets are determined by the combination of problem size, demand type and utilization factor levels. Ten different problem instances are generated for each demand data set. A complete listing of these factor level combinations is provided in Table 2. There are only two sets of setup time matrices used; one for the small problem size and another for the large problem size. With demand data sets, setup time matrices and factor levels identified, computational experiments can be carried out.

Number	Size	Demand Type	Utilization
1	6x10	smooth	50%
2	6x10	smooth	75%
3	6x10	lumpy	50%
4	6x10	lumpy	75%
5	15x30	smooth	50%
6	15x30	smooth	75%
7	15x30	lumpy	50%
8	15x30	lumpy	75%

Table 2. Demand data sets

Computational Experience

Each of the eight demand data sets are solved at 4 possible combinations of inventory cost factors and 2 possible values of the backlogging limit factor. Table 3

provides a complete listing of these 8 factor combinations. In turn each of these 8 factor combinations are solved using 10 possible combinations of solution approach listed in Table 4. Hence, there are a total of 8x8x10 factor level combinations, called treatments, to be tested. With 10 repetitions in each treatment there are a total of 640x10=6400 problem instances. The algorithms are implemented using the C programming language on a IBM[®] Powerstation-220[™] workstation, using the RISC System/6000[™] architecture, running a UNIX[™] operating system.

Number	Setup Cost Factor	Backlogging Cost Factor	Maximum Delay
1	2	2	10%
2	2	2	50%
3	2	5	10%
4	2	5	50%
5	8	2	10%
6	8	2	50%
7	8	5	10%
8	8	5	50%

Table 3. Complete list of inventory costs and maximum delay factors

Solution Approach	Algorithm	Setup Cost Estimator
1	LS	MAX
2	LS	MIN
3	RA	MAX
4	RA	MIN
5	ROP	MAX
6	ROP	MIN
7	EMQ	MAX
8	EMQ	MIN
9	NL	MAX
10	NL	MIN

Table 4. Solution approaches

All the 6400 problem instances were run, and the following observations were made regarding the computational requirements for the algorithms.

- 1. All problems were solved to conclusion within reasonable CPU time and memory space requirements.
- The LS algorithm, when used to solve large smooth problems at low utilization level, requires the most number of computations and hence takes the most CPU time to find a feasible solution.
- 3. The ROP takes considerably less computational effort than the RA algorithm for a given problem. This is because the initial single item problem overloads capacity to a greater extent in the RA algorithm and it takes longer for the infeasibility elimination algorithm to eliminate infeasibilities in this case.

The solution obtained by each algorithm is shown in Appendix C. This appendix lists the actual cost of the schedule generated by each algorithm for each of the ten replications. The keyword marker "INF" indicates that no feasible solution was found to the problem. The computational requirements for the algorithms are reasonable, even for large problems, and for this reason no further analysis is performed with respect to the CPU time and memory requirements for the algorithms.

Output of the experimental runs are then prepared for statistical analysis. This is a two step process:

1. all infeasible results of the algorithms proposed here are removed from further analysis because their costs do not reflect the true costs of the schedule, and

the performance measure of each problem instance is computed using methods previously described.

This resulted in the loss of 1070 data points from the full factorial ANOVA design proposed in the next section. This loss of data results in unbalanced ANOVA design with empty cells. While a balanced design is preferable there are alternative statistical techniques available for unbalanced ANOVA. The general linear model (GLM) procedure of the SASTM statistics module was used for analysis. The software was run on a IBM 3090 mainframe computer running the CMS operating system. The use of statistical output to make inferences about the performance of the algorithms and test the hypotheses is addressed in the next chapter. In the next section, a brief overview of the ANOVA procedure is presented.

Analysis of Variance

Analysis of variance (ANOVA) is a popular and robust statistical procedure for isolating the sources of variability in a set of measurements. When two or more factors are to be investigated simultaneously, as in this study, a multi-factor ANOVA must be used. In multi-factor ANOVA, a treatment corresponds to a combination of factor levels, for example in the study proposed here there are a total of 8 factors with 5 algorithms and each of the remaining factors over two levels so there are a total of $5x2^7$ = 640 treatments.

Use of an ANOVA model is based on the scope of the interpretation of results.

Three types of ANOVA models can be used in a multi-factor study.

- Model I ANOVA: also called fixed effects ANOVA, it is used to study factors that
 are of intrinsic interest, i.e. the results of the study are applicable only to the factor
 levels used in the study.
- Model II ANOVA: also called random ANOVA, it is used in studies where all the factor levels are a representation of a wider population and interest is in the larger population.
- 3. Model III ANOVA: also called mixed model ANOVA, are used in studies where some factors are intrinsic and others represent a wider population.

The statistical methods used to evaluate a model are dependent on the type of model used. Hence, it is necessary that the correct model be identified for this study. In order to test the hypotheses stated earlier a fixed effects ANOVA model will suffice, besides the underlying statistics of the fixed effects ANOVA model are more robust than either the random ANOVA or mixed model ANOVA (Neter et al. 1990). Specifically, the results of mixed model ANOVA and random ANOVA are sensitive to departures from the following requirements for the ANOVA model:

- 1. the probability distribution associated with each treatment is normal distribution,
- 2. each probability distribution has the same variance (standard deviation), and
- 3. the observations for each treatment are random observations from the corresponding probability distribution and are independent of the observations at other treatments.

On the other hand, the fixed effect model is robust to deviations from normal distribution and unequal variances between treatments. However, its is sensitive to non-independence of observations between treatments. Fortunately, this problem can be

eliminated by randomization. Suitably, the data used in this study are generated by random number generators. For the above reasons, a fixed effects model is to be used in this study. Therefore the data does not have to be checked for deviations from the three assumptions listed above.

Like other statistical procedures ANOVA models are subject to Type I and Type II errors. In ANOVA, Type I error represents the risk of determining a factor effect to be significant when actually it is not. Type II error represents the risk of determining a factor effect to be insignificant when in reality it is. The protection against both Type I and Type II errors in ANOVA is controlled by the number of repetitions (sample size) at each treatment. The sample size has to be large enough to detect important differences with high probability. However, if the sample size is too large then unimportant differences between treatments become important with high probability (Neter et al. 1990). Therefore, determining sample size is an integral part of designing an analysis of variance study. Four factors influence the selection of a sample size (Bratcher et al. 1970):

- 1. number of factor levels,
- the smallest difference the experimenter would like to detect (expressed by the number of standard deviations),
- 3. risk of type 1 error, and
- 4. risk of type 2 error.

The primary goal of this experiment is to determine if the differences between the performance measure means of the solution approaches are significant (tested by

hypothesis 1). Therefore, the number of factor levels is 10 (5 algorithms with 2 setup estimation techniques each). Type I error level (risk of asserting that a difference exist when the true difference is 0) should be maintained low. This greatly increases the confidence in the results when statistical results indicate that there is significant difference between the means. Accordingly, the risk of type 1 error is fixed at 0.05 (confidence interval = 0.95). Bratcher et al. (1970) have determined sample sizes for several combinations of the above factors. For type 1 error of 0.05 and number of factor levels = 10. Table 5 shows the sample sizes for some values of type II error and smallest difference to be detected.

	Smallest differen	ce to be detected (nui	nber of std. dev.)
Type 2 error	1	2	3
0.30	27	6	4
0.20	33	9	5
0.10	41	11	6
0.05	48	13	7

Table 5. Some sample sizes for type 1 error = 0.05 and number of levels = 10 (Bratcher et al. 1970)

When very close means are to be analyzed (number of standard deviations = 1), sample size is very sensitive to type 2 error level. However, at larger deviations the sensitivity of sample size to type 2 error level is dramatically less. A preliminary perusal of the output obtained (listed in Appendix C) indicates that there is substantial difference between the means of performance measure. Hence, the differences between means for significance can be set at a relatively high value. For example, to detect means that are

at least 2.5 standard deviations apart with 10 repetitions per treatment, risk of type 2 error can be limited to 0.05.

In general, larger sample sizes are required to detect smaller deviations and place a tighter control of the error levels. In this study, it is far more critical to control type 1 error than type 2 error. Increasing the risk of saying differences are insignificant when they actually are not (type 2 error), merely increases strength of the claim when algorithms proposed here significantly out perform currently used techniques. From the above discussion, it can be determined that the number of standard deviations and type 2 error level are not too critical to this study. Fixing the differences between means to be detected at 2 and risk of type II error at 0.15, in addition type 1 error at 0.05 and number of levels at 10, a sample size of 10 is obtained.

Therefore, experiments have been performed at 10 repetitions for each treatment, this number is typical for similar studies (Dilts and Ramsing 1989). When the number of repetitions is equal across all treatments then the experimental data is said to be balanced otherwise the it is unbalanced. The presence of infeasibilities converts a balanced analysis to an unbalanced analysis. When unbalanced ANOVA is used alternative statistical procedures are available to determine the significance of factors.

ANOVA results indicate the main factors and/or interaction factors that are significant. Further analysis is required to determine if one solution approach is significantly better than others. For example, as a result of ANOVA if we decide that the algorithm factor has a significant effect, then we would still be interested in determining which algorithm provides the better results amongst all the algorithms studied. For this

purpose the Tukey method of multiple comparison described by Neter et al. (1990) is used. This method holds the confidence in the tests at the same level as the type I error level selected for the model.

Summary

In this chapter the experimental procedure used to analyze the proposed algorithms were laid out. The goals of the experiments were set and the hypotheses to be tested were presented. Factors that are to be varied and their factor levels were discussed. In addition, the factors that were to be held constant were also detailed. The procedure adopted to generate random data sets was presented. Initial observations from computational experimentation were described. The appropriateness of ANOVA statistical procedure and a discussion of selection of a sample size was also presented.

Once the experiments have been performed and SAS™ software applied to the output of the experiments the results are ready for analysis. Analysis of results is necessary to determine which algorithm finds the most number of feasible solutions and to test for hypotheses. These are discussed in the next chapter.

CHAPTER VI

ANALYSIS OF RESULTS

This chapter presents the results of the feasibility study and analysis of the experimental results with ANOVA. First, the capacity requirements of the final solution are examined. If the requirements are less than the capacity available then we a have feasible solution and the final cost can be accepted. However, even if capacity requirements are violated for one period then that schedule is infeasible and the final cost cannot be accepted as the true cost of that schedule. Following the feasibility study, ANOVA is performed on the feasible solutions to test for hypothesis 1 and hypothesis 2. The test of hypothesis 1 is dependent on the results of hypothesis 2, if the interactions are not significant then the factor level means of the algorithms can be compared. However, if some or all of the factor interactions are significant then treatment level means have to be compared. Therefore, the test of hypothesis 2 is performed first. Before any of the hypothesis are tested the feasibility results of the algorithms are analyzed.

Feasibility Results

The feasibility requirements are only tested for the three algorithms proposed here because, for the two bases cases feasibility is not required for the final cost to be accepted. The ability of an algorithm to provide a feasible solution is critical, because it affects the applicability of the solution approach in a real world production environment. However, in a complex problem, like the one addressed here, it is difficult to determine if

the demand and inventory cost related factors make the problem inherently infeasible.

Therefore, in some problem instances, especially at high utilization levels, the ability of an algorithm to find feasible solution might be under estimated. The ability of the algorithms to provide a feasible solution is examined below.

The feasibility results for LS, RA and ROP are presented in Tables 6, 7, and 8 respectively. The factor symbols used in this table are same as the ones outlined in Table 1. Each cell in the tables indicates the number of feasible solutions that were found for the treatment represented by that cell, out of 10 problems that were tested for that treatment. First the feasibility results of the LS algorithm are analyzed.

	bl			 b2				
	С	1	c	2	С	l	c	2
	dl	d2	dl	d2	dl	d2	d I	d2
el, fl, gl, hl	10	10	10	10	10	10	10	10
el, fl, gl, h2	10	10	10	10	10	10	10	10
e1, f1, g2, h1	10	10	10	10	10	10	10	10
e1, f1, g2, h2	10	10	10	10	10	10	10	10
el, f2, gl, h1	10	10	10	10	10	10	10	10
el, f2, g1, h2	10	10	10	10	10	10	10	10
e1, f2, g2, h1	10	10	10	10	10	10	10	10
e1, f2, g2, h2	10	10	10	10	10	10	10	10
e2, fl, gl, hl	0	8	0	0	0	9	0	0
e2, fl, gl, h2	0	10	0	0	0	10	0	0
e2, f1, g2, h1	0	8	0	0	0	9	0	0
e2, fl, g2, h2	0	10	0	0	0	10	0	0
e2, f2, g1, h1	0	7	0	0	0	10	0	0
e2, f2, g1, h2	0	10	0	0	0	10	0	0
e2, f2, g2, h1	0	8	0	0	0	9	0	O
e2, f2, g2, h2	0	10	0	0	0	10	0	0

Note: factor symbols are defined in Table 1

Table 6. Feasibility results for the LS algorithm

From Table 6 it can bee seen that of the 128 treatments solved with the LS algorithm, on 48 occasions it did not find even a single feasible solution to the 10 problems at that treatment. On the whole the LS algorithm did not find feasible solution to 490 out of the 1280 problems presented to it. When high utilization problems alone are considered the algorithm found solutions for only 150 out of the 640 (about 23%) problems presented to it. Furthermore, the algorithm did not find a single feasible solution out of the 320 high utilization uniform demand problems presented to it.

	b1			 <u>b2</u>				
	С	:1	c	2	С	l		c2
	d1	d2	d1	d2	d 1	d2	d I	d2
el, fl, gl, hl	9	10	10	10	10	10	10	10
e1, f1, g1, h2	10	10	10	10	10	10	10	10
el, fl, g2, hl	9	10	3	10	10	10	10	10
el, fl, g2, h2	10	10	10	10	10	10	10	10
e1, f2, g1, h1	1	10	3	10	10	10	10	10
e1, f2, g1, h2	10	10	10	10	10	10	10	10
e1, f2, g2, h1	6	8	0	9	10	10	10	10
e1, f2, g2, h2	10	10	10	10	10	10	10	10
e2, f1, g1, h1	0	3	0	0	0	10	0	0
e2, f1, g1, h2	10	9	5	2	0	10	0	0
e2, f1, g2, h1	0	3	0	0	0	10	0	0
e2, f1, g2, h2	10	9	1	4	0	10	0	0
e2, f2, g1, h1	0	1	0	0	1	5	0	0
e2, f2, g1, h2	10	9	10	10	10	10	0	0
e2, f2, g2, h1	0	0	O	0	3	4	0	0
e2, f2, g2, h2	10	10	10	9	7	10	0	0

Note: Factor symbols are defined in Table 1

Table 7 Feasibility results for the RA algorithm

The reason for these disappointing results can be found in the way the algorithm operates. The LS algorithm is initiated by assuming a schedule equal to the demand

matrix. When this initial schedule is sequenced and capacity requirements calculated capacity requirements are greater than capacity availability in every period. This does not leave the algorithm any room to maneuver, as the capacity availability is checked before the lots are shifted. This situation is further aggravated in uniform demand environment where there are more products in each period of the demand matrix, causing increased setup time requirements.

	bl				b2				
		:1	C	2		-1	С	2	
	dl	d2	dl	d2	dl	d2	d I	d2	
el, fl, gl, hl	10	10	10	10	10	10	10	10	
el, fl, gl, h2	10	10	10	10	10	10	10	10	
el, fl, g2, h1	10	10	10	10	10	10	10	10	
e1, f1, g2, h2	10	10	10	10	10	10	10	10	
el, f2, g1, h1	10	10	10	10	10	10	10	10	
el, f2, g1, h2	10	10	10	10	10	10	10	10	
el, f2, g2, h1	10	10	10	10	10	01	01	01	
e1, f2, g2, h2	10	10	10	10	10	10	10	10	
e2, f1, g1, h1	9	9	0	1	10	10	10	9	
e2, f1, g1, h2	10	10	10	10	10	10	10	10	
e2, f1, g2, h1	10	8	0	0	10	10	10	10	
e2, f1, g2, h2	10	10	10	10	10	10	10	10	
e2, f2, g1, h1	1	3	0	0	9	10	10	6	
e2, f2, g1, h2	10	10	10	10	10	10	10	10	
e2, f2, g2, h1	1	4	0	0	10	9	10	7	
e2, f2, g2, h2	10	10	10	10	10	10	10	10	

Note: Factor symbols are defined in Table 1

Table 8. Feasibility results for the ROP algorithm

The RA algorithm ended up with infeasible solution for 457 out of the 1280 problems it was used on. Similar numbers for the ROP algorithm is 124 out of 1280. The RA algorithm by ignoring the capacity requirements initially is able to find more

compared with 0 out of 320 for the LS algorithm. However, for this very same reason it fails to find a feasible solution for 42 out of the 640 low utilization problems, whereas the LS algorithm was able to find feasible solutions for all of these problems. This is caused by the unrestrained overloading of certain periods by the unconstrained single item optimization routine solved initially. The overloading is so great that the infeasibility elimination routine cannot find feasible periods to move the excess capacity. From the ROP feasibility results, it can be seen that placing restraints on the initial single item routine does increase the chance of finding a feasible solution. However, for some treatment combinations none of the methods proposed here are able to find a feasible solution. When all the problem instances are considered, there are only 10 out of 640 (1.6%) for which the ROP problem with the MIN setup cost estimator did not find a feasible solution. This is a very low percentage considering the fact that it is not known if these problems have a feasible solution at all.

Analysis of feasibility results indicates that ROP algorithm is superior to RA and LS algorithms for finding feasible solutions. However, it might very well be that the other two methods out perform the ROP algorithm in instances when they do find feasible solutions. Besides, it is yet to be determined if these algorithms are in fact better than the base case methods namely, EMQ and NL. Before such comparisons can be attempted, it is necessary to determine if the performance of the algorithms is affected by the interaction of the algorithms with nature of demand and inventory cost factors. This

requires a test of hypothesis 2 stated in chapter V. The testing methodology and the results are described in the next section.

Test of Hypothesis 2

As per the strategy presented in chapter V, hypothesis 2 is first tested. The results of the unbalanced ANOVA are first examined for the importance of the interactions between main effects. Testing methodology for hypothesis 1 is dependent on the results of test for hypothesis 2. If interactions are unimportant then the same ANOVA model can be used to test for hypothesis 1. On the other hand, if the interactions are important then, the ANOVA model has to be modified before hypothesis 1 is tested. Hence, at this stage of the statistical analysis we are merely interested in the presence of interaction effects between the factors. The test for hypothesis 2 can be formally stated as

H₀: Interaction effects are significant

H_a: Interaction effects are not significant

The relevant results of the SAS output for ANOVA model are presented in Table 9. The F value for the interaction effects is given by the equation

$$F^* = \frac{Mean\ Square\ Interactions}{Mean\ Square\ Error}.$$
 For $\alpha = 0.05$ the decision rule becomes

If $F^* > F(0.95, 539, 4779)$ conclude H_o

If $F^* \le F(0.95, 539, 4779)$ conclude H_a

 $F^* = 62.79$ and $F \cong 1$, accept H_o . Therefore, with a confidence of 95% ($\alpha = 0.05$) the results indicate that the interactions are important.

Source	DF	Sum of Squares	Mean Square	F Value
A*B*C*D*E*F*G*H	539	75266.64	139.64	62.79
Model	550	177445.45	322.63	145.07
Error	4779	10628.40	2.22	
Corrected Total	5329	188073.86		

Note: Factor levels are defined in table 1

Table 9. ANOVA results for test of hypothesis 2

However, the reliability of the ANOVA results in this particular instance is questionable. This is caused by the unbalanced nature of the input data. Especially, presence of empty cells (treatments at which at which no data are available) leaves the software to make assumptions of the data that can be undesirable (Neter et al 1990). However, the ANOVA results reinforce the influence of factors observed in the feasibility analysis. Therefore, it seems reasonable to assume that interactions are significant. This is a safer conclusion to arrive at than to decide that interactions are not important, as supported by the following analysis.

The first option is to test further (test for hypothesis 1) on the assumption that interactions are important. Then the means of the solution approaches would have to be compared at each one of the 64 treatments. During this analysis, some treatments that do not give a feasible solutions can be dropped from consideration resulting in a more balanced design. It is possible that the interactions were not actually important and this option was selected. In this worst case scenario the maximum damage done is the time invested in performing the more detailed analysis.

The second option is to continue on the assumption that interactions are not important. This makes test of hypothesis 1 much easier as only one more ANOVA run need to be carried out. But, the penalty for having made the wrong choice in this case is substantial. For example, based on all means it can be determined that ROP is superior to other algorithms. This does not mean that ROP out performs all other algorithms under every treatment. It is possible that the LS algorithm out performs the ROP in a low utilization uniform demand environment or alternatively it is possible that there exists no significant difference between the performance of the algorithms at certain treatments. The possibility of arriving at a result similar to the one just described would be completely missed if option 2 is selected.

As indicated by the above discussion, the more conservative option 1 is a better choice. Accordingly, hypothesis 1 is performed over all 64 treatments. This process is described in the next section.

Test of Hypothesis 1

Since significant interactions are present between the factors a single comparison across all factor level combinations would not represent the actual reality about the performance of the algorithms. This can only be found out if the treatment means are compared using the Tukey procedure.

However, this drastically increases the number of Tukey tests to be performed. There are 4 demand factor levels and 2 inventory cost factor levels yielding 64 (2⁴x2²) treatments. Hence, 64 single factor ANOVA models are run and each time the 10

solution approaches, listed in Table 4, are compared to determine the best solution for a given treatment. It is possible that for a given treatment one or more of the algorithms developed here provide infeasible solutions. In these cases, the comparison of means must be based on unequal sample sizes. Fortunately, the Tukey procedure used for comparison of means can accommodate unequal sample sizes. In fact when the sample sizes are unequal the results obtained from Tukey tests are more conservative (Neter et al. 1990). This allows for the comparison of those solution approaches that find feasible solutions for at least 1 of the 10 problems presented to it.

The complete ranking of solution approaches by performance at each ANOVA run is presented in Appendix D. For each of the 64 treatments, this appendix lists the mean performance measure for each solution approach, the number of feasible solutions found and which solution approaches are significantly different from others. The solution approach(es) that provides significantly lower performance measure than others at each ANOVA run is presented in Table 10. The solution approach number presented here are the same those used in Table 4. This table lists, for each treatment, the solution approach(es) that provide significantly lower performance measures than others. When more that one solution approach is listed in a treatment it is listed in the ascending order performance measures, i.e., the solution approach listed first is better than other listed solution approaches but not significantly better. At these treatments, we cannot say that one approach is better than others listed for that treatment. Formally hypothesis 1 can be stated as:

H_o: A solution approach developed here produces significantly lower schedule costs than base cases

H_a: Otherwise

Hypothesis II is tested after each ANOVA run, if the solution approach that provides the significantly lower performance measure is a combination of an algorithm developed here and a setup estimator then accept H_o . Any other result substantiates the acceptance of H_a .

From Table 10 it is seen that solution approach 6 (ROP with MIN setup estimator) provides the lowest cost feasible schedule at each treatment. However, at some treatments its cost do not substantially deviate from some other methods proposed here. Also, at all treatments but four, solution approach 6 provides significantly lower performance measure ratio than any of the base cases. Thus, the hypothesis H_o is valid for 60 out of the 64 treatments. The four treatments that do not support H_o have the following factor combinations:

treatment 1: c2, d1, e2, f2, g1, h1;

treatment 2: c2, d1, e2, f2, g1, h2;

treatment 3: c2, d2, e2, f2, g1, h1;

treatment 4: c2, d2, e2, f2, g2, h1.

			c]				c2	
	d1		p	2	d1		d2	
	el	e2	e]	e2	e]	e2	el	e2
gl, h1	9	9	6,5,2,4,1,3	6,2,1,4,5	9	9	6,4,2,1	9
g1, h2	9	9	6,5,2,4,1,3		9	9	6,4,2,1	9
f1, g2, h1	6,2,4	6,5	6,2,4,5,1,3		6,4 6	9	6,4,2,1,3,5	9
g2, h2	6,2,4	9	6,2,4,5,1,3		6,4,2	9	6,4,2,1,3,5	6,5
g1, h1	9	9	6,5,1,4,2,3		6,4	8,9	6,4,1,2	6,8,7
g1, h2	9	9	6,5,4,1,2,3		6,4	8,9	6,4,5	9
g2, h1	9	9	6,5,4,1,2,3	6,5,4,2,1	9	9	6,4,2	6,7,8
g2, h2	9	9	6,4,1,2	6,2,1,4,5,3	9	9	6,4	9

Note: Solution approaches are defined in Table 5.4, factor symbols are defined in Table 5.1

Table 10. Best solution approach for each demand and inventory cost combination

The four treatments that substantiate H_a are high utilization large problems with high setup cost factors. At these treatments, solution approach 6 performs better than any of the current approaches though not significantly better. The following analysis is based on the cost values listed in Appendix C and performance measure comparisons in Appendix D for each of the above four treatments. The reason for narrowing performance gap can be explained as follows:

1. Treatment 1 and treatment 2: These are long schedule horizon problems with uniform demand type. The average daily demand values used to calculate EMQ lot sizes is a close approximation of the actual demand values. When EMO is used in these circumstances, the scheduling cycles tends to balance out with the demand pattern (Elmagrabhy 1978). This is especially true when EMQ is used with MIN setup estimator (approach 8) as this tends to produce smaller lots resulting in shorter cycles. Further, at these particular treatments the penalty for backlogging is low, and this reduces the cost for deviating from customer requirements. The corrections for capacity constraints using the "overload penalty" has a significant effect in these demand patterns. This is especially true for the items that have lower average cost per unit as defined in chapter IV (these tend to be scheduled later when most the earlier items have cornered substantial amounts of the available capacity). For this reason, optimal solutions for the single item problems are drastically affected by the "overload penalty". Furthermore, due to the tight capacity considerations the infeasibility elimination part of the heuristic can find feasible solutions only with substantial increase in costs incurred. This explains the narrowed gap in the quality

- of solutions provided by approaches 6 and 8. However, it must be emphasized that the schedules generated by approach 6 are feasible whereas those generated by approach 8 are not necessarily so.
- 2. Treatment 3 and treatment 4: The reason for the statistical indifference at these treatments lies in calculation of performance measures. Once again, performance measure is the ratio of the minimum cost schedule found for a problem divided into the cost of schedule determined by the approach in question. However, these performance measures are skewed when none of the approaches proposed here is able to find a feasible solution. At treatment 3 there are 4 such problem instances and at treatment 4 there are 3 such instances. For these problem instances, the performance measure for either approach 7 or 8 equals 1 because they provide the lowest cost schedule amongst the base cases (remember, only feasible solutions amongst the algorithms proposed here are considered for statistical comparison). Therefore, at these treatments the repetitions used for Tukey procedure is unbalanced, with ten repetitions for the base cases and 6 repetitions at treatment 3 and 7 repetitions at treatment 4 for approach 6. For solution approaches 7 and 8, this leads to 4 performance measures of "1" at treatment 3 and 3 such values in treatment 4. These values reduce the statistical difference between the means of the approaches. However, when approach 6 is able to find feasible solutions, these solutions out perform those found by approaches 7 and 8, by at least, a factor of 2. For this reason, when only the problem instances for which approach 6 found a

feasible solution are compared the difference between the procedures becomes significant.

From the analysis thus far, it can be seen that solution approach 6 is superior to the other approaches tested here. In an experiment of the size performed here, several inferences can be drawn about the general performance of the approaches that do not directly relate to either of the hypotheses. These inferences are not statistically tested but are based on rough cut analysis of the experimental and statistical results. These general trends in the performance of the solution approaches are discussed below.

Other Results

- The above comparisons are made without testing for the feasibility of EMQ and NL
 algorithms. Since feasibility requirements merely increase the cost of schedules, this
 arrangement gives a fair shake to the traditional algorithms.
- 2. The LS, RA, and ROP algorithms perform better with MIN setup estimator than with the MAX setup estimator. This indicates that a conservative approach in estimating the potential setup cost savings is preferable. Also, the MIN estimator under estimates the setup time requirements and this encourages greater mobility when the lots are shifted around to achieve feasibility.
- 3. In small problem sizes with lumpy demand environment LS and RA based approaches provide good solutions that are mostly statistically indifferent from ROP based approaches. This is true in both low utilization and high utilization rates.
 However, in large problem environments with lumpy demand there is a significant

difference in performance under low utilization and high utilization rates. In such problems, when the LS and RA based approaches are able to find feasible solutions they tend to be as good as ROP approach. But, in large high utilization environments they are less likely to find feasible solutions.

4. Between two problems with the same capacity utilization the one with the greater number of products is more difficult to solve. This is due to the non-negligible setup times required for switching between products. This difference is greater in uniform demand environments, where greater number of setups are generally required.

Summary

In this chapter, the results of the experiments have been analyzed. The ability of the algorithms proposed to provide feasible solutions was analyzed. Results indicate that a "overload penalty" between successive solutions to the single item lot sizing problem is a far superior approach compared to other algorithms tested here. Especially, when the ROP algorithm is used with MIN setup estimator (solution approach 6), it fails to find a feasible solution to only 1.6% of the 640 problems solved using the approach.

An ANOVA test for the significance of interactions between the factors indicated that interactions are significant. The Tukey procedure was used to compare the performance of the approaches at each treatment defined by these interactions. Once again, approach 6 performed better than other approaches tested at all treatments. In 28 of the 64 treatments approach 6 was significantly better than other approaches and in 60

out of the 64 treatments the approaches proposed in this research performed significantly better than the base cases.

So far the methodology, experimentation and analysis of the results of the experimentation have been described. In the next chapter, conclusions that can be drawn from this research study are presented, the significant contributions are highlighted and directions for future research are discussed.

CHAPTER VII

CONCLUSIONS, CONTRIBUTIONS AND FUTURE RESEARCH

This research was a significant undertaking in the area of scheduling in a dynamic demand environment. This study has explored the use of information that already exists in a manufacturing enterprise to develop better, less expensive, schedules. The implications of this study, in terms of major conclusions, contributions, and directions for future research are discussed in this chapter. Definite conclusions can be drawn from the vast array of problems which were addressed here. This research was built upon results obtained by previous researchers and has further extended the knowledge in the area of dynamic lot sizing and scheduling. Because of the complexity of the problem, research in the area of lot sizing and scheduling has been on going for several decades. Potential cost savings ensure that it is likely to be on going for several decades into the future. In the next section, conclusions that can be drawn from the analysis of results in chapter VI are discussed.

Conclusions

The problem of determining schedules, including lot sizes, sequence and timing, in a dynamic demand environment in the presence of sequence dependent setups, finite capacity, setup carryover and variable backlogging has been successfully addressed in this research. Three different heuristics, each used with two different setup cost estimators, for solving the problem have been proposed, studied and evaluated. These heuristics are compared with two base cases, NL and EMQ. In all, ten solution

approaches have been extensively tested and their performance evaluated over a wide variety of problem instances duplicating real world problem conditions. Results show that the regeneration algorithm with "overload penalty" (ROP) using minimum setup estimating procedure (MIN) is most adept in finding feasible solutions.

Statistical analysis of the schedule costs generated by the algorithms indicates that the demand environment and the inventory related costs in the production system significantly affect the performance of the solution approaches. However, further analysis shows that for a majority of factor combinations the ROP heuristic used in combination with MIN setup estimator significantly out performs all other solution approaches tested. In treatments at which the solution approach is not significantly better than other approaches it performs at least as well as any other solution approach.

Each of the 10 solution approaches tried here is tested over the same set of 640 problem instances. Table 11 shows:

- the number of times each solution approach found the minimum cost feasible schedule over all the approaches tested,
- 2. the worst case performance of the algorithm, expressed using the same performance measure used in the statistical analysis, and
- 3. the average performance measure for the algorithm.

The table clearly indicates that solution approach 6 (combination of ROP and MIN) is superior to all others. On the average the cost of schedules generated by EMQ is at least 5.8 times and those generated by no lot size method is 9.5 times the cost of schedules generated using solution approach 6. Finally, this research shows that with intelligent

application of operations research techniques good solutions can be obtained to even the most challenging large scheduling problems.

Solution Approach	Number of Minimum Cost Solutions	Worst Case Performance	Average Performance
1	3	4.85	2.07
2	3	4.21	1.90
3	0	8.57	2.66
4	1	4.21	1.85
5	2	11.4.3	2.54
6	623	1.21	1.00
7	4	19.44	5.82
8	9	47.89	7.80
9	0	40.92	9.55
10	0	40.92	9.55

Note: Solution approaches are defined in Table 4

Table 11. Relative performance of solution approaches

Contributions

In this study, in addition to development, implementation and testing of heuristic solutions to a complex dynamic lot sizing and scheduling problem, several other contributions have been made to the literature in the area of production scheduling.

These contributions are listed below.

Formulation of the Problem: In this study, a new formulation is presented for a real
world scheduling problem. This extends the formulation introduced by
Gopalakrisknan et al (1995). This formulation can potentially be used by other
operations research practitioners to determine alternate approaches to solve the
problem.

- 2. Solution Improvement Techniques: Two extensions to the Wagner-Whitin (Wagner and Whitin 1958) extreme point property have been proposed and proved. These extensions allow the application of the property when backlogging is allowed. In this study, they have been incorporated into each of the algorithms proposed here and are applied to improve the quality of the solutions determined by the algorithms.
- 3. Optimal Sequencing Technique: In this research, a new procedure, a combination of dynamic programming and a heuristic solution to the TSP problem, has been found to determine the optimal sequence for production once the production lots within each period is determined. This technique provides significant cost reductions when used in a sequence dependent setup environment. At a practical level, this method provides an optimal solution to most real world sequencing problems. The sequencing technique can be used in other sequence dependent setup environments. For example, it can be used as part of algorithms that assume sequence dependent setup costs, zero setup times and no backlogging, a problem studied by Fleischmann (1994).
- 4. "Overload penalty": In this study "overload penalty" plays a crucial role in generating not only feasible schedules but also superior quality schedules. "Overload penalty" is based on the marginal cost of eliminating infeasibility. This simple yet powerful concept can be transformed into other multi-item environments. This allows the solution approaches to take advantage of optimal solutions to simpler problems. This elegant approach can be used in place of the mathematically daunting Lagrangean relaxation approach.

5. Problem Size: This study is different from previous studies in that it makes very few assumptions about the nature of demand and inventory related costs in the real world production system. By solving several variations of large problems (15 products 30 periods), this research has shown that it is not necessary to make assumptions that debilitate the quality of results when attempting to develop solutions large real world scheduling problems.

Directions for Future Research

The problem of dynamic lot sizing and scheduling is NP hard hence, it is unlikely that optimal solutions for complex problems in this area can be found within reasonable computational efforts. For this reason, heuristic approaches have to be developed to solve scheduling problems in real world production systems. In this research, a set of approaches have been proposed to generate schedules in the presence of several complicating factors. However, there exists a possibility for improving the quality of solutions. The potential savings in production costs resulting from efficient schedules justifies further research in this area. Research work here can be extended in the following directions:

1. Setup estimator: It has been reported that MIN and MAX provide the best estimates of setup time and cost (Dilts and Ramsing 1989). In this research, both setup time and setup costs are estimated using only one of these estimators at a time. However, it may be possible to obtain better schedules by using the MAX estimator to estimate setup costs and MIN estimator to estimate setup time. The reasoning being that

- MAX cost estimator encourages elimination of greater number of lots to reduce setups and the MIN time estimator will increase the mobility of the lots when infeasibility eliminating routine tries to shift production to eliminate infeasibility.
- 2. "Overload penalty": In this study, only one type of "overload penalty" is used. The penalty for exceeding capacity is proportional to the square of the difference between required capacity and available capacity. The function used to determine the "overload penalty" affects the schedules generated. When the "overload penalty" is linear, it may not have a significant effect on the overloading of periods resulting in greater number of infeasible solutions. On the other hand, a higher degree polynomial may negatively affect the quality of the solution in low capacity utilization environments. More work is needed to determine the exact relationship between the "overload penalty" and capacity overloading.

Summary

A comprehensive study has been performed on a class of real world multi-item dynamic lot sizing and scheduling problem. The problem formulation accounts for all possible significant factors that affect the quality of schedules. These are: known dynamic demand, multiple items, capacity constraint, sequence dependent setup cost and setup time, finite variable backlogging, and setup carryover. A review of current research showed that solutions, to the scheduling problem of the complexity attempted here, has not been attempted yet. Yet the benefit accruing from the solution methodology is very real. It was statistically proven that the regeneration algorithm with

"overload penalty" is the most effective solution approach to this problem. On an average the cost of schedules generated by EMQ computations was at least 5.8 times the cost of feasible schedules generated by the regeneration algorithm with "overload penalty".

NOMENCLATURE

- A_i setup cost per production lot of i, independent of sequence (\$/setup)
- b; penalty cost for backlogging per unit per period for i (\$/hour/day)
- C_t capacity available in a period t (hour)
- C_{TSP} cost of the solution provided by the TSP algorithm (\$)
- $c_{tk}^{t'}$ cost of producing a lot in period t' to meet all demand between the regeneration points of t and k (\$)
- dit demand for product i in day t (hour)
- E_{tk}^{i} estimated savings from moving product i from t to k (\$)
- f_t minimum cost incurred between regeneration points t and T (\$)
- fp_t^k product that will be produced first by state k on day t
- h_i inventory holding cost per unit per period for i (\$\hour/day)
- H_i inventory/backlogging cost for i (\$)
- i item index $(i = 1, 2, \ldots, N)$
- I_{it} inventory of item i at the end of period t (hour)
- j item index (j = 1, 2, ..., N)
- l number of products currently included in the TSP sequence
- lp_t^k product that will be produced last by state k on day t
- N number of products in the system
- n_{t} number of products scheduled for production on day t
- o_{kt} product sequenced kth on day t

- p_i production rate for i per period (unit/period) where $p_i > r_i$
- PC_t^k lowest possible setup cost from state k in period t to T (\$)
- qt slack capacity available in period t, a negative value indicates overloading (hour)
- Q_i lot size for i resulting from EOQ and EMQ computations (unit/cycle)
- $\sum_{i}^{T} d_{it}$ r_i demand rate for i per period (unit/period); $r_i = \frac{t=1}{T}$
- s_{ij} setup time to switch from product i to product j (hour)
- s_i estimated setup time (hour)
- S_{ij} cost to switch from product i to product j (\$)
- S_i estimated setup cost (\$)
- SC_i average cost per unit time per setup (\$/period/setup)
- t period index $(t = 1, 2, \ldots, T)$
- tg target period to move production to achieve feasibility
- TC the total cost of a feasible schedule (\$)
- TSP_t^k cost returned by the TSP algorithm for state k on day t (\$)
- $U_i(t)$ marginal cost coefficient for i if demand in period t is produced in period 1 (\$/time²/unit)
- V_i the average cost per unit for i estimated using EOQ formula (\$/unit)
- w_{it} 1 if i is produced in period t0 otherwise
- x_{it} production lot scheduled for i in period t (hour)

- y_{ijt} 1 if product j is produced immediately after product i in period t 0 otherwise
- α maximum number of periods of backlogging allowed (day)
- β_{it} 1 if product i is produced last in period t 0 otherwise
- Δ set of items for which lot sizes have already been determined
- ΔH_{μ} change in inventory/backlogging cost associated with product μ (\$)
- φ_i the product occupying the ith position in the TSP sequence
- γ_i^k cost of including product i in the current TSP sequence at position k (\$)

$$\gamma_i^{\,k} = (S_{\phi_{k-1}i} + S_{i\phi_k}\,)$$
 where k = 2, . . ., l+1

- η quantity to be moved to remove infeasibility (hour)
- λ_{it} 1 if product i is produced first in period t 0 otherwise
- μ product selected for moving to remove infeasibility
- Π_{t} set of items that have production lots > 0 in period t, i.e. $i \in \Pi_{t}$ iff $x_{it} > 0$
- θ_k cost of kth sequence when solving TSP by complete enumeration;

$$k = 1, 2, ..., {n_t \choose 2} P$$
 (\$)

- ρ_i utilization ratio for $i = \frac{r_i}{p_i}$
- σ_l^k state in t+1 that gives the lowest cost solution for state k in period t to T (\$)
- τ_i cycle time for item i (period)
- ω_t idle capacity in period t (hour)

- $\boldsymbol{\xi}_t^{\,k}$ sequence returned by the TSP algorithm for state k on day t
- ψ set of nodes not yet included in TSP sequence
- ζ overload penalty (hours²)
- ∇ cost of moving 1 unit of the selected product to target period (\$/hour)

REFERENCES

- ARAS, O. A., and SWANSON, L. A., 1982, A lot sizing and sequencing algorithm for dynamic demands upon a single facility. *Journal of Operations Management*, 2 (3), 177-185.
- BARR, R. S., BRUCE G. L., KELLY J. P., RESENDE M. G. C., and STEWART, W. R., 1995, Designing and reporting on computational experiments with heuristic methods. *Journal of Heuristics*, 1 (1), 1-27.
- BOMBERGER, E., 1966, A dynamic programming approach to a lot size scheduling problem. *Management Science*, **12** (11), 778-784.
- BRATCHER, T. L., MORAN, M. A., ZIMMER, W. J., 1970, Tables of sample sizes in the analysis of variance. *Journal of Quality Technology*, **2** (3), 156-164.
- CATTRYSSE, D., MAES, J., and VAN WASSENHOVE, L. N., 1990, Set partitioning and column generation heuristics for capacitated dynamic lot sizing. *European Journal of Operational Research*, **46** (1), 38-47.
- CATTYRSSE, D., SALOMON, M., KUIK, R., and VAN WASSENHOVE. L. N., 1993, A dual ascent and column generation heuristic for discrete lot sizing and scheduling problem with setup times. *Management Science*, **39** (4), 477-486.
- CHEN, W. H., and THIZY, J. M., 1987, Analysis of relaxations for the multi-item capacitated lot sizing problem. *Technical Report 86-1-3* (School of Management and Department of Industrial Engineering, NY: State University at Buffalo).

- CHOO, E. U. and CHAN, G. H., 1990, Two-way eyeballing heuristics in dynamic lotsizing with backlogging. *Computers and Operations Research*, 17 (4), 359-363.
- DAVIS, S. G., 1990, Scheduling economic lot size production runs. *Management Science*, **36** (8), 985-998.
- DILTS, D. M. and RAMSING, K. D., 1989, Joint lot sizing and scheduling of multiple items with sequence dependent setup costs. *Decision Sciences*, **20** (1), 120-133.
- DIXON, P. S. and SILVER, E. A., 1981, A heuristic solution procedure for the multi-item, single-level, limited capacity, lot-sizing problem. *Journal of Operations Management*, 2 (1), 23-39.
- DOGRAMACI, A., PANAYIOTOPOULOS, J. C., and ADAM, N. R., 1981, The dynamic lot-sizing problem for multiple items under limited capacity. *AIIE Transactions*, **13** (4), 294-303.
- EISENHUT, P. S., 1975, A dynamic lot sizing algorithm with capacity constraints. *AIIE Transactions*, 7 (2), 170-176.
- ELMAGHRABY, S. E., 1978, The economic lot scheduling problem (ELSP): review and extensions. *Management Science*, **24** (6), 587-598.
- FLEISCHMANN, B., 1990, The discrete lot-sizing and scheduling problem. *European Journal of Operational Research*, 44 (3), 337-348.
- FLEISCHMANN, B., 1994, The discrete lot-sizing and scheduling problem with sequence dependent setup costs. *European Journal of Operational Research*, 75 (2) 395-404.

- FLORIAN, M., LENSTRA, J. K., and RINNOOY KAN, A. H. G., 1980, Deterministic production planning algorithms and complexity. *Management Science*, **26** (7), 669-679.
- GOPALAKRISHNAN, M., MILLER, D. M., and SCHMIDT, C. P., 1995, A framework for modeling setup carryover in the capacitated lot sizing problem. *International Journal of Production Research*, **33** (7), 1973-1988.
- HANSSMANN, F., 1962, Operations Research in Production and Inventory (New York, NY: John Wiley and Sons)
- HARRIS, F. W., 1913, How many parts to make at once. Factory, The Magazine of Management, 10 (2), 135-136.
- HSIEH, H., LAM, K. F., and CHOO, E. U., 1992, Comparative study of dynamic lot sizing heuristics with backlogging. *Computers and Operations Research*, **19** (5), 393-407.
- HSU, W., 1983, On the general feasibility test of scheduling lot sizes for several products on one machine. *Management Science*, **29** (1), 93-105.
- KARMARKAR, U. S. and SCHRAGE, L., 1985, The deterministic dynamic product cycling problem. *Operations Research*, **33** (2), 326-345.
- KIM, D. and MABERT, V. A., 1995, Integrative versus separate cycle scheduling heuristics for capacitated discrete lot sizing and sequencing problems. *International Journal* of Production Research, 33 (7), 2007-2021.
- KIRCA, O. and KOKTEN, M., 1994, A new heuristic approach for the multi-item dynamic lot sizing problem. *European Journal of Operational Research*, 75 (2), 322-341.

- KOEPKE, C. A., 1941, *Plant Production Control* (New York, NY: John Wiley and Sons Inc.).
- LAMBRECHT, M. R. and VANDERVEKEN, H., 1979, Heuristic procedures for the single operation, multi-item loading problem. *AIIE Transactions*, **11** (4), 319-326.
- LAWLER, E. L., 1976, *Combinatorial Optimization: Networks and Matroids* (New York, NY: Holt, Rinehart and Winston).
- LAWLER, E. L., LENSTRA, J. K., RINNOOY KAN, A. H. G., and SHMOYS, D. B., 1985, *The Traveling Salesman Problem* (New York NY: John Wiley and Sons).
- LITTLE, J. D. C., MURTY, K. G., SWEENEY, D. W., and KAREL, C., 1963, An algorithm for the traveling salesman problem. *Operations Research*, 11 (6), 972-989.
- MAES, J. and VAN WASSENHOVE, L. N., 1986, Multi item single level capacitated dynamic lot sizing heuristics: a computational comparison (part 1: static case). *IIE Transactions*, **18** (2), 114-123.
- MANNE, A.S., and VEINOTT, A. F., 1967, Optimal plant size with arbitrary increasing time of paths demand. *Investments for Capacity Expansion: Size, Location and Time Phasing*, A. S. Manne (ed) (Cambridge, MA: The M.I.T. Press), pp. 178-190.
- MATHUR, K and SOLOW, D., 1994, Management science: The Art of Decision Making (Englewood Cliffs, NJ: Prentice Hall).
- NETER, J., WASSERMAN, W., and KUTNER, M. H., 1990, Applied Linear Statistical Models, 3rd edn (Homewood, IL: IRWIN)

- RITCHIE, E., TSADO, A. K., 1986, A review of lot-sizing techniques for deterministic time-varying demand. *Production and Inventory Management Journal*, **27** (3), 65-79.
- SALOMON, M., 1991, Deterministic Lot Sizing Models for Production Planning (New York, NY: Springer-Verlag).
- SILVER, E. A., and MEAL, H. C., 1969, A simple modification of the EOQ for the case of a varying demand rate. *Production and Inventory Management Journal*, **10** (4), 52-65.
- TAHA, H. A., 1975, Integer Programming: Theory, Applications and Computations (Academic Press).
- THIZY, J. M., and VAN WASSENHOVE, L. N., 1985, Lagrangean relaxation for the multiitem capacitated lot-sizing problem: a heuristic implementation. *IIE Transactions*, 17 (4), 308-313.
- TRIGEIRO, W. W., THOMAS, L. J., and MCCLAIN, J. O., 1989, Capacitated lot sizing with setup times. *Management Science*, **35** (3), 353-366.
- TRIGEIRO, W. W., 1989, A simple heuristic for lot sizing with setup times. *Decision Sciences*, **20** (2), 294-303.
- TURBIDE, D. A., 1995, MRP II: still number one. *Industrial Engineering Solutions*, 27 (7), 28-31.
- WAGNER, H. M., and WHITIN, T. M., 1958, Dynamic version of the economic lot size model. *Management Science*, 5 (1), 89-96.

- WALLACE, T. F., 1990, MRP II: Making It Happen: The Implementer's Quick Guide to Success with Manufacturing Resource Planning, (Essex Junction, VT: O. Wight Ltd.).
- ZANGWILL, W. I., 1966, A deterministic multi-period production scheduling model with backlogging. *Management Science*, **13** (1), 105-119.
- ZANGWILL, W. I., 1969, A backlogging model and a multi-echelon model of a dynamic economic lot size production system-a network approach. *Management Science*, **15** (9), 506-527.

APPENDIX A

NUMERICAL EXAMPLE

Consider the 4 product 5 period problem with demand matrix given in Table A.1 and setup time matrix in Table A.2. Demand as well as setup time is expressed in hours of production.

		Period			
Product	_1	2	3	4	5 _
A	3	0	0	2	0
В	0	6	0	1	4
С	2	0	3	0	0
D	0	0	5	0	2

Table A.1 Demand Matrix

	To Product							
From	A	В	С	D				
A	0	1	1	2				
В	2	0	1	2				
С	1	3	0	1				
D	1	1	2	0				

Table A.2 Setup Matrix

In addition capacity is 8 hours per day $C_i = 8 \ \forall \ t$; Setup cost factor = 3, i.e. $S_{ij} = 3*s_{ij}$; backlogging limit $\alpha = 2$; $h_i = 1 \ \forall \ i$; $b_i = 2 \ \forall \ i$. The problem will be solved using the minimum setup estimator (MIN) to convert sequence dependent setup to sequence independent setup.

No Lot Sizing

In this method all the requirements over the scheduling horizon is produced in one lot. Lot size for items are obtained by adding up their demand over the entire

horizon. For example the lot size for product A is 3+2=5. Similarly, lot size for other items would be 11, 5 and 7 for items B, C and D respectively. The sequencing problem here is simply to determine the sequence that provides the lowest sum of setup costs. From inspection of the setup time matrix the optimal sequence $A \rightarrow B \rightarrow C \rightarrow D$ is determined, with a total setup time of 3 and a setup cost of 9 (no setup time is levied for product A as per convention defined in chapter I). Taking capacity considerations into account, production is scheduled as shown in Table A.3. Table A.4 indicates the number of units in inventory/backlogged at the end of the period.

	Period							
Product	1	2	3	4	5			
A	5	0	0	0	0			
В	2	8	l	0	0			
С	0	0	5	0	0			
D	0	0	0	7	0			

Table A.3 No Lot Size Schedule

	Period							
Product	1	2	3	4	5			
A	2	2	2	0	0			
В	2	4	5	4	0			
C	-2	-2	0	0	0			
D	0	0	-5	2	0			

Table A.4 No Lot Size Inventory/Backlogging

The total inventory cost is obtained by adding up all the positive values in Table A.4 and multiplying it by holding cost factor ($h_i = 1$). Similarly, backlogging cost is obtained by adding up all the negative values in Table A.4 and multiplying by

backlogging cost factor ($b_i = 2$). Therefore, the inventory/backlog cost is 23*1 + 9*2 = 41. There are only three setups performed with total setup time of 3 hours. Using setup cost per hour factor of 3 we get a total setup cost of 9. Therefore the total cost of the schedule is 9 + 41 = 50.

EMQ Calculations

The MIN setup estimator is used to estimate the setup time $s_A = \min(2, 1, 1) = 1$; similarly the setup time estimates for other products can be obtained; $s_B = 1$; $s_C = 1$ and $s_D = 1$. Using the setup cost factor (f=3) the estimates of setup costs can be calculated $S_A = 3*1 = 3$; similarly $S_B = 3$; $S_C = 3$; $S_D = 3$. The average demand values per period (r_i) is calculated next: $r_A = \frac{3+2}{5} = 1$; similarly $r_B = 2.2$; $r_C = 1$; $r_D = 1.4$. $p_i = 8$ for all i. Therefore, $\rho_A = 1/8$; $\rho_B = 11/40$; $\rho_C = 1/8$; $\rho_D = 7/40$. Now we can calculate the cycle time for each product using $\tau_i^* = \sqrt{\frac{2S_i}{h_i r_i (1 - \rho_i)}}$. This yields

$$\tau_A^* = \sqrt{\frac{2 \times 3}{1 \times 1 \times (1 - \frac{1}{8})}} = 2.619$$
; similarly $\tau_B^* = 1.94$; $\epsilon_C^* = 2.619$;

 $\tau_D^* = 2.279$ and the lot sizes are calculated using $r_i \tau_i^*$; for product A lot size = $1 \times 2.619 = 2.619$ which is rounded off to 3; similarly the lot sizes for other products can be calculated as 4, 3, and 3 respectively for items B, C, and D.

For products A and C only 2 lots are required to meet their cumulative demand.

Whereas, products B and D need 3 lots. Since the setup time to switch from D to A is

only 1 hour the optimal sequence remains the same. Making the required changes as stated in chapter IV we get the schedule shown in Table A.5 and Inventory/Backlogging situation shown in Table A.6.

	Period							
Product	I	2	3	4	5			
A	3	0	2	0	0			
В	4	0	4	0	3			
C	0	3	0	2	0			
D	0	3	0	3	3			

Table A.5 EMQ Schedule

	Period							
Product	1	2	3	4	5			
A	0	0	2	0	0			
В	4	-2	2	l	0			
С	-2	1	-2	0	0			
D	0	3	-2	l	0			

Table A.6 EMQ Inventory/Backlogging

The complete sequence of production is $A \rightarrow B \rightarrow C \rightarrow D \rightarrow A \rightarrow B \rightarrow C \rightarrow D \rightarrow B \rightarrow D$.

This results in a total setup cost of 30. The total inventory/backlogging cost is 14*1 + 8*2 = 30, yielding a total cost of 30 + 31 = 61.

A Lot Shifting Algorithm (LS)

The sequence independent setup costs and times are once again calculated using MIN estimator as $S_A = 3$; $S_B = 3$; $S_C = 3$; $S_D = 3$ and $S_A = 1$; $S_B = 1$; $S_C = 1$; $S_D = 1$

Step 1 The algorithm initially sets schedule = demand =
$$\begin{pmatrix} 3 & 0 & 0 & 2 & 0 \\ 0 & 6 & 0 & 1 & 4 \\ 2 & 0 & 3 & 0 & 0 \\ 0 & 0 & 5 & 0 & 2 \end{pmatrix}$$
 In this

matrix each column represents a day and each row represents a product. For example according to the above schedule the production lot for product B on day 4 is 1.

Step 2 In this step the schedule matrix is sequenced. Here there are 5 stages corresponding to each day in the horizon. Number of states in each stage is equal to the factorial of number non zero lots produced in that state. Stages 1, 3, 4 and 5 have 2 states each and stage 2 has 1 state. For example the 2 possible states for stage 1 are (A,C) and (C,A). Two dummy stages (stage 6 and stage 0) represent the transition from this scheduling horizon to the adjacent horizons.

The dynamic programming algorithm starts by first calculating the optimal setup cost sequence within each state. When there are several non-zero products in a period then a TSP algorithm is used to calculate the best sequence. However, in this situation this is a trivial problem as the maximum number of products produced on any day is 2. In this case the cost of sequence within each state is merely equal to the setup cost between the first product and the last product in the state. In stage 2 there is only one non zero lot (product B), in which case the cost of the state is zero.

The dynamic programming algorithm starts in stage 5 and goes back up to stage 0. For each state in a stage the algorithm determines the state in the next stage that produces the lowest cost sequence from that stage to stage 5 (equation 64). These calculations are shown in table A.7. The state in the next stage that produces the lowest

cost to stage 5 is shown in *italics*. Costs shown in the table are sum of cost of sequence within the state, cost of switching from the last product in the state to the first product in the state selected in next stage, and cost of going from state selected in next stage to stage 5. For example the cost of going from state (C,D) in stage 3 to stage 5 when the state in the next stage is (A,B) is the sum of:

- 1. cost of sequence (C,D) = 3,
- 2. cost of changing from product D in stage 3 to A in stage 4 = 3, and
- 3. cost from state (A,B) in stage 4 to stage 5 = 9, resulting in a total cost of 15.

Stage	State	State in next Stage	Cost
6	(0)	-	0
5	(B,D)	(0)	6
	(D,B)	(0)	3
4	(A,B)	(B,D)	y
		(D,B)	12
	(B,A)	(B,D)	15
		(D,B)	15
3	(C,D)	(A,B)	15
		(B,A)	21
	(D,C)	(A,B)	18
		(B,A)	30
2	(B)	(C,D)	18
		(D,C)	24
1	(A,C)	(B)	30
	(C,A)	<i>(B)</i>	24
0	(0)	(A,C)	30
		(C,A)	24

Table A.7 Cost of states

The algorithm then traces the optimal sequence starting from stage 0, at each stage selecting the state in the next stage that provides the lowest cost to stage 6 (equations 65 and 66). In relation to Table A.7 the optimal sequence is determined as follows:

- at stage 0 select state (C,A) in stage 1 as it has a lower cost than state (A,C)
- at stage 1 the only option in stage 2 is state B
- at stage 2 the best state in the next stage is state (C,D)
- for state (C,D) in stage 3 the best state in stage 4 is (A,B)
- for state (A,B) in stage 4 the best state in stage 5 is (B,D)

The sequence of production in each stage and across the scheduling horizon can be represented using the matrix $\begin{pmatrix} C & B & C & A & B \\ A & D & B & D \end{pmatrix}$. In this matrix the columns represent each stage (period) and the rows represent the sequence of production starting from the first row. Capacity availability/overloading for each period is calculated next. For example consider period 3. In this period capacity is required to switch production from product B in period 2 to product C, produce 3 units of product C, then switch to product D and produce 5 units of product D. The total capacity required in this period then is 1 + 3 + 1 + 5 = 10. Since the capacity available in each period is 8 we have an overload of 2 units. Overload is represented with a negative sign in the capacity availability matrix. Similar calculations for the other periods yields a capacity matrix of (2, 1, -2, 3, 0) for the schedule and sequence matrix listed above.

Step 3 In this step entire lots that can be moved to save setup costs are considered. Taking capacity availabilities into account entire lots that can be considered for moving are product A from period 4 to period 1 and product B from period 4 to period 2. The first move costs 6 units to carry additional inventory from period 1 to period 4 and saves a setup for product A estimated to be 3 units ($S_A = 3$). Therefore the move costs more than it saves and is not selected. Whereas the second move costs 2 and potentially saves 3 units, so this move is made. The schedule is recomputed, and the new schedule is

$$\begin{pmatrix}
3 & 0 & 0 & 2 & 0 \\
0 & 7 & 0 & 0 & 4 \\
2 & 0 & 3 & 0 & 0 \\
0 & 0 & 5 & 0 & 2
\end{pmatrix}$$
The sequence of production and capacity availabilities are

recalculated as before, the sequence is $\begin{pmatrix} C & B & C & A & B \\ A & D & D \end{pmatrix}$ and capacities matrix is (2, 0, -2, 5, -1). No more lots can be moved around to save setup.

Step 4 Overloading can be eliminated in period 5 by moving setup item B to period 4 (equation 72 is satisfied). The sequences and lot sizes remain the same but the new capacity matrix is (2, 0, -2, 4, 0) (using equations 73 and 74). Now the overloading in period 3 has to be eliminated.

Both items C and D have to be considered. First the algorithm considers item C. The estimated setup time is 1 hours ($s_C = 1$). Two options are available.

1. Shift some production to period 1 (equation 87 is satisfied). The number of units to be shifted is determined by equation (88), in this case v = min(2, 3, 2). The cost of

this move per unit overload eliminated is calculated using equation (89). the change in the inventory/backlogging cost is calculated using equations (69, 70 and 71). Plugging in all the numbers into these equations we get $\Delta H = 4$; $z = \frac{\Delta H}{v} = \frac{4}{2} = 2$.

2. Another alternative is to move production into period 4. Equation (83) is satisfied. The entire lot for product C can be moved (3 units). Since, production is shifted forward the feasibility of this move has to be evaluated. Equation (98) is satisfied (t=3, t* = 4, m=3). Therefore, the move is a feasible move. Once again the cost per unit shifted is calculated using equation (84). Plugging in all the numbers, we get $z = \frac{\Delta H}{x_{it}} = \frac{6}{3} = 2.$

The above procedure is repeated for product D. Equation (92) is satisfied by both periods 1 and 4. Let us first consider shifting production to period 1. In this case v can be calculated form equation (93), v = min(2, 1,5) = 1. The cost per unit of infeasibility eliminated is calculated from equation (94), $z = \frac{3+2}{1} = 5$ Now let us consider shifting production to period 4. Once again the feasibility of the move is evaluated. Using equation (93) the size of the lot to be shifted is calculated v = min(2, 3, 5) = 2. The cost of this move per unit of overload eliminated is $z = \frac{\Delta H + S_C}{v} = \frac{4+3}{2} = 3.5$. Obviously the lowest cost option is to move two units of product C from period 3 to period 1 or 3 units from period 3 to period 4. Shifting 2 units to period 1 is selected.

The new schedule is
$$\begin{pmatrix} 3 & 0 & 0 & 2 & 0 \\ 0 & 7 & 0 & 0 & 4 \\ 4 & 0 & 1 & 0 & 0 \\ 0 & 0 & 5 & 0 & 2 \end{pmatrix}$$
 the sequence remains the same and is

$$\begin{pmatrix} C & B & C & A & B \\ A & D & D \end{pmatrix}$$
 the new capacities are $(0, 0, 0, 4, 0)$. Hence the infeasibility

has been eliminated.

Step 5. The quality of the solution cannot be further enhanced as no conditions required for optimality have been violated.

Now the inventory/backlogging matrix for the above schedule is calculated

$$\begin{pmatrix}
0 & 0 & 0 & 0 & 0 \\
0 & 1 & 1 & 0 & 0 \\
2 & 2 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0
\end{pmatrix}$$

The total setup cost is calculated from the over all sequence of production $C \rightarrow A \rightarrow B \rightarrow C \rightarrow D \rightarrow A \rightarrow B \rightarrow D$. The total setup time for this sequence is 8, and the total cost is 24 (8*3). Once again the total inventory/backlogging cost is 6 (from inventory/backlogging matrix). Therefore, total cost of the schedule is 24+6=30.

A Regeneration Algorithm (RA)

Once again
$$S_A = 3$$
; $S_B = 3$; $S_C = 3$; $S_D = 3$ and $S_A = 1$; $S_B = 1$; $S_C = 1$; $S_D = 1$.

Step 1. Solve the single item problem for each item using the regeneration point technique described in chapter III. The algorithm first considers item A with a demand pattern (3 0 0 2 0). The best period for production between any two regeneration points

is calculated using equation (57). For example given a regeneration point at period 0, Table A.8 shows the cost of production in each period for the next regeneration point. The values in Table A.8 are equal to $c_{0k}^{I'}$.

For example, consider the first regeneration point in period 0 and the next regeneration point in period 3. There are three possible periods (1, 2, 3) to produce the lot to meet the cumulative demand in this period (cumulative demand = 3). If lot is produced in period 1, then inventory at the end of this period becomes 0 (production = 3 units and demand = 3 units). This makes period 1 a regeneration point. This is not a feasible solution because it violates that the rule that the next regeneration point following period 0 is period 3. Next consider production in period 2. The setup cost for the period is 3 and the backlogging cost is 6. Therefore the total cost of production in period 2 is 9. Similarly the total cost of production in period 3 is 12 + 3 = 15.

	Period of Production							
Next Regeneration Period	1	2	3	4	5			
1	3	_1	-	_	-			
2	x^2	9	_	-	_			
3	x	9	15		_			
4	9	13	17	X	-			
5	X	х	X	X	X			

^{1 -} indicates periods that are not within regeneration points 0 and the next regeneration point

Table A.8 Cost coefficients for regeneration in period 0

Similar cost coefficients are generated for all other possible regeneration points.

The period that provides the lowest cost period of production between two successive regeneration points is saved. Table A.9 shows the lowest cost between two regeneration

² x indicates infeasible periods as producing in these periods violates regeneration point theorem

points and period of production to achieve this low cost. The cost coefficients shown in Table A.9 are c_{tk} for all combinations of t and k.

	Next regeneration point									
					p	eriod	of pro	ductio	on	
regeneration at point i	1	2	3	4	5	1	2	3	4	5
0	3	9	9	9	X	1	2	2	1	X
1	_ ¹	0	x^2	7	X	-	2	X	2	X
2	-	-	0	5	X	~	-	3	3	X
3	-	-	~	3	7	~	-	-	4	5
4	-	-	-	-	0	~	-	-	-	5

^{1 -} indicates periods that are not within regeneration points considered

Table A.9 Cost coefficients and period of production between all regeneration points

For example consider first regeneration in period 2. Three possibilities exist for the next regeneration period namely, 3, 4 and 5. Let us consider each one in sequence. First consider period 3. Cumulative demand in this period is 0. Therefore, the total cost of production is 0 and the only period in which this 0 production can be scheduled is 3.

Next, consider the second regeneration period 4. The cumulative demand now is 2 (sum of demand in periods 3 and 4). Production of these 2 units can either be scheduled in period 3 or 4. First consider period 3. The total production cost is 5 (3 for setup and 2 for inventory). Now consider production in period 4. The inventory at the end of period 3 in this case is 0. Therefore, production cannot be scheduled in period 4. So the only option is producing 2 units in period 3 at a cost 5, as shown in Table A.9.

Now consider the second regeneration point in period 5. Once again the cumulative demand is 2. If production is scheduled in period 3 then inventory at end of

² x indicates infeasible periods as producing in these periods violates regeneration point theorem

period 4 is 0. Hence, this is not a feasible option. Similarly if production is scheduled in periods 4 or 5 inventory at the end of period 3 is 0, which makes production in these periods infeasible. Therefore, there is no feasible solution possible for a regeneration point in period 2 and the next one in period 5.

Once the lowest costs between two regeneration points have been determined the task is to use dynamic programming to select the best possible pairs of regeneration periods in each period. This is achieved by recursion starting in period 5. The recursion works as follows:

$$f_5 = 0$$

$$f_4 = \min_{4 < k \le 5} (c_{4k} + f_k) = c_{45} + f_5 = 0$$

$$f_3 = \min_{3 < k \le 5} (c_{3k} + f_k) = c_{34} + f_4 = 3$$

$$f_2 = \min_{2 < k \le 5} (c_{2k} + f_k) = c_{23} + f_3 =$$

$$f_1 = \min_{1 < k \le 5} (c_{1k} + f_k) = c_{12} + f_2 = 3$$

$$f_0 = \min_{0 < k \le 5} (c_{0k} + f_k) = c_{01} + f_1 = 6$$

where f_t is the lowest cost of going from that stage t to the regeneration point in period 5. f_t is calculated recursively starting from period 5 using equation (58). For example, consider stage 3. Given a regeneration period in 3 then there are two options to get to stage 5. The first option is to directly have the second regeneration point in period 5 with total cost of 7 ($c_{35} + f_5$). The second option is to have the second regeneration point

in period 4 and then select the best way to go from period 4 to period 5. The total cost of this option is 3 $(c_{34} + f_4)$. Therefore the second option is selected.

Similarly the best path to period 5 is calculated for other periods and is shown above. The optimal regeneration points are selected by starting from period 0 and successively determining the next lowest cost regeneration point. From period 0 the next lowest cost regeneration period is 1, similarly from 1 the next lowest cost regeneration period 2 and so on. The sequence of regeneration points is the optimal sequence.

Therefore the best policy will be to have regeneration points at 0, 1, 2, 3, 4 and 5 i.e. just producing enough in each period to meet demand in that period. Here the lots are scheduled in periods 1 and 4, and the lot sizes are 3 and 2 respectively. The total cost of the schedule is 6. Similarly, the optimal schedules are generated for all products. At the expense of being succinct only the final optimal schedules are presented for the other items. For item B there are two optimal schedules (0, 7, 0, 0, 4) or (0, 6, 0, 0,5). For item C the optimal schedule is (2, 0, 3, 0, 0) and for item D the optimal schedule is (0, 0, 5, 0, 2). Hence at the end of the first step the following schedule can be obtained

$$\begin{pmatrix}
3 & 0 & 0 & 2 & 0 \\
0 & 7 & 0 & 0 & 4 \\
2 & 0 & 3 & 0 & 0 \\
0 & 0 & 5 & 0 & 2
\end{pmatrix}$$

Step 2. The above schedule is exactly same as the one generated at the end of the lot shifting procedure of the LS algorithm. Therefore the infeasibility elimination procedure is similar. Hence only the final solution is provided here. The schedule is

$$\begin{pmatrix} 3 & 0 & 0 & 2 & 0 \\ 0 & 7 & 0 & 0 & 4 \\ 4 & 0 & 1 & 0 & 0 \\ 0 & 0 & 5 & 0 & 2 \end{pmatrix} \text{ and the sequence is } \begin{pmatrix} C & B & C & A & B \\ A & D & D \end{pmatrix} \text{ once again this}$$

approach yields the final schedule cost of 30.

Regeneration Algorithm with "Overload Penalty" (ROP)

Still
$$S_A = 3$$
; $S_B = 3$; $S_C = 3$; $S_D = 3$ and $S_A = 1$; $S_B = 1$; $S_C = 1$; $S_D = 1$. Also we know $S_A = 1$; $S_B = 1$; $S_C = 1$; $S_D = 1$. Also we

Step 1. First the sequence in which the regeneration principle is used to generate optimal solution is determined. The sequence is based on the average cost values (V_i) determined for each product using equation (106). For product A we have

$$_{A} = \frac{\sqrt{2 \times S_{A} \times r_{A}}}{r_{A}} = \frac{\sqrt{2 \times 3 \times 1}}{1} = 2.45 \text{ similarly V}_{B} = 1.65; V_{C} = 2.45; \text{ and V}_{D} = 1.65$$

2.07. The average cost for items C and A are equal. In such cases the algorithm selects the product whose average cost value was first generated. Therefore, the order of scheduling is A, C, D, B.

Step 2. This algorithm is similar to RA algorithm until the 'if condition' in equation (108) is satisfied. Since the "overload penalty" does not come into play for the first two products the final results for these products determined earlier are merely repeated here. The schedule for A is (3, 0, 0, 2, 0) and for C is (2, 0, 3, 0, 0). Next item D is considered for scheduling. Now the 'if condition' in equation (108) is satisfied and "overload penalty" comes into play.

First the capacity requirements in each period is calculated using estimated setup times. For example in period 1 for A and C together we need total production time of 5 (3+2), the total estimated setup time is 2. Therefore total capacity required for A and C in period 1 is 7 (5+2). Similar capacity requirements are calculated in other periods and the capacity requirements in each period is (7, 0, 4, 3, 0). From these values the capacity available in each period can be computed by subtracting capacity requirements from capacity available in each period (8). The capacity availability matrix is (1, 8, 4, 5, 8).

With information on capacity availabilities the optimal regeneration periods can be calculated as before. However, this time around some of the cost coefficients will be modified by incorporation of "overload penalty". The demand sequence for product D is (0, 0, 5, 0, 2). Once again the cost of production in each period for a given pair of regeneration points is determined. However, now the $c_{lk}^{l'}$ values are computed using equation (109) to account for "overload penalty". Table A.10 shows the cost coefficients with the first regeneration point in period 0.

For example consider the next regeneration in period 5. One option is to produce in period 1. Cumulative demand is 7 (5+2). Total capacity required to produce a lot of size 7 is 8 (including an estimated setup time of 1 hour). However, only 1 hour of capacity is available in this period. "Overload penalty" is calculated using equation (109) as 49 (8-1)². Now the cost coefficient in that period is the sum of "overload penalty", setup and inventory cost to carry 5 units from period 1 to period 3. "Overload penalty" is 49, estimated setup cost is 3, and inventory cost is 10 (5x2). The cost

coefficient is 70 (49+3+18). Production in other periods is not feasible because inventory in period 1 is 0 with these options.

		Peri	od of Produ	ction	
Next Regeneration Period	1	2	3	4	5
1	0	_1	-	_	_
2	x^2	X	-	-	-
3	38	X	X	-	-
4	X	X	x	x	-
5	70	X	X	X	X

^{1 -} indicates periods that are not within regeneration points 0 and the next regeneration point

Table A.10 Cost coefficient for regeneration in period 0 with "overload penalty"

Similar cost values are generated for all other possible regeneration points. The period that provides the lowest cost period of production between two successive regeneration points is saved. Table A.11 shows the lowest cost between two regeneration points and period of production to achieve this low cost. The values in Table A.11 is equal to c_{tk} for all combinations of t and k. These computations are similar to one used in RA except for the incorporation of the "overload penalty".

	Next regeneration point									
	lowest cost coefficient				ļ	period of production				
regeneration at point i	1	2	3	4	5	1	2	3	4	5
0	0	Х	38	х	70	1	Х	1	X	1
1	-1	0	8	X	14	-	2	2	X	2
2	-	-	7	14	23	-	-	3	4	3
3	_	-	-	0	5	-	-	-	4	4
4	_	_	_	-	3	-	-	_	-	5

^{1 -} indicates periods that are not within regeneration points considered

Table A.11 Cost coefficients and period of production between all regeneration points

² x indicates infeasible periods as producing in these periods violates regeneration point theorem

² x indicates infeasible periods as producing in these periods violates regeneration point theorem

The recursion would work as follows:

$$f_5 = 0$$

$$f_4 = \min_{4 < k \le 5} (c_{4k} + f_k) = c_{45} + f_5 = 3$$

$$f_3 = \min_{3 < k \le 5} (c_{3k} + f_k) = c_{34} + f_4 =$$

$$f_2 = \min_{2 < k \le 5} (c_{2k} + f_k) = c_{23} + f_3 = 10$$

$$f_1 = \min_{1 < k \le 5} (c_{1k} + f_k) = c_{12} + f_2 = 10$$

$$f_0 = \min_{0 < k \le 5} (c_{0k} + f_k) = c_{01} + f_1 = 10$$

The optimal solution is to have regeneration points at (0, 1, 2, 3, 4, 5). Once again the solution is to produce only in periods in which demand exists i.e., produce 5 units in period 3 and 2 units in period 5. The schedule is (0, 0, 5, 0, 2). Now item B is scheduled, taking into account the schedules of previous three items. Once again the regeneration points are determined using procedure described above. The schedule for item B is (0, 6, 0, 0, 5).

Step 3. The combined schedule of the four items are $\begin{pmatrix} 3 & 0 & 0 & 2 & 0 \\ 0 & 6 & 0 & 0 & 5 \\ 2 & 0 & 3 & 0 & 0 \\ 0 & 0 & 5 & 0 & 2 \end{pmatrix}$. The optimal

sequence is
$$\begin{pmatrix} C & B & C & A & D \\ A & D & B \end{pmatrix}$$
 with capacities (2, 1, -2, 5, -2).

Step 4. The overloading in period 5 can be overcome by moving the setup for the switch between product A in period 4 and product D in period 5 to period 4. The new

capacities are (2, 1, -2, 3, 0). Overloading in period 3 can be eliminated using methods described earlier. Here only the final solution is provided. The final schedule is

$$\begin{pmatrix} 3 & 0 & 0 & 2 & 0 \\ 0 & 7 & 0 & 0 & 4 \\ 4 & 0 & 1 & 0 & 0 \\ 0 & 0 & 5 & 0 & 2 \end{pmatrix}$$
 with sequence shown as
$$\begin{pmatrix} C & B & C & A & D \\ A & D & B \end{pmatrix}$$
, and the total

cost is 30.

APPENDIX B DEMAND AND SETUP DATA SETS

Table B.1 Demand data set 1: Small problem size, smooth demand, low utilization

Period										
Product	1	2	3	4	5	6	7	8	9	10
1	2	2	1	4	2	1	1	2	3	1
2	3	3	3	1	3	1	4	2	2	2
3	l	2	2	2	1	2	2	2	.3	Ì
4	1	1	2	3	1	3	1	1	1	3
5	2	2	2	1	3	3	2	3	ì	2
6	3	2	2	1	2	2	2	2	2	3
-	Ū	_	_	•	_	_	_	_	_	
1	2	2	2	2	2	4	4	2	2	2
2	2	2	1	2	2	3	2	ı	2	2
3	2	2	2	2	3	1	1	2	2	2
4	2	2	2	3	2	2	1	1	3	2
5	2	2	2	2	1	1	2	3	2	2
6	2	2	3	1	2	1	2	3	1	2
1	4	1	1	2	2	3	2	3	2	2
2	1	1	2	1	2	4	3	2	2	2 3
3	2	2	2	2	2	i	2	2	2	1
4	1	2	3	1	3	l	2	2	2	3
5	2	3	1	5	2	i	2	2	3	2
6	2	3	3	i	l	2	ì	l	i	1
Ü	_	5	5	•	•	~	•	•	•	-
1	2	2	3	l	1	1	l	2	3	1
2	1	3	3	2	2	2	3	1	2	3
3	2	1	1	2	2	2	1	2	3	4
4	4	3	1	3	2	2	2	2	1	1
5	2	2	2	1	3	-	2	3	ì	2
6	l	Ī	2	3	2	4	3	2	2	1
1	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2
3	2	2	2	2	2	2	2	2	2	
4	2	2	2	2	2	2	2	2	2	2 2
5	2	2	2	2	2	2	2	2	2	2
6	2	2	2	2	2	2	2	2	2	2
1	1	2	1	2	1	3	2	1	2	3
2		1	2	4		2	2	2	3	1
3	2 2 3	2	3 2	1	2 2	1	2	2	1	2
3 4	3	2 3	2	2	1	1	2	2	1	2 1
5	2	1	2	1	4	2		2	3	2
6	2	3	2	2	2	3	2 3	2 2 2 3	2	2 3
•	, -	•	-		-					
1	2	1	1	1	3	2	2	3	2	2
	2 2 5		3	3	1	3	2	2	2	2
3	5	2	1	3 2	2	1	1	2	2	1
2 3 4	1	3	3	3	2	1		2 2 1	1	2
5	1	2 2 3 3	1	2	2	3	3	2		3
5 6	1	1	3	1	2 2	3 2	2 3 2	2 2	2 3	2 2 1 2 3 2
,	-	-	-	-	-	_	_	_	-	

Table B.1 (Continued)

Product 1 2 3 4 5 6 7 8 9 10 1 4 3 3 2 3 2 2 1 3 2 2 2 2 1 2 1 2 2 3 1 2 3 2 2 2 1 2 2 2 1 3 2 4 1 1 2 3 1 2 3 3 2 1 5 2 2 2 2 2 1 2 1 3 3 2 1 3 2 2 2 2 1 3 2<	`	ŕ			F	eriod					
2 2 2 1 2 1 2 2 3 1 2 3 2 2 2 1 2 2 2 1 3 2 4 1 1 2 3 1 2 3 3 2 1 5 2 2 2 2 2 1 2 1 1 3 6 1 2 2 2 2 1 2 1 1 3 3 2 2 2 1 3 3 2 2 2 2 1 2 <td< td=""><td>Product</td><td>11</td><td>2</td><td>3</td><td>4</td><td>_ 5</td><td>6</td><td>7</td><td>8</td><td>9</td><td>10</td></td<>	Product	11	2	3	4	_ 5	6	7	8	9	10
3 2 2 2 1 2 2 2 1 3 2 4 1 1 2 3 1 2 3 3 2 1 5 2 2 2 2 2 1 2 1 1 3 6 1 2 2 2 2 1 2 1 1 3 2 2 2 1 3 3 2 2 2 2 1 2	1	4	3	3	2	3	2	2	1	3	2
4 1 1 2 3 1 2 3 3 2 1 5 2 2 2 2 2 1 2 1 1 3 6 1 2 2 2 2 1 2 1 1 3 2 2 2 1 3 3 2 2 2 2 1 2 2 2 2 1 2	2	2	2	1	2	1	2	2	3	1	2
5 2 2 2 2 2 1 2 1 1 3 6 1 2 2 2 2 2 1 2 2 2 1 3 3 2 2 2 2 1 2 2 2 2 1 2 2 2 2 2 2 2 2 2 1 2	3	2	2	2	1	2	2	2	1	3	2
6 1 2 2 2 3 3 1 3 2 2 1 3 3 2 2 2 2 1 2 2 2 2 1 2 2 2 3 3 2 2 2 2 3 2 2 3 3 4 2 2 2 3 2 2 2 4 3 1 1 2 1 1 3 2 2 2 2 2 5 1 2 3 1 2 2 2 1 2 <td< td=""><td>4</td><td>1</td><td>1</td><td>2</td><td>3</td><td>1</td><td>2</td><td>3</td><td>3</td><td>2</td><td>i</td></td<>	4	1	1	2	3	1	2	3	3	2	i
1 3 3 2 2 2 2 1 2 2 2 2 1 2 2 2 3 3 2 2 2 2 3 2 2 3 3 4 2 2 2 3 2 2 2 4 3 1 1 2 1 1 3 2 2 2 2 5 1 2 3 1 2 2 2 1 2 3 1 3	5	2	2	2	2	2	1	2	1	i	3
2 1 2 2 2 3 3 2 2 2 2 2 3 2 2 3 3 4 2 2 2 3 2 2 2 4 3 1 1 2 1 1 3 2 2 2 2 5 1 2 3 1 2 2 2 1 2 3 1 3 3 1 3 2 2 3 3 2 2 3 3 </td <td>6</td> <td>1</td> <td>2</td> <td>2</td> <td>2</td> <td>3</td> <td>3</td> <td>l</td> <td>3</td> <td>2</td> <td>2</td>	6	1	2	2	2	3	3	l	3	2	2
2 1 2 2 2 3 3 2 2 2 2 2 3 2 2 3 3 4 2 2 2 3 2 2 2 4 3 1 1 2 1 1 3 2 2 2 2 5 1 2 3 1 2 2 2 1 2 3 1 3 3 1 3 2 2 3 3 2 2 3 3 </td <td></td>											
3 2 3 3 4 2 2 2 3 2 2 4 3 1 1 2 1 1 3 2 2 2 5 1 2 3 1 2 2 2 1 2 2 6 2 1 1 1 2 2 2 2 2 2 2 1 3 1 2 2 2 3 1 1 1 3 3 1 3 1 3 2 3 3 1 3 2 3 3 2 3	1	3	3	2	2	2	2	l	2	2	2
4 3 1 1 2 1 1 3 2 2 2 2 5 1 2 3 1 2 2 2 1 2 2 6 2 1 1 1 2 2 2 2 2 2 2 1 3 1 2 2 2 3 1 1 1 3 3 1 2 2 3 2 2 1 1 2 1 3 1 3 1 3 2 4 3 3 1 1 1 3 2 2 3 2 2 3 2 2 3 2 2 3 2 2 3 2 3 2 2 3 2 2 3 2 3 2 2 3 2 3 2 3 2 3 2 3 2 2 3 2 3 2 3 <td< td=""><td>2</td><td>1</td><td>2</td><td>2</td><td>2</td><td>3</td><td>3</td><td>2</td><td>2</td><td>2</td><td>2</td></td<>	2	1	2	2	2	3	3	2	2	2	2
5 1 2 3 1 2 2 2 1 2 2 6 2 1 1 1 2 2 2 2 2 2 1 3 1 2 2 2 3 1 1 1 3 2 2 3 2 2 1 1 2 1 3 1 3 1 2 2 3 3 1 2 1 3 2 4 3 3 1 1 1 3 2 2 3 2 5 1 1 3 3 2 2 4 4 1 2	3	2	3	3	4	2	2	2	3	2	2
6 2 1 1 1 2 2 2 2 2 2 1 3 1 2 2 2 3 1 1 1 3 2 2 3 2 2 1 1 2 1 3 1 3 1 2 2 3 3 1 2 1 3 2 4 3 3 1 1 1 3 2 2 3 2 5 1 1 3 3 2 2 4 4 1 2	4	3	1	l	2	1	1	3	2	2	2
1 3 1 2 2 2 3 1 1 1 3 2 2 3 2 2 1 1 2 1 3 1 3 1 2 2 3 3 1 2 1 3 2 4 3 3 1 1 1 3 2 2 3 2 5 1 1 3 3 2 2 4 4 1 2	5	1	2	3	1	2	2	2]	2	2
2 2 3 2 2 1 1 2 1 3 1 3 1 2 2 3 3 1 2 1 3 2 4 3 3 1 1 1 3 2 2 3 2 5 1 1 3 3 2 2 4 4 1 2	6	2	1	1	1	2	2	2	2	2	2
2 2 3 2 2 1 1 2 1 3 1 3 1 2 2 3 3 1 2 1 3 2 4 3 3 1 1 1 3 2 2 3 2 5 1 1 3 3 2 2 4 4 1 2											
3 1 2 2 3 3 1 2 1 3 2 4 3 3 1 1 1 3 2 2 3 2 5 1 1 3 3 2 2 4 4 1 2	1	3	1	2	2	2	3	1	1	1	3
4 3 3 1 1 1 3 2 2 3 2 5 1 1 3 3 2 2 4 4 1 2	2	2	3	2	2	1	l	2	1	3	1
5 1 1 3 3 2 2 4 4 1 2	3]	2	2	3	3	1	2	}	3	2
	4	3	3	1	l	1	3	2	2	3	2
6 2 2 2 1 3 2 1 3 1 2	5	i	1	3	3	2	2	4	4	1	2
	6	2	2	2	1	3	2	1	3	1	2

Table B.2 Demand data set 2: Small problem size, smooth demand, high utilization

				F	eriod					
Product	1	2	3	4	5	_6	7	8	9	10
1	3	3	3	3	4	5	3	3	2	4
2	4	2	4	3	1	2	4	3	4	2
3	1	3	4	4	4	4	3	.3	.3	4
4	3	4	1	2	3	3	3	3	2	2
5	4	4	3	3	2	2	3	3	3	4
6	3	2	3	3	4	2	2	3	4	2
1	2	3	2	4	2	4	3	2	4	3
2	3	3	2	4	2	3	4	3	4	2
3	4	3	3	3	5	2	4	4	2	2
4	2	4	4	2	3	2	3	4	3	3
5	4	2	4	3	3	3	2	3	3	5
6	3	3	3	2	3	4	2	2	2	3
1	4	4	4	2	2	l	4	4	2	4
2	2	3	4	2	2	4	2	3	4	2
3	2	3	2	3	2	4	3	4	4	4
4	2	3	3	5	4	4	3	3	2	3
5	3	2	3	3	4	2	3	3	2	3
6	5	3	2	3	4	3	3	1	4	2

Table B.2 (Continued)

Product 1 2 3 4 5 6 7 8 9 10 1 3 4 2 4 2 3 2 3 4 2 4 2 3 2 2 4 3 2 4 3 2 4 3 3 3 4 4 4 3 2 4 3 3 4 4 4 4 3 3 2 4 3 3 3 4 4 4 4 3 3 2 4 3 3 3 4 2 2 4 4 3 3 3 2 2 4 4 3 3 3 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4<	14010 = 12 (0	jonnina ca)	,		Ī	Period					
2	Product	1	2				6	7	8	9	10
3 2 3 3 3 4 4 3 2 4 3 3 3 4 4 4 3 3 3 4 3 3 3 4 3 3 2 3 3 3 4 3 3 2 2 3 4 4 4 4 4 4 4 2 2 2 4 4 2 2 2 4 4 2 2 2 4 4 3 3 3 4 1 1 4 4 4 2 2 2 4 4 4 2 2 2 4 4 4 2 2 2 4 4 4 2 2 2 4 4 4 3 3 4 4 4					4						
4 2 4 2 5 2 4 4 4 3 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 2 4 4 2 2 2 4 4 2 2 3 3 3 4 4 3 3 3 4 4 4 2 2 3 3 3 3 3 3 3	2										2
5 3 2 3 2 3 2 3 3 4 3 3 4 3 3 4 3 3 4 4 4 4 4 4 4 4 4 4 4 2 1 2 4 2 2 2 4 4 2 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 2 2 4 4 1 1 4 5 4 2 2 2 4 4 2 2 3 3 3 4 4 4 2 2 3 3 3 4 4 4 4 4 4 4 3 3 3 4 4 4 4 3 3 3		2									
6 4 2 4 2 3 2 3 2 3 3 1 3 4 4 4 4 3 3 2 2 4 2 4 3 3 3 3 3 4 2 2 4 3 2 2 2 4 4 3 3 3 4 2 4 2 2 4 4 2 5 4 4 1 1 5 4 2 2 2 4 4 3 3 3 4 1 1 4 5 4 2 2 2 4 4 4 2 2 3 2 2 2 4											
1 3 4 4 4 4 3 3 2 2 4 2 4 3 4 2 1 2 4 2 2 4 3 2 2 2 4 3 3 3 3 4 2 4 2 4 4 2 2 4 4 3 4 1 5 4 2 2 2 4 4 3 4 1 6 3 3 2 4 4 2 2 3 2 3 1 4 5 4 2 3 2 2 4 4 2 2 3 2 3 2 3 2 3 2 4 3 3 <											
2 4 3 4 2 1 2 4 2 2 2 4 3 2 2 2 4 4 2 2 4 4 2 2 4 4 2 5 4 1 1 4 5 4 2 2 2 4 4 2 5 4 4 2 2 3 2 3 2 3 2 3 2 3 3 2 3 3 2 3 4 4 2 2 2 4 4 2 2 3 3 2 3 3 3 3 3 3 4	6	4	2	4	2	3	2	3	2	3	.3
2 4 3 4 2 1 2 4 2 2 2 4 3 2 2 2 4 4 2 2 4 4 2 2 4 4 2 5 4 1 1 4 5 4 2 2 2 4 4 2 5 4 4 2 2 3 2 3 2 3 2 3 2 3 3 2 3 3 2 3 4 4 2 2 2 4 4 2 2 3 3 2 3 3 3 3 3 3 4	1	2	4	4	4	4	2	2	2	2	1
3 2 2 2 4 3 3 3 3 4 2 1 4 2 2 4 4 2 2 4 4 1 1 4 1 1 4 4 2 2 2 4 4 2 2 3 2 3 2 3 2 2 2 4 4 2 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 3 3 4 <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>											
4 2 4 4 2 2 4 4 3 4 1 5 4 2 2 2 4 4 2 5 5 4 4 6 3 3 2 4 4 2 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 3 2 4 4 2 2 2 4 4 2 2 2 4 4 2 2 3 3 3 4 3 <td></td>											
5 4 2 2 2 4 4 2 5 4 4 6 3 3 2 4 4 2 2 3 2 3 1 4 5 4 2 3 2 2 2 4 2 2 2 3 3 3 4 2 2 2 4 4 4 2 2 3 </td <td></td>											
6 3 3 2 4 4 2 2 3 2 3 1 4 5 4 2 3 2 2 2 4 4 2 2 2 3 3 4 3 3 3 4 2 3 <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>											
1 4 5 4 2 3 2 2 2 4 2 2 2 2 3 3 4 3											
2 2 3 3 4 3 3 3 4 4 4 4 4 4 4 4 4 4 4 2 3	· ·	J	,	_	•	•	_	-	2	_	5
2 2 3 3 4 3 3 3 4 4 4 4 4 4 4 4 4 4 4 2 3	1	4	5	4	2	3	2	2	2	4	2
3 3 2 3 4 2 4 3 3 2 4 4 4 4 2 3 3 3 4 3 3 3 1 5 3 2 3 2 3 4 4 3 <td>2</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>4</td> <td></td>	2									4	
5 3 2 3 2 3 4 4 3	3	3	2	3	4	2	4		3	2	4
6 2 2 3 3 4 2 2 3 2 4 1 3 <td< td=""><td></td><td></td><td>4</td><td></td><td>3</td><td>3</td><td>3</td><td>4</td><td>3</td><td>3</td><td>l</td></td<>			4		3	3	3	4	3	3	l
1 3			2		2						
2 3	6	2	2	3	3	4	2	2	3	2	4
2 3											
3 4 1 1 2 2 2 3 4 4 4 3 3 3 3											
4 3 4 1 1 2 2 3 4 1 1 2 2 3 4 4 4 3 3 3 3 4 4 4 3 3 3 4 4 4 2 3 3											
5 3 4 1 1 2 2 2 2 3 4 4 1 2 2 3 4 4 4 3 3 3 4 4 4 3 3 3 4 4 4 3 3 3 4 4 4 3 3 3 4 4 4 2 3 4 4 4 2 3 4 4 4 2 3											
6 3 4 1 1 2 2 2 3 4 1 3 3 2 2 2 3 4 4 3 3 3 2 3 4 4 4 3 3 3 3 3 4 4 4 3 3 3 3 4 4 4 3 3 3 3 4 4 4 3 3 3 4 4 4 3 3 3 4 4 4 2 3 4 4 4 2 3 4 4 4 2 3 4 4 2 3 4 4 2 3 3 4 4 2 3											
1 4 2 2 4 2 2 4 5 4 1 2 2 3 3 1 3 2 2 2 2 3 4 3 4 3 4 4 4 3 3 2 3 4 4 3 3 2 4 3 4 4 4 3 3 5 2 3 4 3 4 2 2 2 4 3 6 3 4 3 3 2 4 3 2 2 2 4 3 6 3 4 3 3 2 2 4 3 2 2 2 4 3 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 <											
2 2 3 3 1 3 2 2 2 3 4 3 4 3 4 3 4 4 3 3 2 3 4 3 3 2 4 3 4 4 4 4 3 3 5 2 3 4 3 4 2 2 2 4 3 6 3 4 3 3 2 4 3 2 2 4 1 4 4 2 3 2 3 3 3 4 4 2 2 3 2 2 3 4 4 2 3 4 2 2 3 2 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 3 4 4 2 3 3 1 4	U	3	3	3	3	3	3	3	3	3	3
2 2 3 3 1 3 2 2 2 3 4 3 4 3 4 3 4 4 3 3 2 3 4 3 3 2 4 3 4 4 4 4 3 3 5 2 3 4 3 4 2 2 2 4 3 6 3 4 3 3 2 4 3 2 2 4 1 4 4 2 3 2 3 3 3 4 4 2 2 3 2 2 3 4 4 2 3 4 2 2 3 2 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 3 4 4 2 3 3 1 4	1	4	2	2	4	2	2	4	5	4	1
3 4 3 4 4 3 3 2 3 4 3 3 2 4 3 4 4 4 4 3 3 5 2 3 4 3 4 2 2 2 4 3 3 6 3 4 3 3 2 4 3 2 2 4 3 1 4 4 2 3 2 3 3 3 4 4 4 2 3 4 4 4 2 3 4 4 4 2 3 4 4 4 2 3 4 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 4 4 2 3 3 4 4 2 3 3 4 4 2 3 3 4 4 2 3 3 4 4 3 1			3			3					
4 3 3 2 4 3 4 4 4 4 3 3 5 2 3 4 3 4 2 2 2 4 3 6 3 4 3 3 2 4 3 2 2 4 1 4 4 2 3 2 3 3 3 4 4 2 2 3 2 2 3 4 4 2 3 4 3 3 2 3 3 4 4 2 3 4 3 3 3 4 4 2 3 2 3 4 4 3 3 4 3 2 2 4 2 5 3 4 3 3 3 3 4 4 3 1 6 3 2 4 4 2 3 3 4 2 4 1											
5 2 3 4 3 4 2 2 2 4 3 6 3 4 3 3 2 4 3 2 2 4 1 4 4 2 3 2 3 3 4 4 2 2 3 2 2 3 4 4 2 3 4 3 3 2 3 3 4 4 2 3 4 3 3 3 4 3 4 2 2 3 4 2 3 4 2 3 4 2 3 4 2 3 3 4 4 2 3 3 1 4 2 4 2 3 3 4 4 3 1 4 4 3 1 4 4 3 1 4 4 3 1 4 4 2 4 4 2 4 4 2 4 <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></td<>											
6 3 4 3 3 2 4 3 2 2 4 1 4 4 2 3 2 3 3 3 4 4 2 2 3 2 2 3 4 4 2 3 4 3 3 2 3 3 4 2 2 3 2 3 4 3 3 4 3 2 2 4 2 2 3 2 3 4 2 3 3 4 2 2 3 4 2 2 3 4 2 2 4 2 3 3 1 4 2 3 3 4 4 3 1 2 4 4 2 3 3 3 3 3 3 3 3 3 4 2 4 2 <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td>4</td><td></td></td<>										4	
2 2 3 2 2 3 4 4 2 3 4 3 3 2 3 3 4 2 2 3 2 3 4 3 3 3 4 3 2 2 4 2 5 3 4 3 3 3 3 4 4 3 1 6 3 2 4 4 2 3 3 4 2 4 1 2 4 3 3 3 3 2 4 2 2 2 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 4 3 2 2 2 4 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 2 3 4 4 3	6			3						2	4
2 2 3 2 2 3 4 4 2 3 4 3 3 2 3 3 4 2 2 3 2 3 4 3 3 3 4 3 2 2 4 2 5 3 4 3 3 3 3 4 4 3 1 6 3 2 4 4 2 3 3 4 2 4 1 2 4 3 3 3 3 2 4 2 2 2 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 4 3 2 2 2 4 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 2 3 4 4 3											
3 3 2 3 3 4 2 2 3 2 3 4 3 3 4 3 2 2 4 2 5 3 4 3 3 3 3 4 4 3 1 6 3 2 4 4 2 3 3 4 2 4 1 2 4 3 3 3 3 2 4 2 2 2 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 4 3 2 2 2 4 3 4 2 3 4 4 3 2 2 2 4 3 4 2 3 4 4 3 2 2 2 4 3 4 2 3 4 4 3 3 3 3 3		4	4		3	2				4	
5 3 4 3 3 3 4 4 3 1 6 3 2 4 4 2 3 3 4 2 4 1 2 4 3 3 3 3 2 4 2 2 2 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 4 3 2 2 4 3 4 2 3 2 2 2 4 3 3			•	_	_				_	-	•
5 3 4 3 3 3 4 4 3 1 6 3 2 4 4 2 3 3 4 2 4 1 2 4 3 3 3 3 2 4 2 2 2 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 4 3 2 2 4 3 4 2 3 2 2 2 4 3 3	3	3	2	3	3		2	2	3		3
6 3 2 4 4 2 3 3 4 2 4 1 2 4 3 3 3 3 2 4 2 2 2 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 4 3 2 2 4 3 4 2 3 2 2 2 4 3 3	4	3	3		3		3	2	2	4	2
1 2 4 3 3 3 3 3 2 4 2 2 2 3 4 2 3 5 3 4 4 3 3 2 2 2 4 3 4 4 3 2 2 4 3 4 2 3 2 2 2 4 3 3	5	3		3		3	3	4	4	3	
3 2 2 2 4 3 4 4 3 2 2 4 3 4 2 3 2 2 4 3 3	6	3	2	4	4	2	3	3	4	2	4
3 2 2 2 4 3 4 4 3 2 2 4 3 4 2 3 2 2 4 3 3	1	2	t	2	7	2	2	7	2	,	7
3 2 2 2 4 3 4 4 3 2 2 4 3 4 2 3 2 2 4 3 3		2	+ 2		j n	5	.5 =	.š ?	2		<u>۔</u> ع
4 3 4 2 3 2 2 4 3 3	2	2	2		2 4	ک 2			-1	7	.ı 7
5 4 3 4 3 3 2 3 3 3	3 A	3	2 A	2		ა ე	+ 2		J.	<u>د</u> ع	3
	5		3	4	3	<u>د</u> ع	2	3	3	3	., 4
6 5 2 3 3 4 2 3 2 2 4	6	5	3 2	4 3	3	4	2	3	2	3 2	4 4

Table B.3 Demand data set 3: Small problem size, lumpy demand, low utilization

				P	eriod				······································	
Product	l	2	3	4	5	6	7	8	9	10
1	5	6	0	0	0	2	0	0	0	4
2	4	0	0	4	0	2	0	0	0	2
3	0	0	0	0	0	4	5	12	0	4
4	3	6	0	0	0	3	0	0	0	2
5	0	0	0	4	6	1	0	0	12	()
6	0	0	12	4	6	0	7	()	0	()
1	0	2	0	0	0	0	2	()	12	6
2	0	4	5	5	6	0	0	0	0	0
3	0	3	3	0	4	0	0	0	0	6
4	8	0	4	4	0	0	0	12	0	0
5	4	0	0	0	2	3	3	0	0	0
6	0	3	0	3	0	9	7	0	0	0
	•		10	0	0	•		•	•	0
1	0	4	12	0	0	0	4	0	3	0
2	6	0	0	12	0	4	0	3	2	0
3	0	0	0	0	0	4	4	0	2	2
4	0	0	0	0	0	4	4	()	3	
5	0	5	0	0	12	0	0	0	2	+
6	6	3	0	0	0	O	0	9	0	3
1	0	4	6	0	0	0	0	4	3	O
2	6	0	6	7	2	0	0	0	0	0
3	0	0	0	5	0	12	4	0	2	0
4	6	0	0	0	4	0	0	4	4	0
5	0	4	0	0	3	0	8	0	0	12
6	0	4	0	0	3	0	0	4	3	0
Ü	O	7	O	Ū	2	O	O	•		
1	0	8	4	6	6	0	0	()	()	0
2	0	4	Ö	0	Ö	12	0	7	3	()
3	3	0	4	3	0	0	()	()	0	8
4	0	0	4	0	6	0	9	O	1	0
5	5	0	0	3	0	0	3	0	4	0
6	4	0	0	0	0	0	0	5	4	4
1	4	3	0	0	0	0	0	0	5	3
2	4	0	0	0	0	1	12	6	0	O
3	4	6	0	0	0	4	0	0	0	5
4	0	3	0	6	6	0	0	0	4	0
5 6	0	0	12	0	6	4	0	0	3	0
6	0	0	0	6	0	3	0	6	0	4
1	3	4	0	0	0	U	0	4	()	2
2 3 4	2	0	0	4	6	7	0	0	O	()
3	0	0	7	5	6	5	0	0	0	()
4	4	5	0	0	0	0	0	2	0	2 4
5 6	3	0	5	0	0	0	12	0	12	4
6	0	3	0	3	0	0	0	6	0	4

Table B.3 (Continued)

`				P	eriod					
Product	1	2_	3	4	5	6	7	8	9	10
1	0	12	0	0	2	0	3	5	0	0
2	0	0	3	0	0	4	2	0	0	2
3	0	0	5	0	3	4	0	0	0	4
4	0	0	2	0	2	0	1	0	0	4
5	12	0	2	12	5	0	2	0	0	2
6	0	0	0	0	0	4	4	7	12	0
1	3	0	0	0	0	0	5	4	0	4
2	0	2	4	0	4	12	0	()	0	()
3	0	10	2	0	0	0	0	5	5	()
4	3	0	0	12	0	0	4	O	4	8
5	3	0	0	0	4	0	0	3	3	()
6	3	0	6	0	4	0	3	()	()	()
_										
1	0	0	2	0	0	6	1	0	0	5
2	0	0	2	0	8	0	3	0	7	0
3	0	0	0	12	0	0	l	5	5	0
4	12	0	4	0	4	0	4	0	0	0
5	0	12	0	0	0	0	1	3	0	7
6	0	0	4	0	0	6	2	4	()	0

Table B.4 Demand data set 4: Small problem size, lumpy demand, high utilization

				P	eriod					
Product	1	2	3	4	5	6	7	8	9	10
l	8	7	0	0	0	3	0	0	0	6
2	6	0	0	6	0	4	0	0	0	3
3	0	0	0	0	0	5	11	18	0	6
4	4	11	0	0	0	4	0	0	0	3
5	0	0	0	5	7	2	0	0	18	0
6	0	0	18	7	11	0	7	()	()	()
1	0	0	6	8	0	()	5	4	()	()
2	9	0	0	0	7	0	()	2	()	5
3	0	10	12	0	11	0	()	4	()	()
4	9	0	0	0	0	0	6	()	4	7
5	0	0	0	10	0	0	7	8	5	0
6	0	8	0	0	0	18	0	0	9	6
1	9	3	0	0	0	0	0	0	5	9
2	0	8	13	0	3	0	0	0	6	0
3	0	4	5	0	4	0	0	0	7	()
4	0	0	0	18	5	8	0	10	0	()
5	9	0	0	0	6	0	12	8	()	0
6	0	3	0	0	0	10	6	U	()	9

Table B.4 (Continued)

				F	eriod	(icti)				
Product	1	2	3	4	5	6	7	8	9	10
1	7	0	0	0	0	3	0	0	5	7
2	0	9	18	0	0	0	0	5	0	5
3	8	0	0	0	8	0	18	0	6	0
4	0	9	0	0	0	4	0	3	3	0
5	0	0	0	0	10	6	0	10	0	6
6	3	0	0	18	0	5	0	0	4	0
1	0	0	0	0	18	0	7	5	0	3
2	9	18	0	Õ	0	0	0	3	3	3
3	0	0	6	0	0	Ü	7	4	()	7
4	0	0	6	0	0	8	4	6	O	0
5	0	0	0	12	0	10	0	0	8	5
6	9	0	6	6	0	0	0	0	7	0
1	6	3	0	8	0	0	0	0	0	5
2	7	3	0	0	0	10	0	8	0	0
3	0	6	4	0	4	0	0	0	0	3
4	0	0	8	0	5	0	0	10	0	4
5	0	6	6	0	5 5	0	0	0	18	6
6	5	0	0	10	4	8	18	0	0	0
O .	3	U	U	10	4	O	10	O	,	· ·
1	0	0	0	0	7	6	5	()	9	()
2	0	2	0	4	0	0	0	18	9	0
3	0	7	13	5	0	0	7	0	0	0
4	0	6	0	0	4	6	0	0	0	13
5	0	0	0	0	7	6	6	0	0	5
6	18	3	5	9	0	0	0	0	0	0
1	6	0	0	0	18	3	0	0	0	5
2	0	6	18	0	0	5	7	0	0	0
3	3	5	0	6	0	0	0	0	0	4
4	0	7	0	5	0	3	0	0	0	6
5	2	0	0	0	0	7	6	18	()	3
6	7	0	0	7	0	0	5	()	18	()
1	0	4	6	4	0	0	18	0	0	()
2	12	3	ő	Ö	0	ő	0	7	6	0
3	0	5	0	4	18	9	ő	Ů	Ű	0
4	0	6	ő	3	0	ó	ő	6	4	0
5	0	0	ő	3	0	9	0	Ö	8	18
6	6	0	12	4	ő	ó	0	5	Ű	0
1	9	4	0	7	0	0	3	0	()	0
2	0	0	6	0	8	0	7	()	18	()
3	0	0	8	5	10	()	8	()	()	()
4	9	7	0	2	O	()	O	6	()	0
5	0	3	4	0	0	18	0	0	U	12
6	0	4	0	4	0	0	0_	12	0	6

Table B.5 Demand data set 5: Large problem size, smooth demand, low utilization

_																															
	30	1	0	0	-	0	0	_	7	7	7	0	7	0	0	_	0	0		0	0	7	-	7	0	7	_	0	0	7	_
	29	_	_	_	_	0	7	0	0	0	0		_	0	7	7	0	0	7	_	7	-	С	=	7		=	_		-	
	28	_	0	0	_	7	7	0	0	_	7	0	_	0	0	7	0	_	0	7	0	0	_	0	_	7	7	~	0	С	_
	27	7	0	7	_	0	0	7	7	0	_	_	0	0	С	_	_	С	0	_	0	_	0	0	_	7	0	-	_	C1	~
	56	0	0	_	_	-	7	_	0	0	_	0	7	7	_	0	0	7	_	0	-	0	_	_	0	7	¢	С	~	_	_
	25		0	0		0	7	7	_	_	_	0	0	0	7	_	0	_	7	0	0		_	0	7	~	_	_	=	7	0
	54	0	0	_	0	0	-	_	7	_	_	0	0	_	7	7		0		_	7	_	0	_	_	7	0	0	0	0	7
	23	-	0	0	_	0	_	_	0	_	7	_	_	_	0	7	_	-	0	7	0		0	-	7	С	0	7	0	_	_
	22	7	0	_	_	0	0	_	7	_	0	_	0	c	_	7	0	C	7	7	0	=	_	7	=	-	_	=	_	_	_
	21	7	0	0	0	-	7	0	7	_		_	0	0	_	_	7	0	_	0	0	0	7	~	_		-	0	7	С	0
	20	-	7	0	_	_	0	_	0	0	_	_	_	_		_	7	0	0	0	7	7	0	0	7	0	_	7	0	0	_
	19	_	0	7	-	-	0	0	_	7	0	_	7	0	_	0	0	_	7	0	-	_	7	7	_	-	0	_	0	C	=
	18	_	_	~	7	0	0	_	0	7	0	0	_	_	0	_	0	_	0	_	0	_	0	_	_	_	0	_	_	7	~
	17	-	0	_		_	_	7	7	0	0	0	0	0	7	_		0	_	7	_	0	0	_		0		_	_	_	_
	16	0	_	_	7	-	0	_	0	0	_	_		0	_	7		7	0	0	0	0	_	7	_	7	С	0		~1	=
po	15	7	0	_	_	-	0	_	0	7	_	_	_	0	0	_	7	0	0	\sim 1		С	-	_	0	_	=	С		C1	
Period	14	-	0	7	0	_	7	7	7	0	_	0	0	0	0	_	0	0	~	7	0	0		0	=		С		_	C 1	7
	13	7	0	_	7	0	7	_	0	С		_	_	0	С	_	0	0	c	7	_	0	_	=	_	7	_	С	C1	=	~ 1
	12		_	0	0	0	_	7		7	0	_	_		_	0	_	7	С	C	0	c	c	C 1	0		~1	C	C1	_	_
	11	7	7	0	0	7	0	7	7	0	0	7	0	0	0	0	0	_	_	_	0	7	7	_	0	0	_	7	_	0	0
	10	7	0	0	0	_	0	7	_	_	_	_	_	0	_	-	7	7	0		0	_	0	0	_	0	0	0	7		7
	6	_	0	_	0	_	_	_	7	_	_	_	0	0	0	7	_	0	0	~	0			=	7	æ		-	7	=	
	8	0	0	7	_	-	0	_	0	0	7	_	7	7	С	0	0	-	_	_	_	=		_	_	~	_		_		=
	7	_		0	0	-	7	_	7	0	0	0	_	_	_	_	_	_	0	7	7	_	_	_			0	0	0	-	0
	9	_	0	0	7	0	_	7	0	7	0	7	0	0		_	_	0	_	С	_	7		С	0	7	_		_		=
	Ş	0	0	0	_	7	_	0	0	7	0	_	7	0	7	_	0	7	_	7	_	0	0	_	C	Ç	=	0	~	C1	_
	4	7	_	0	0	0	_	7	7	0	7	0	0	0	_			_	0	7	0	_	0	7	_	-	_	0	7	0	0
	3	0	7	0	0	7	0	_	7	_	_	7	0	0	0		0	0	_	0	_	0	_	_	7	7	0	0	7		_
	7	_	0	0	_	0	_	7	7	0	7	0	0	7	-	0	0	_	=	_	=	=		7	~		=	_	~	-	=
	-	_	_	0	_	_	_	0	_	_	0	_	7	_	c	_	_	_	_	0	7	7	С	0	=	-	=	=	_	_	7
	nct										~		۲,	~		<u>ر</u>						_	_		_	_	_	C 1	rc.	-	v.
	Product		2	33	マ	5	9	7	×	6	=	=	13	_	7	15		2	۱۳,	7	v.	9	7	∞.	ۍ	=	_		~	<u>-</u>	
•																															

	30	_	0	0	0		0	_	_	0		7	0	7	7	_	0	0	0	_	_	_	7	0	_	7	_	_	_ <	> –
	29	0	0	0	_	_	_	0	_		2	7	0	_	_	_	7	0	0	_	0	=	_	C	7	=			cı -	
		0	0	7	_	0	_	0	0	7	_	0	0	_	7	7	0	_	0	7	_	0	0	_	_	_	0	7	_ ,	7 0
	27 2							7					_		0			_	0	0			0	7	0	0	7	0	~ ~	7 0
	26 2				0					7		7	0	0	0	0	_		_	0									0 0	
	ار	7				7				7							0	7	(0			_				_		~	
	- 1							_															_				0		0 -	
	3 24			0			_	_		0							_													- 0
	``	7				_	_	_		0										7			_	_		2			c -	
	22	0	7	0	7	0	0		7	0	_	0	0	7	0	2	0	_	2	=	~ 1	=	=	_	0	0	_	C1		-1
	21		_	0	0	_	0	7	_	0		0	_	_	7	_	~	0	0	7	=	_	=	С	_	_	_	_	— r	7 0
	50	_	0	7	-	-	_	0	_	0	_	7	0	0	_	_	0	7	_	-	_	0	_	_	7	0	С	_	o -	
	19	_	_	7	0	-	0	0	_		7	-	0	-	_	0	0	_	7	0	0	0	_	7	0	_	-	_	7 -	- 0
	8	7	0	-	_	0	7	0	0	0	-	0	0	_	7	7		0	7	0	7	0	7	0	_	0	0	7		- 0
	17	7	_	0	0	_	-	_	7	0	_	0	-	_	0	_		0	7	7	_	_	0	0	0	0	7	7	- 0	0
	16	7	0	0	0	-	0	7	7	-	_	0	_	-	_	0	0	-	-	-	_	_	С		7	0	-	-	— s	-
poi	15	7	0		0	_	_	_	0		0	7	0	_	7	C		0		0	_	_	=	∼ 1	-	Ξ	=	L1	- :	= ~1
Period	14	7	0	_	0	7	0	0	0	_	_	_	7	-	0	-	7	-	7	С	0	С	С	7			-	=	с 1 с	= =
	13	0	7	7	0	0	0	-	_	7	_	0	0	_	_	_	0	_	0	-	_	7	_	0	0	_	0	_	۰ د	7 71
	12	0	_	0	0	0	0	_	_	7	7	7	0	0	_	7		_	0	7	7	0	0	0	_	_	7	0		- 0
	=	7	_	0	7	_	7	_	_	0	0	0	0	_	0	_		0	0	0	0	0	7	_	_		7	7	~ <) C
	10	0	7	0	_	_	_	0	7	_	_	0	0	7	_	0	0	_	0	0	0	_	_	7	_	7	_	0		
	6	7	7	_	_	0	_	0	0	7	0	_		0	_	0		0	0	7	_	=	=	_		_	_	=		- ~1
	&	_	7	7	0	0	_	0	7	_	С	\sim 1	=	=		=	=	=		_	~1	C1	=	=	_	=	=		<u> </u>	- 1
	7	_	_	7	_	_	_	7	0	0	C	7	0	0		0	7	_	-	7	_	c	0			=	_	_		- =
	9	_	_	_		0	_	_	_	_	0	7	0	2	0	0	0	7	_	0	_	_	7	0	7	_	_	0	– :	0 0
	5	0	_	0	0	0	7	7	0	0	0	_	7	7	7	0	c	_	0	0	0	0	_	_	7	7	7	0	_ (5 0
	4							7			_	_		7		_							~1	_			0			- ···
										_	_		_				_	•	_											-
nued	3	7	_	7		0	0	-		_	0			0		_	_	_			7		7				_		0	_ — _
Conti	2	2	_	_	_	_	_	9	J	7	0	_	0	_	0	_	-	. 7		7	7	0	_	0	0	ن	7	-	C :	
3.5 ((1	0	_	0	_	_		_	_	_	¢	_	_		_	_	C	_	Ξ	C1	Ξ	=	_	_	_	Ξ	_		- 1	- 1 —
Table B.5 (Continued)	Product	-	7	ĸ	4	5	9	7	∞	6	10	Ξ	12	13	7	15	_	7	m	4	Ś	9	7	∞	0	10	Ξ	12	<u>"</u>	<u> </u>

ç	ء اج	1 -		. c	. 0	7	_		_	0	0	0	0	7		0	0	_	0	7		_	0	_	_	0	_	7	_	_
,		1 -	- c	· –	. 2		0	0	0	_	_	_	_	0		0	0	_	_	7	7	0	_	0	7	C	0			
, 0	1	· -	ء <i>د</i>	1 C	. ~	_	_	7	0	0	7	_	0	_	0	c		7	=	=	_	_	7	=	7	=		=	~ ₁	=
,	-					0							7		0	~	0	~			_	_	_	0	_	0	_	_		_
נ						. 0			0										0						7		~1	~ 1		
																													_	_
,						_										_			0									7	<u> </u>	٥
5		1 -			۰	0	_	7	0	0	_	0	_	0	0		7										0	_	_	_
ć		٠, ٦	4	-	. 0	0	0	1	_	7	-	0	0	_	_	0	0		0	0	7	7	7	0	_	_	0	_	_	_
ć	7 -	٠ ,	۰ ۱		· –	-	2	_		0	-	0	0	—	0	0	7	_	_	0	_	_	0	0	7	0	7	-	C	_
	ح د			. (10	0		-	-	7		0	0			С	С	С	7	7	0	=	7	С	CI		-	-	=	
ć	3 0	> <	> -	-	0	_	-	0		0	0	7		7	7	0	7	_	7	С	0	-	7	-	0	-	-	0	С	-
9	- -	- <	-	,		_	-	0	-	_	0	-	7	0	-	-		7	0	0	7	0	_	0	0	_	0	7		
0	٠	1 <	> -	- c	2	0	_	7	-	0	0	0	-	0	7	С	0	7		C	_	_	7	_	-	=	С	-	7	=
į.	- -) C	0	7	7	_	_	0	0	0	-	_	7	_	_	_	_	0	7	_	-	_	~	0	-	0	С	0
71	2 0	ى د	٦ -		. 0	_	_	0	_	0		7	0	_		_	0	_	_	0	7	7	0	0	0	C	_	0	7	7
od 31	2	۰ د	۷ ح) c	·	. 7	0	_	7	_	_	0	0	_	_	_	7	_	_	0	0	0	7	7	0	0	7	0	_	0
Period	<u> </u>	> <	> -	- c	۰ د	-	0	_	~	~1		=	0	_		7	0	0	7	_	7	=	∼ 1	=	~1	=	-	_	=	=
5	2	۰ ر	۷ د	· -	0	. 7	7	0	0	_	0	0	7	7	_	_	_	_	0	0	_	С	7	_	_	_	7	0	С	_
5	2 0	> -			· –		_	_	7	_	0	0	0	_	7	_	_	_	_	0	0	_	_	0	_	_	7	С	0	7
Ξ	= -	۰ ر	۷	> -		. 0	_	_	0	_	_	_		_	_	0	7	0	_	0	0	0	7	_	7	0	0	7	7	0
9	2 <	> -	- c	-		. —	-	7	_	7	0		_	0	_	_	7	0	0	0	0	7	7		0		_	0	7	0
c	, -			-			0	_	0	_	_	0	_	0	7		_	0	_	_	0	_		0	7	0	_	_	-	7
٥	_ ه	- د	> -		· –	. 0	0	7	_	0	_	_	7	_	_	_	_	0	_		_	0	_	7	0	7	_	0	C	_
t) C				7							0	0	С		7	-	=		-	~1	0	~ 1			_	_
		` > -	- c			. 2			0							_	_		_								=	_		_
					_												_	_	_		0) C	_	_	٥,	~ 1	_	_		_
	0 -					,		_	2	(4	0					_	_	_	_		_		_	_	1.41			_	_	_
				>				_	0	_	_	_	7	_	0	0	0	_	_	0	_		0	_	_	CI	_	7	_	
nued)	٦١	7 (> ~		0	°	2	0	_	0	_	7	_	_	_	_	_	2	_	0	_	0	0	_	0	_	7	_	-	
ontii	7	→ (> <	> <	0	1 0	0	_	0	_	_	7	7	_	_	0	_	-	0	0	0	7	0	7	-	_	_	_	_	_
.5 (C	- -		- ,	۷ ٥	,	ı C	0	_	-	-		0	_	_	0		0	_	7	0	_	0		0	-	7	0	-	0	7
Table B.5 (Continued)	Froduct	- (7 (o -	t 1/	, v	7	∞	6	10	11	12	13	7	15	-	2	m	4	Ś	9	7	œ	6	0	=	12	<u></u>		5

	_	[
	30	0	0	_	7	0	0	0		_	_		_	_	7	-	•		_	7	_	_	_	-	0	0	0	_	_	_	_	0
	29	-	-		0	0	_	_	0	-	_	7	0	7	0		•	0		0	_	7	0		0	_	0	0	7	_		7
	28	7	_	_	0	_	7	_	0		_	0	0	7	0	0	·	_	_	_	_	0	7	=	~ 1	0	~ 1	_		0	С	=
	27	7	_	0	_	-	0	0	7		0	C	_	-	0	2	ı	_	_	C1	=	=	=	Ξ	C1	C1	-			-	c	=
	26	-	7	_	_	0	0	0	0		_	0	7	7		=		Ç	_	C		-	C	_	7	С	C	=	-	-	7	7
	25	0		7		0	0	7	0	_	0	0	-	_	7	_	,	0	7	7	0	_	~	_	С	0		_			-	0
	24	-	0	0		0	_	-	~	7	7	_	0	0	0	7	!	0	_	0	_	_	~	0	0	_	7	0	7	0	_	7
	23	0	7	7	7	0	0	_	0	_	_	_	0	7	0	0		-	_	0	_	0	-	_	_	0	_	0		7	7	0
	22	0	_		0	_	0	7	0	0	7	7	0	_	7	0		0	0	7	_	0	~	_	0	0		0	7	7	7	0
	21	0	7	0	0	7	_	0	_	7	0	_	_	_	0	_		_	0	0	0	0	~	_	_	7	_	7				=
	20	-	0	0	0	7	0	_	0	0	_	_	7	7	_			_	0	_	_	С	7	=	~1	С	7	Ξ	_	_	=	_
	19	-	0	7	_	0	0		0	_	0	_	_	0	7	7		_	0	_	0	7	C	0	_	0	_	С	Ċ1	_		7
	18	0	_	_	_	0	_	0	-	0	0	7	7	7	_	0		_	7	_	0	0	0	7	С		_	С	_	7	_	=
	17	0	0	_	7	_	7	_	0	_	_	7	0	0	0	_		0	0	_	_	0	_	7	0	_	0	0	_	7	7	_
	16		_	0	0		7	7	0	_	_	0	_	0	_	_		0	7	0		_		0	0	_	_	0	_	7	<u> </u>	_
þç	15	0	_	7	_	0	_	_	0	_	_	_	7	0	0	_		_		0	7	_	0		_	0	_		_	_	o ·	_
Period	14		0	_	_	_	0	7	0	С	7	7	_	0		c			_	Ξ	~1	~ 1	_	=	r-1	_		Ξ	Ξ	=	Ξ.	_
	13	7		_	_		_	7	0	=	С		7	0	=	0		_	_		_	=	_	_	0	_	=	C1	Ξ	=	_	~ 1
	12	-	7	0	0	0	_	_	~	_	_	7	_	0	0	_		7	_	0	0		C	=	7	7	_	_	=		— :	=
	=	_	_	0	_	0	_	_	0	0	0	7	0	_	7	7		7	0	0	0	7	_	0	_	0	С	7	7	c .	7	=
	2	7	0	_	_	_	7	0	7	0	0	_	_	0	0	_		0	0	0	_		_	7	0	7	0	0	_	7	7	>
	6	7	_		_	0	_	0	7	0	_	_	_	_	0	0		0	_	_	0		0	0	0	0	_	7	_	7 ,	٦ -	_
	∞	0	_	0	7	-	_	_	_	0	_	0	0	0	7	7		7	0	0		0	0	_		_	_	_	_	<u> </u>		_
	7	0	0	0	_	_	7	0	7	0	0	7	0	7	0	7		7	=	_		_	=	=	ĊĮ.	_	~ 1	=		= .	;	=
	و	0	0	7	_	_	7	_	_	0	0		_	0	_	_		0	_	0	_	_	_	_	_	_	=	_	۲	Ξ.		_
	Ş	_	7		_	0		_	0	_	7	0	_	0	0			7		0	_	0	_	0	_		7	c	0	c (7 -	_
	4	0	0	_	7		7	0	_	0	0	0	0	7	7	_		7	_	0	7	_	0	0	0	7	0	_	0			
	3	0	7	_	0	7	_	0	7	0	0	_	0		0	7		0	_	0	_	0		_	7	0	_	0	7			_
	7	0	0	_	_	_	0	0	7	7	0	0	_	7	0	7		0	0	7	_	_	_	0	7	_	0	7	0	۰ ت		_
	_	0		7	7	7	7	7	0	0	_	0	0	0	0	0		0	0	0	7	_		_	_	0	_	=	_	7 3	۰ د	~1
	ا ا																															
	Product	-	7	т,	4	'n	9	7	∞	6	2	=	12	<u>~</u>	ন	5.		_	℃ 1	rc.	-,	v.	c	t	×	÷	Ξ	=	<u> </u>	<u>"</u>	<u> </u>	<u>.</u>

Table B.5 (Continued)

		1																													1
	30	0	0	0	7	7	0	7	0	7	7	_	0	0	_	0	-	0	_	0	_	-	-	0	0	_	-	0	7	_	7
	59	0	7	_	0	0	-	7	0	_	0	0	_	7	0	7	_	7	-	0	0	0	0	7	0	_	7	0	-	-	-
	28	-		0	7	7	7	0	0		0	_	0	0	_	_	7	_	_	-	0	-	_	0	0	7	-	0	0	_	-
	27	2	7		_	_	0	-	-	_	0	0	0	_	-	0	7	_	~	С	0	7	=	_	-	=		_	=	Ξ	-
	26	0	_	7	7	0	0	7	-	0	_	0	0	-	7	0	2		7	0	С	0	0	7	-	_	0	0	0		7
	25	_	_	0	0	7	0	_	7	0	7	0	7	0	0	_	0	-	0	7	_	-	_	-	С	0	-	7	0	0	7
	24	0		_	_	0	0	_	7	7	_	-	_	0	_	0	_	7	_	0	0	0	0	0	7	_	0	0	7	-	7
	23	0	_	0	_	_	0	7	0	_	-	0	_	_	_	7	0	-	0	7	0	0	_	_	0	_	7	_	_	-	-
	22	0	0	0	7	_	-	7	0	-	7	_	0	0	_	_	0	_		_	7		-	7	0	-	0	0	_		0
	21	0	_	0	7	_	0	_	7	0	0	7	0	-	0	7	7	0	0	7	0	0	_	_	0	С	0	_	7	7	-
	20	-	_	_		_	0		_	0	7	7	-	0	0	0	С	0	С	-	7		~ 1	_		=	_	_	=	_	-
	19	0	0	7	_	_	_	0	7	7	_		С	0	0	-		_	_	С	c	~	-	7	С	-	-		7	С	=
	18	0	-	0	7	0	7	7	0	_	_	_	_	0	_	0	_	0	0	0	0	~		C 1	~	С	7	0	7	-	0
	17	7	0	_	0	_	0	_	7	0	7	_	0	0	_	-	7		0	-	_	0	0	-	_	7	С	7	0	_	
	16		_	0	7	-	_	0	_	7	7	0	0	0	_	0	0	0	7	0	0	~	0	7	-	-	7	_	0	_	-
po	15	0		_	_	0	_	7	0	_	0	_	0	_	7	_	_	_	_	7	-	0	0	-	0	_	0	_	0	,_	7
Period	14	0	0	7		7	7	0	0	0	_	_	_	0	_	_	_	7	0	_	7	0	0		0	C	0	-	0	7	7
	13	0	0	_	7	7		_	_	7		_	0	0	0	С	c	_		-	_	C	_	~1		-	=	CΙ	_	=	=
	12	0	0	0	_	_	_	_	7	0	-	7	-	_	_	0	7	0	_	7		C	_		0	О	_	0	7	-	=
	11	_	_	_	7	_	7		0	0	0	0	0	7	0	-	_	0	0	7	7	-		С	_	0	-	C	CΙ	C	-
	10	-	0	_	_	0	_	0	7	0	_	-	_	7	0	-	_	0	7	0		7	7	-	С	0	-	_	C	0	-
	6	_	0	_	0	7	0	0	_	0	0	7	7	7	0	-	0	7	-	7	0	C	-	_	_	С	0	7	-		=
	8	-	_		0	0	_	0	7	_	-	7	_	_	0	0	0	_	7	7	7	0	0	7	0	0	С	0	_	0	7
	7	0	0	_	_	7	0	_	0	7	0	-	-	0	7	_	0	-	0	7	0	0	_	_	7		С	0	7	=	7
	9	_	_	0	_	0		_		0	7	=	0		~		-	-		0	-		_	=	=		_	C)	=	_	-
	3	7	0	7	0	-	-	0	_	0	-	0	_	0	_	7	7		0		-	C		_		0	_	=	7	_	0
	4	2	0	0	0	0	7	0	0	7	0	0	7	_	_	7	_	_	7	0	0	7	С	0	0	7	_	-	0	_	-
ed)	c	0	_	0	0	7	7	_	0	0	0	7	_	0		7	2		0	0	-	~	0	0	_		-	_	0	_	7
ntinu	7	7	0	0	_	0	0	-	0	_	7	0	_	7	7	0	7	0	0	0	7	-	_	7	7	0	0	0	0	_	-
s (Co	-	-	_	7	_	0	0	-	_	-	-	0	7	_	0	0	7	_	0	0	0	-	_	-	7	0	0	7	-	0	-
Table B.5 (Continued)	Product	1	7	т,	4	5	9	7	×	6	01	=	12	13	7	15	_	7	ır,	ব	'n	ý	7	×	6	9		12	<u></u>	三	15
																															ı

Table B.6 Demand data set 6: Large problem size, smooth demand, high utilization

														Per	iod															
Product	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30
1	0	0	1	1	1	2	2	2	1	0	2	1	0	0	1	0	2	1	2	1	2	1	0	1	1	1	1	1	2	2
2	1	0	2	0	2	1	2	2	2	2	2	0	2	1	0	1	1	2	1	1	1	2	1	1	2	1	2	0	2	2
3	1	1	I	1	1	2	0	1	1	1	2	2	0	2	1	0	1	0	1	1	1	1	1	2	I	1	1	2	1	0
4	l	1	1	0	1	0	1	1	2	l	0	2	0	2	2	1	1	2	2	2	1	1	0	2	1	l	1	1	0	1
5	1	0	1	2	2	0	2	1	0	2	l	1	2	2	1	1	2	1	1	1	1	0	I	2	0	2	1	1	1	1
6	1	1	Ì	2	1	1	1	2	2	2	1	1	1	1	2	l	0	2	0	1	1	1	1	2	2	2	1	1	2	2
7	1	2	1	1	1	1	1	0	1	0	1	0	2	0	1	1	3	0	0]	2	2	2	1	1	1	1	2	1]
8	1	1	0	2	()	ı	1	2	1	1	2	l	2	2	2	1	0	1	1	1	2	2	1	1	2	2	l	2	1	2
9	2	1	1	Ì	2	1	1	0	l	0	0	2	2	1	2	1	2	ţ	2	l	1	0	2	0	1	1	2	1	1	1
10	2	2	ì	2	()	2	1	2	2	2	2	j	1	2	l	2	2	2	2	1	1	2	2	1	2.	Ţ	0	1	2	I
11	2	2	2	2	2	2	1	1	1	1	1	1	1	1	1	2	2	2	1	2	1	2	2	0	1	1	2	1	0	l
12	0	2	2	1	1	ł	I	1	ł	1	2	ł	2	1	1	1	2	Į	2	1	1	0	2	2	2	1	1	2	1	ļ
13	2	2	Ì	ì	2	2	2	1	1	2	2	2	1	1	2	2	2	2	1	l	0	1	ì	1	ì	1	1	2	1	2
14	1	1	2	()	l	0	1	1	0	1	0	1	2	1	0	2	0	()	1	1	1	1	1	1	0	1	2	0	1	l
15	2	2	l	2	ı	2	ı	l	2	2	0	2	0	1	1	2	0	I	ı	2	2	2	1	I	ı	1	1	1	2	0
1	2	I	2	ı	I	ł	2	2	ì	1	ì	1	2	1	2	1	2	2	1	2	2	I	1	0	2	1	2	1	0	0
2	1	1	1	1	2	l	2	1	0	2	2	2	1	1	2	l	ì	2	2	2	2	Ì	0	1	1	0	1	0	2	1
3	1	0	1	1	2	}	0	l	1	2	1	2	1	1	1	2	0	1	1	1	2	0	1	1	0	j	1	j	2	2
4	1	1	1	1	l	1	1	2	2	0	1	0	2	2	0	2	0	2	I	0	2	2	2	2	2	2	0	2	1	0
5	1	2	0	1	2	1	2	0	2	0	2	1	0	2	1	1	2	()	1	1	1	2	2	1	2	1	0	1	2	2
6	1	2	1	2	1	1	2	2	2	1	ſ	0	Ī	i	2	1	i	1	1	1	0	0	1	1	1	2	2	0	2	0
7	2	1	2	2	2	l	2	I	2	2	i	l	2	1	1	1	2	ļ	I	1	l	0	l	2	1	2	0	1	2	2
8	1	1	()	2	1	2	1	1	()	l	()	1	0	0	1	2	2)	1	l	1	2	}	2	1	()	2	2	1	l
9	0	1	2	1	1	ì	l	1	2	1	2	2	1	1	2	1	1	1	2	2	0	2	2	2	1	2	I	2	0	0
10	2	1	2	I	1	l	0	1	ì	l	()	ì	2	2	2	2	2	1	I	2	2	1	l	l	l	()	1	2	1	1
11	2	2	2	1	2	1	1	2	0	i	2	2	l	1	2]	ì	2	1	2	l	2	2	ì	2	2	1	0	0	2
12	2	2	1	()	1	2	l	2	1	1	2	2	2	l	1	()	1	1	2	0	0	2	1	1	1	1	2	2	1	2
13	1	1	l	1	()	l	0	1	1	2	2	2	2	1	0	ì	I	l	1	1	2	1	2	l	l	1	2	1	1	2
14	1	l	1	1	1	2	2	0	2	1	0	()	1	1	0	1	1	2	1	2	0	1	0	2	2	1	2	2	2	2
15	0	1	1	2	()	1	1	1	1	2	1	ì	()	2	1	l	l	()	ŀ	0	2	1	1	0	()	2	l	1	1	1

	30	7	7	7	0	_	7	_	_	7	0	0	_	7	0	7	0	7	_	7	7	_	_	7	_		С			(7
	29	0	_	7	7	7	_	_	_	_	_	_	_	_	_	7	7	_	7	7	_	_	_	_	_	0	7	0	0 (7 '	7
	28	7	7	_	_	0	7	7	7			0	7	0	_	_	_	_	_	7	7	_	7	_	7	_			_ ;	o .	_
	27	0	_	7	7		_	7	_	7		_	_				_	7	_	7	7	_	7	_	7	0		7	:	0	0
	26	_	7	_	7		_	0	7	7	-		_	7	_	0	7	С	7	∼ 1	=	_	C)		7	=	~	=	∼ 1 ·	_	_
	25	_	_	7	7	7	0	7	_	_	_	7	0	_	_	_	-	0	_	_		_	_	7	_	_	~ 1	∼ 1	7	_	_
	24	7				_	7	7	7	0	_	0		7		_	_	0	7	_		7			7	_	_	_	_	_	7
	23	0	_	_	_	7		_	7	_		_	7	7	_	_	7	_	0	7	_	_	_	7				_	_	_	7
	22	7			7	_	0	_	_	_	_	7	7	_	7	0	_	_	_	0	0	7		7	7	_	0		7	7	7
	21	_		0	_	_	7	7	7	7	_	_	0	7	_	_	7	_	_	0	7	0	7	_	_	7	_	_	7	-	7
	20	0	7	0	_	7	-		_		_	7	7	7	_		7	7	7	0	0	_	_	_				7	7	7	C
	19	_	_	0	_	_	7	0	_	7		_	7	_	7	7	7	7	_	_	7	_	7	7	-		_	=	_	_	=
	18	_		7	0	_	_	7	_	7	7	0	7	_	0	7	7	7	C 1	C	_	~ 1	7	_	_	_	7	=	_	_	=
	17	7	0	7	7	7	_	_	_	_	_	_	_	0		7		0	_	7	0	_	_	7	0	_	7	7	7	~	_
	16	_	0	_			_	_	7	7	_	0	7	7		7		_	7	7	_	_	_	7		7	0	_	_	_	_
þ	15	_	_		_		0	_	_	7	7	7	0	7		7	0	_	7		7	C		7	7	7	_	7	_	C	
Period	14	7		7	0		-	7	_	7	_	7	0	7	0	_	7	_	_	_	_	7	_	=	_	С	7	_	7	_	7
	13	-	_		_	7	7	_	7	7	_	0	0		_	7	7	0	0	7			_	С	_	С	7	C 1	7	~ 1	7
	12	_	_	_	7	7	_			7	7	7		0	0	_	_	0	7	_	0	~1	7	~1	_	=	_	_	~1		~ 1
	11	_	_		_	0	_	_	7	7	7	7	_	7	0	_		_	7	_	_	7	С	7	~ 1		7	C	_	_	_
	10	1		_	7	0	0	7	0	_	7	_	7	7	7	_	7		_	7	7	_	0	7	_	_	7	_	0	_	_
	6	2	_	,	7	_	_	_	7	_	_	_	_	_	_	_	_	7	0	7	_	7	0	_	_	0	_	7		7	7
	8	1	7	_	0	_	_	0	7	_	0	7	7	_	7	7	7	0	_	0	_	_	7	7	7	7	_	_	_	7	0
	7	1	0	_	_	7	7	_	_	7	_	0	_	7	_	7	7	7	_	_	_	_	_	0	_	0	7	_	7	7	_
	9	2	_	_	7	0	_	7	_	_	0	7	7	_	0	7	7	_	7	_	7	7		7	0	_	0	7	_	_	0
	5	_	_	_	7	0	7	0	_	7	0	7	_	_	7	7			_	7	_	7	С	_	7	7	=	~	7	_	=
	4	_	_	7	_	_	7	_	_	0	_	_	_	7		7	0	7	_	_	0	~			7	_	_	_	7	_	7
ਉ	3	7	_	_	7	7	_	7	0	_	_	7	_	_	0		7	_	7	_	7	7	_	_		_	0	_	_	_	
timue	7	-	_		_		0	_	7	0	7		7	_	7	7		0	7	_	_	7	7	7	0	-	_	7	_	~1	_
Table B.6 (Continued)	_	_	0	7	7	7		_	_	_	7		_	0	_	7		0	7	_	7		~1		~1	_	_	_	_	0	~ 1
e B.6	ıct																														
Table	Product	-	7	m	4	Ś	9	7	∞	6	01	=	12	3	7	15	_	7	"	7	'n	9	7	×	6	10	=	12	<u></u>	<u>T</u>	15
,		l																													

	30	7	_		7	7	_	7	7	7	_	7	0	0	0	С	-	_	7 -	- ~	0	7	-	7		-		<u>۔</u>	~ -
	53	1	0	7	-	_	7		7	-	7	_	-	_	_	-	7	7	7 -	- ~	· —	-	0	7	0	0	0	7 .	- 7
	78	1	_	7	_	7	7	_	_	0	7			_	-	_	-	_		- ~	· –	-	_	_	-	-		(7 7
	27	1	_	_	7	-	_	_	7		_	_	_	7	_	_	0	0	- (4 C	7	7	_	_	7	_		<u> </u>	
	56	0	7	7	-	_	7	_	0	0	7	7	_	7	0	7	0	_	7 -	- ~	_	0	7	_	7	_	0	7	7 -
!	25	-	, ·		_	7	_	0	_	_	~	_	_		7	7	7		0 1	7 -	_	=	_	C 1	-	-		ΛI .	- ~1
	24	0	7	_		_	_	7	_	7	0	7	_	7	_	_	0	7	7 (v	_		7	_	-		c ·	- (~ -
:	23			7	_	_	_	_	_	7	_		_	_	_	7	7	_	0 (4 ~	С	7	_	_	-	-	(~1 (7 -
:	22	_		_	7	7	0	_	_	-	0	_	_	7	7	7	0	7	7 -		0	7	0	_	7	7	 .		- ~1
:	71	_	0	7	_	,	_	7	7	0	7	_	_	7	-	_		_	- <	2	7	7	_	0	7	_	(7 .	
	2		7	7	_		7	0	_		_	_	_	7	_	_	-	_	7 -	- 2	0	-	7	_		_	– (7 (7 0
,	6	7	<u> </u>	_	_	_	_	0	7	7	_	_	_	_	7	_	_	7	7 -	- 2	_	7	_	7	-	С	0 (э·	- 2
•	∞	(ο.		7	7	_	7	0		_	_	_	7	7	_	7			- ~	=	-	_	_	\sim 1	_	~1 :	= (~ı —
	-	-	7	7	_	_	_	7	_		_	_	0		7	_	_	7	~ ~	- ~	_	7	_	_		_	٠ -		
;	9	7	- ,	_	7	_			7	7		_	7	0	0	_	0	_		۰ -	_	~	_	7		7	 .		- ~
po!		7	o ,	_	_	7	7	7	_	0	_	7	_	_	_	_	2	_	0 ~	- ~	_	-	_	_	7		<u> </u>	7 :	= ~1
Period	4	7	- (7	7	0	0	7	7	-	_	7	_	0	7	0	7	7	7 ,	۰ o	_	7	_	_	-	С	<u> </u>	<i>-</i>	
;	13	7	7 •	-	_	7	7	0	0	0	7	7		_	0	7	-	0	7 -	- 0	7	0	_	_	7	7	~ (7 -	
;	2	- 0	۰ د	7		_	_	7	_	_	0	7	7		_	7	-	0		- ~	7	~	_	_	-	_	Λ·		
;	=	0		_	7	_	_	_	0	_	7	~ 1	7	_	-	7	-	_	~ 1 ~	- ~1	7	~	_	=	<u>ر ۱</u>	_	e -	-	
	2	0 ·			_	_	7	7	_	7	7	_	7	-	_	0	7	_	- =	0	_	7	=	\sim I	7		~ 1 :	= r	1 (1
•	م	- .	<u> </u>	7	0	0	_	_	_	7		~	_	_	7	7	-	7	0 0		_	c	7	-	-	C ↓	- 1	\1 r	17
(∞	7	7 .	_	0	7	7	-			-	_	_	_		_		_	7 -		_	7	0	0	7	7	7 -		
ı	-	- ·		_	7	-	_	-	_	7	-	_	7	_	-	-	-	_	- ~		7	-	7	_	7	0	7 -		
,	او	7	o ,	_	0	7	7	0	-	7	7	0	_	7	7	-	2	0	7 -		7	-	7	7	0	-	7	-	
,	\sim	7		-	0	0	7	_	_	_	7	7	-	7	0	7	7	_	<i>-</i> ر	10	7	-	7	-	0	_	7 (7 (> -
•	4	7	o ·	_	7	_	0	-	7	7		C	-	_	7	~ 1	7	-	= ^	1 —	_		7	_	Ξ	=	r-1 -	- ^	ન ભ
` '	~	0	7 .	-	7		7	_	_	-	7	0	_	-	-	7	-	-			7	7	-	7		0	7 :	= 1	7 -
•	7	0 .	<u> </u>	_	-	7	7	7	0	7	-	7	7	0	-	_		-	- ^	۰ -	_		_	_	7			c	7 -
	-	<u> </u>		-		_	_	0	_	7	7	_	_	7		7	_	7		2	7	0	0	_	-	(1)	7 -		7 -
•	Product	- •	7 '	٠,	4	2	9	7	∞	6	01	11	12	13	14	15		7	m t	ריח	9	7	∞	6	0.1	Ξ:	2 5	<u>.</u>	15

30	2		7 .	- -		. ~		_	_	-	0	7	_	-		7	-	7	7	_		- =	; –	_	_		- ~
29	7	7	۲.	_ <	۰ د	٠ د	1 ~	_	-	_	0	0	_	-	_	7	_	_	7	,	7 -			_	0	_	- 7
28	7	7	۰ ب				. 7	_	_	7	-	0	7	_	,	_	-	7	0	7 .	-	1 -	. 7	_	_		0 7
27	i -	0	0 -		- -	. 2	0	7	7	_		7	7	7	-	_	7	7	7	7		- ~		0	_	0	
26	0	7	۰ .	-	٦ -		. —	0	7	_	7	7	_	7	7	7	7		_		- ~	- 0	0	7	_	_	7 -
25	-	7	۰ د	7 (7	-	. 7	0		_	-	-	7	_	_	_	_	7	0	۰ د	7 (1 ~	. —	_	_	7	0 7
24	7	7	7 (7 -				0	7		-	_	=	_	7	_	7	_		~1 :	= ~	- =	_	~	~1		
23	7	<u> </u>	- -	، د	۰ -	. 7	_	_	7	_	0	7	0	7		_	_		7	э·		. –	0	7	7	7	- ~
22	0	7	<u> </u>	۷ ر	۰ -		_	0	7		7	7	0	_	_	7	0	7		- :	ر د	٥ ٢	. ~	7	7	7	o
21	7	_	– ,	7 -	- -	·	_	_		_				7	7	0	-		7	0 (7	- 0	_	_	7	C1 -	- ~
20	_		7 -			_	7		- ·		7	7		0	0	0	-	7	۲,	- (7 0	0	~ ~	~	7	0	N 71
19	0		- ,	۷ ر	1	_	7	_	– (7		_	_	_	-	_	_	o ·	– ,	٧.			7	7	_	7	2 5
81	0	7	7 -		- 7	_	_	7	0		7	7	0	_	_	_	7	– (-	7 (~ ~	۰ م	С	С	7	-	~ ~
17	_	7 .					_		7 .	_	(~ 1	0	7	_	_	c	7	~ (٦.			c	~ 1	_	ΛI ·	
16	7	7 .	- <	۰ د	٠	7	7	0	– (7	7 .	_	0	0	7	7	_	- ,	η.			-		_	_		0
od 15	2	– .	- ر	۷ –	- 7	_	7		— (۰ د	7	0	7	0	7	7	7	<u>۔</u>	7 .	- <i>c</i>	۷ C	0	7	7	С	0 (7 -
Period 14 15	-	- (7 -	- ر	٠	_	-	0	— (0 '	7	7	7	-	-	_	1	7 .	- 6	7 (> ~	. –	7	0	_	_ (7 7
13	-	7 0	> -	- ~	۰ -	_	7	7	7 .		- (-		_	7	0		7 ()	o -	- ~	· —	7	7	0	(7 7
12	-	٦.				7	7	0	0	o .	- (7	7	7	-	7	- ·	- (~ (۷ ٥) C	-	7	_	_	7 .	
	2	0 (7 0	> -	. 7	_	0	-			7	7	_	7	-	7	7 .	_	7 -	(7 ~	0	_		0	c -	- ~1
10	_	7 -			. 0	_	_	_	‹	7 (7 (7	_		7	_	 .						_	~1	0	C1 (`1
6	-	7	7 -	- c	2	_		_	– (7 .			_	_	7	_	– (7 -			٧	_	C	_			- 2
∞	-	7	> -		. 7	_	_	7		- -	<u> </u>	- (7		7	_	- (7 -		۷ -	- c	7	7	7	c ·	– •	
7			- ر	۰ –	. –	7	_	0	7 (7 -		 .		_	-	_	– .			۷ <	0	7	7	\sim 1	∼ 1 ·		
9	0	7 (7 0	, c	ı —	0	_	7	7 (7 .	- <)	7	_	-	7	7	7 -		7 -	- =	_	_	0	C1 ·		
5	2	-	> -		. ~	_	0	,	7 -			- (7	7	-	0	۲.		- 6	۷ ر	٧	7	7	0	α .		- c
4	2	7 -	- ر	4 0	· —	_	_	7	<u> </u>	> -		7 .	_	-	-		7 (7 r	7 -	- <	-	~ 1		=	Ξ.	_ <	-1 CI
, w	7	-	7 -		. 7	С	_					- (7	_	 -	_		- (~1 ~	- r	ı ~	-	_	-	<u> </u>	_ ^	1 -
2	7	— <	> -	- ~	0	7	7	— ·	7	> 0	7 -	- (7	0	_	0	<u></u> د	۷ -				0	_	7	7 ,	7 (171
	7	7 -				7	7	7	0	۰ د	- (7 .	-	0	_	_						_	_	7		- r	7 7
Product	_	7 ر	0 4	rv	9	7	∞	o :	2:	= :	7 :	<u>:</u>	14	15	_	7	m .	4 "	n v	2 1	- 20	6	10	=	7 :	<u>د</u> -	<u> </u>

	30	_	_	_	_	0	7	7		7	-	_	7	0		7	-	7	_	7	0	7		0	7	7	_	0	=	~	7
	59	0	7	7		_	0	-	7	0	_	0	7	7	7	7		_	_	-	-	_	7			_	7	C		~	2
	28	-	_	_	7	_		7	_	7	0	_	7	_		-	0	7	-	_	7		_	7	-	_	-	С		7	7
	27	7	-	_	0	7	_	_	7	7	7	7	0	0	7	0	7	_	7	7	С	_	0	0	-	7	7	7	7	0	-
	56	7	0	7	7	7	0	_	_		-	7	_	0	7	-	****	0	7	7	_	_	7		-	_	0	7	7	0	7
	25	-	_	_	7	7	7	-	7	_		_			0	_	7	_	0	_	7	7	_	_	7	7	-	_		_	0
	24	_	_	7	0	_	7	_	7	_	_	0	_	7	7	_	-	7		_	_	~	_	7	_	_	-	_	7		-
	23	-	_	7	_	7	_	7	_	0	0	7	7	_	7	0	7	0	7	7	7	С	_	0	7	7	-	C	-	7	7
	22	0	7	0	7			_	7	7	_	_	_	_	_	7	-	-	7	7	7	-	0	_	_		_	_	-	7	-
	21	7	_	0	_	7	_	7	_	7	_	_	-	_	_	-	0	0	_	-	7	7	_	7	0	_	-	7	7	CI	-
	20	-	_	7	0	7	_	_	0		7		7		_	7		7	_		0	7	7	7	-	7	0	_	-	7	
	19	_	_	_	_	_	7	_	_	_	_	_	7	7	7	0	-	_	_	_	_		_	7	-	7	_		7	0	7
	18	0	-	_	7	_	_	7	7	_	_	_	_	_	7	_	_	7	_	0	0		7	_	_	7	7	0	7	_	7
	11	-	_	0	7	7	7	_	0	_	_	7	7	_	0	7	_	7	-	_	_	~	_	=	7	7	=	~1	\sim 1	_	-
	16	_	_	7	_	_		7	7	_	_	0	0	_	7	7	7	_	7	-	7	0	0	7	_	_		_	~1	=	7
po	15	0	7	7		_	7	0	_	7	7		_	_	7	0	_	7	7	_	7	C	_	7	С	~1	7	=	-	_	-
Period	14	_	0	7	7	0	_	0	_	7	7	7	7	_	7	0	_	7	7	_	7	0	_		7		-	_	_	-	-
	13	0	0	7	0	7	_	7	_	7	7	0	7	7	_		0	_	7	_	_		7	7	7	_	С	_	-	_	7
	12	7	_	_	0	-	7	_	_	7	_	_	7	_	-	_	7	_	_	7	_	0	7	7	_	7	0	-	_	_	-
	11	_	0	_	_	7	7	0	_	7	7	_		7		_	_	_	7	_	7	-	7	_	0	_	_	7		7	٥
	10		_	7	0	_	_	0		_	7	7	7	_		7	7	_	_	C	7	-		7		=		_	7	~ 1	-
	6	0	7	0	_	7	_	7	0	7	_	_	_	7	_	7	_	_	7	_	7	-	_	0	7	CI	7	С	_		-
	8	7	7	_	0		_		7		_	_	7	_	_	7	_	_	_	7		-		7		0	-	7	7		7
	7	~	_	7			_	_	_	7	_	7	_	7	_	0	0		_		7	7	0	7	-	7	_	_	_	_	7
	9	-	_	_	_	7	7	_	0	_	7	7		0	7	_	7	0	7	_	_	-	_	0	С	7	7	~ 1	_	7	-
	5	0	_	0	_	_	_	_	7	7	0	7	7	_	7	7	0	7	_	_	_		_	_	7	7	-	7	_	_	-
	4	7	_	_	_	7	7	0	_	_	_	_	7	_	_	_	_	_	7	_	7	0	7	7		_		7	С	7	٥
	3	7	_	_	_	_	_	7	7	_	7	0	_	7	_	=		_		_	_	-	~ 1	=	~ 1	<u>~1</u>	=	_	-	C ł	~1
	7	-	7	7	_	7	_	0	_	_	7	_	0	_	7	-	-	0	_	7	_	7	=	_	_		7	7	_	~1	-
	_	0	0	_	_	_	7	7	7	_	_	7	7	_	_	_	0	_	7	0	7	7	_	_	7	_		_	7	_	-
	Product	- 1	7	ю	4	5	9	7	∞	6	10	11	12	13	4	15		2	m	ক	'n	9	7	∞	6	10	=	12	<u></u>	<u> </u>	15

Table B.7 Demand data set 7: Large problem size, lumpy demand, low utilization

	30	0	3	_	0	0	0	0	7	С	0	ব	C	7	С	0	,	=	-1	~ 1	0	=	=	=	=	~1	=	=	=	=	7	Ξ
	53	0	0	0	0	0	0	0	0	7	4	~	С	С	m	0	,	=	0	0	0	0	~1	'n	С	С	Ś	С	0	0	0	c
	28	3	0	0	0		0	4	0	0	4	0	0	0	0	0	,	၁	0	0	0	С	0	0	7	0	0	0	0	4	0	0
	27	0	٣	0	_	0	٧	0	0	0	0	0	7	0	0	_		0	0	3	0	0	0	0	7	0		0	0	0	0	
	26	0	0	٣	0	0	0	4	0	0	0	0	0	'n	0	0		0	0	0	0	0	7	0	0	0	0	4	"	_	0	0
	25	0	0	0	9	0	0	0	0	'n	0	0	0	0	0	_	,	=	0	0	0	0	0	'n	4	0	7	_	0	0	0	0
	24	_	0	0	0	0	0	0	ς,	_	0	0	4	m	0	0	c	>	۲۲,	m	0	9	С	0	0	0	c	0	С	=	0	С
	23	0	С	0	6	0	0	0	0	С	0	С	=	۲۲,	=	=		=	Ξ	=	=	cc.	C ‡	=	C1	=	Ξ	Ξ	C 1	=	=	"
	22	3	0	0	0	0	0	0	(1)	7	0	0	0	0	4	С	(0	7	0	_	c			7	0	=	С	_	_	ce,	=
	21	0	0	0	0	4	0	0	_	'n	0	0	0	7	0	0	,	-	0	4	0	_	0	0	0	0	"	0	0	0	4	C
	20	0	0	0	0	0	_	0	0	0	0	9	0	0	Ś	0	,	~ 1	0	0	0	0	œ	0	0	0	0	0	0	_	0	С
	19	0	0	0	0	0	4	0	0	7	7	0	4	0	0	0		0	0	0	S	0	0	7	0	0	0	0	0	0	0	С
	18	0	7	0	0	0	4	0	0	0	_	0	0	0	0	0		Υ,	4	0	0	0	0	0	0	7	0	0	0	0	~-	0
	17	0	0	0	0	_	0	4	_	2	0	0	0	0	_	0	¢	>	0	S	0	С	0	7	_	ις,	0	С		0	0	Ç
	-16	0	0	0	0	0	0	0	0	0	۲۰,	C	rr,	7	=	7	:	=	=	=	=	rr,	Ξ	=	Ξ	Ξ	v.	=	7	Ξ	=	Ξ
og [o	15	0	0	0	0	0	0	0	0	0	0	c,	0	7	С	7	ć)	ίĊ	0	0	С	7	С	0	0	0	0	С	7	0	0
Period	14	0	0	0	0	0	0	0	7	0	0	0	'n	0	0	0		>	0	0	_	_	0	0	0	0	0	4	0	"	٣	C
	13	5	0	7	0	0	0	0	0	0	'n	0	0	0	0	0	,	0	0	0	0	0	0	7	0	0	0	0	0	_	0	4
	12	0	0	0	Ś	0	0	0	0	0	0	0	9	0	0	_	,	0	7	0	0	0	'n	0	0	7	0	0	0	0	'n	0
	11	Š	0	7	0	0	0	0	0	0	0	0	С	0	0	'n	(>	4	0	0	C	0	0	c	0	7	9	C	=	0	C
	10	4	0	4	0	7	0	С	0	С	0	_	С	0	0	_	:	=	С	0	C	c	-	0	'n	_	=	=		=	Э	7
	6	0	0	'n	0	0	4	_	С	0	=	¢	С	7	=	c	:	=	0	=	=	ડ	Ξ	=	=	Ξ	Ξ	-	Ξ	=	C1	=
	8	0	к,	0	4	0	0	0	"	0	0	0	0	0	7	С	·	0	'n	0	_	0	D	С	С	0	c	Ś	0	0	0	_
	7	4	0	m	0	0	0	0	0	0	0	_	0	0	С	4	(>	0	'n	0	S	0	0	7	0	C	0	Ç	0	0	c
	9	0	7	_	0	9	0	0	0	0	0	7	0	0	_	0		0	0	0	0	0	0	0	0	0	0	7	С	S	0	0
	5	7	0	4	0	0	0	0	0	0	0	0	0	0	_	0	•	_	0	0	m	0	0	0	٣,	-	0	0	_	0	0	cr,
	4	0	0	_	3	0	0	S	0	0	7	0	_	0	0	0		>	0	ς,	0	0	4	0	0	0	0	0	С	0	0	'n
	3	0	0	0	0	_	0	7	0	4	-	0	0	_	ť	0		>	0	_	0	0	'n	0	С	9	0	0	c	7	0	С
	7	-	0	0	0	С	0	'n	0	0	0	0	ပ	c	=	c		=		=	=	Ξ	Ξ	~	=	=	Ξ	~ 1	7	er.	=	Ξ
	-	0	0	0	0	0	7	0	0	0	0	0	0	0	0	'n		7	۲۰,	0	0	0	_	0	0	0	7	0	0	7	7	С
	Product	-	7	3	4	Ş	9	7	%	6	01	11	12	13	4	15			7	٣,	4	'n	9	7	∞	6	10	=	12	<u></u>	4	5
	Pr																															

	_																													
	30	0	_	0					0								0	0	4	S	0	0	0	m	0	0	0	0	0	0 0
	29	2	0	0	0	0	0	0	0	0	2	0	0	С	0	С	40	0	0	С	Ξ	=	С	0	cr,	С	C	ক	0	0 0
	28	4	0	4	0	0	0	0	0	0	-	7	0	—	0	0	0	0	S	0	С	0	Ś	0	0	С	0	0	0	0 2
	27	0	0	_	0	0	0	0	0	4	0	_	0	0	ĸ	ę	0	0	0	0	0	0	4	0	0	0	0	0	S	m O
	56	0	0	0	-	0	4	_	0	_	0	0	m	0	7	0	4	0	0	0	0	0	m	7	0	m	0	0	0	0 0
	25	0	-	_	4	0	0	-	0	ĸ	0	0	0	0	7	0	0	0	0	ĸ	7	0	0		0	0	0	0	9	00
	24	0	_	0	0	0	0	0	0	_	0	7	4	4	0	0	0	0	4	0	c	0	0	-	0	0	0	0	4	0 0
	23	7	0	0	0	0	4	0	3	0	0	7	0	0	0	_	0	3	0	0	_	4	0	0	0	0	4	0	0	0 0
	22	4	0	0	ĸ	_	0	0	0	0	0	0	m	_	0	С	¢	0	_	С	9	0	C	rc,	7	=	=	=	=	==
	21	0	0	0	4	0	4	0	0	0	0	0	4	0	0	0	c	m	0	0	-	_	=	~	=	0	7	0	=	- ~
	20	0	0	0	0	4	7	0	0	0	0	0	0	9	0	0	0	0	0	0	0	c	C	ব	C	=	7	0	С	၁ ဇ
	19	0	7	_	0	0	m	m	0	c	0	0	С	0	0	0	0	0	0	_	0	0	0	'n	0	c	=	=	7	c ~
	18	4	0	0	0	Ş	8	0	0	0	0	0	0	0	0	0	0	0	0	0	0	4		0	0	0	0	0	0	7 V
	17	0	0	0	0	0	S	_	0	0	0	0	9	0	0	0	0	0	0	0	0	0	0	0	'n	m	0	0	7	00
	16	9	0	0	3	0	0	0	0	0	0	0	0	3	0	0	9	0	0	0	0	0	0	_	0	'n	0	0	0	c
þ	15	0	0	7	0	0	0	0	0	7	0	0	0	c	رح,	0	c	7	0	0	C	C	=	=	=	0	rr.	ي		= =
Period	14	0	0	0	0	0	0	0	7	0	0	_	4	0	0	0	0	m	С	0	0	0	0	0	S	С	7	0	0	2 5
	13	0	0	0	0	0	0	0	0	3	4	0	5	0	0	0	0	0	2	0	0	0	0	0	C	0	0	7	رد .	-1 —
	. 7	0	0	7	7	0	0	0	0	7	0	0	Š	0	_	0	0	0	0	7	0	0	0	0	0	0	4	(۲,	С	O 15
	-	İ							0								6	0	9	m	0	0	0	0	7	0	_	0	0	00
	10								0																		0	0	0	00
	9 1		7						7			0	_	_	_	_	`	_	_	_	·		=	_ _	_	_		را 	_	
	8	0		_	_	~		·	_	_) =		_	_	_	٠	_	_	_	_	_	_	2	_		c-1	_	
			_	7	_	_			_			. 2			_	_	_	_		_	_	_	_	_	-	_	0		_	
	7								_								÷	4	4					÷				_	_	
									0													_							_	
	S								3																					- -
	4	0	4	0	0	0	0	0	0	4	"	0	0	0	0	_	0	0	3	0	0	7	0	0	0	7	7	0	C	m O
•	3	0	0	0	0	_	5	0	0	0	0	9	0	0	0	0	6	0	0	0	0	0	0	0	0	0	0	0	0	m 0
	7	0	4	0	0	0	0	0	0	0	Ś	0	7	=	0	-	0	া	C	C	0	Ξ	=	=	Ξ	rc.	=	v.	=	===
	_	0	0	0	0	4	0	0	ιν,	0	-	0	۲۲,		С	С	9	0	C	0	0	С	=	=	=	=	0	=	ی	3 3
	Product	_	2	m	4	5	9	7	«	6	01	=	12	13	14	15	_	2	۳,	ব	'n	9	7	×	6	01	=	12	23	<u> </u>

	30	4	0	9	0	0	0	0	7	0	0	0	0	0	0	C	ŗ	√	> <	; c	0	0	0	ন	_	0	0	0	Ś	0	0
	29	0	0	0	"	0	0	0	0	0	_	4	С	ব	0	0	5	. "	, 5		. =	=	C	=	C1	Ξ	┱	Ξ	Ξ	Ξ	Ξ
	28	0	0	0	9	0	0	0	0	_	C	0	Ś	0	0	=	=	; c	o rr	· c	7	=	С	_	=	=	С	=	S	=	=
	27	0	0	ж	0	7	c	0	0	_	0	0	0	~	0	С	<	· –	7		0	c	0	0	0	m	=	4	С	=	-
	26	0	0	0	0	0	7		7	0	0	7	0	0	0	0	0	· c	7		-	0	4	0	0	_	С	0	С	_	0
	25	0	0	0		0	5	0	0	_	0	0	0	0	4	_	c	· C	~	0	0	0	0	0	0	0	'n	0	4	0	~
	54	0		0	0	0	9	0	0	0	0	S	0	0	0	0	-	· C	· -	,	Ś	0	7	0	4	0	0	0	0	0	0
	23	0	_	_	0	0	0	0	0	0	0	0	7	~	κ	7	C	· c	· -	· c	0	0	0	0	4	0	رد,	7	0	(1)	0
	22	7	0	0	0	0	Ś	0		0	0	0	7	7	0	0	"	, =	: 7	· c	0	rc,	c	=	Ξ	0	Ξ	=	=	=	C
	21	7	0	0	0	_	0	0	0	7	0	0	0	0	7	0	C	· C	· C	· •	0	7	С	0		0	0	ব	10	=	=
	20	0	S	0	0	0	0	0	0	0	7	0	0	0	0	0	-		· c	Ç	0	0	0	0	_	С	m	7	0	С	Ś
	19	0	0	0	0	0	0	0	0	0	0	Ś	0	0	0	7	C	ی د	· ~	0	0	0	0	117	0	0	_	0	c	С	=
	18	0	0	0	0	0	4	0	7	0	_	0	0	0	Ś	0	C	· C	· C	0	0	0	4	0	0	0	0	0	С	Š	"
	17	0	_	0	0	0	0	0	0	0	9	0	0	0	<u>ب</u>	0	_		· C	৵	4	0	0	0	0	7	0	_	0	c	0
	16	_	7	0	7	7	0	0	0	0	0	7	0	0	'n	0	_	· C	C	0	0	0	0	_	c		C	S	۲۲,	0	С
po	15	7	0	S	0	0	0	С	0	_	_	=	С	0	0	cc,	=	0	=	_	\approx		Ξ	er.	_	C)	Ξ	=	-7	=	Ξ
Period	14	0	0	0	0	0	0	0	0	ব্য	0	7	4	С	0	0	0	0		=	0	=	С	С	۲۲,	=	=	0	=	=	c
	13	0	0	5	4	0	0	0	3	0	0	0	0	0	0	0	0	С	0	4	0	0	0		4	0	0	С	0	0	۲۰,
	12	0	0	0	3	0	7	-	3	0	7	0	0	_	0	0	0	0	0	ব	0	4	0	0	0	0	0	0	4	0	0
	=	0	0	4	0	7	0	0	0	0	0	0	_	Ś	0	0	C	m	0	_	0	0	0	0	0	0	'n	0	0	0	ст,
	10	0	2	0	~	0	0	0	Ş	0	0	0	0	_	0	0	0	0	0	0	0	Ś	0	m	_	0	0	0	0	0	m
	6	0	0	0	7	0	0	0	0	Ś	0	ç	0	0	7	0	0	0	0	0	0	9	0	0	0	0	0	7	0	0	4
	∞	m	0	0	0	0	0	0	0	0	0	0	0	7	7	С	=	=	=	0	=	=	۲۰.	=	-	Ξ	Ξ	=	C)	cc.	=
	7	0	0	0	0	0	0	-	_	Ş	0	0	С	_	0	4	'n	0	'n	С	0		0	C	0	_	=	0	=	=	0
	و	0	0	0	0	2	0	0	0	0	0	'n	0	0	_	_	0	0	0	0	0	7	0	S	C	0	0	(()	0	~ 1	=
	S	0	0	0	0	7	0	9	0	0	0	マ	0	0	0	0	0	ĸ	0	0	0	0	0	0	0	7	9	0	0	_	0
	4	4	0	0	4	0	0	-	0	0		0	0	7	0	0	0	"	0	0	۲۲,	=	0	0	0	7	=	C	C	С	7
	<u>س</u>	0	0	_	0	0	7	7	0	0	0	4	0	0	0	٣	4	0	7	0	æ	0	0	0	0	0	0		0	0	0
	7	0	4	0	0	0	0	0	0	0	0	7	9	0	0	0	0	0	0	0	С	0	~	0	0	9	C	=	С	=	7
	-	0	m	_		_	ব	-	0	0	0	0	_	0	0	=	С	7	=	=	17.	=	=	Ξ	=	Ξ	=	=	•	C 1	=
	Product	_	7	m	4	5	9	7	∞	6	01	=	12	<u></u>	7	15	_	7	m	4	S	9	7	×	6	2	_	12	<u></u>	<u>크</u> :	<u></u>
	_																														

		ı																													
	30	9	0	7	_	0	0	0	0	0	0	ĸ	0	0	0	0	0	0	· C	0	0	0	0	4	0	0	œ	О	0	0	0
	29	0	0	0	0	0	0	0	7	4	0	'n	0	0	ιņ	0	C	· C	· C	0	7	0	0	0	n	7	С	0	0	0	0
	28	0	0	0	0	9	0	_	0	0		0	7	С	7	0	C	: =	~	ı ro	=	=	=		=	=	S	=	=	Ξ	=
	27	0	0	0	0	0	-	7	0	0	0	0	m	0	9	0	0	· c	- 60	٦ ،	0	0	0	Ś	0	С	0	0	7	С	0
	56	_	0	5	-	0	3	0	0	_	_	0	0	0	0	0	C	· '^	'n	0	0	0	0	0	С	0	c	7	=	C	=
	25	0	0	0	ю	0	0	3	0	0	0	7	0	0		m	C	~	0		0	С	0	7	9	_	0	c	=	0	С
	24	0	0	0	m	0	-	0	7	0	7	0	4	С	0	0	S	· C	C	0	0	С	Ç	0	_	С	7	=	0	=	er.
	23	0	0	7	0	0	0	0	0	0	œ	0	7	0	0	0	c	· C	0	0	0	4	0	0	0	4	0	0	0	7	7
	22	7	4	0	0	4	0	0	0	0	0	0	0	0	0	7	4		0	0	0	'n		0	0	_	0	_	0	0	0
	21	0	0	0	0	0	0	7	0	0	4	0	9	c	=	=	0	· =	=	=	=	7		=	=	=	=	Ξ	=	C 4	د ۱
	20	0	0	0	7	0	7	0	0	0	0	7	0	0	0	9	0	· C	0	0	С	c	9	0	0	С	_	=	=	=	'
	19	0	0	5	0	0	_	0	_	0		0	0	0	4	0	0	0	0		0	С	9	0	_	0	0	0	~	~1	0
	81	0	0	0	0	7	0	0	0	0	_	0	0	4	0	5	0	0	_	0	0	0	0	0	~	0	0	0	S	0	ব
	11	0	3	0	3	0	0	0	0	0	0	4	0	_	0	_	~	. 0	_	_	5	_	0	0	0	0	0	_	0	0	0
	. 91	0	0	0	0	_	7	0	0	0	0	0	33	0	4	7	(*)	0	0	0	0	0	3	3	0	0	0	3	0	0	0
_	15								9			0			0	0	0	0	0	0	0	0		0	0	0	3	∞	0	0	С
Period	14								0							2	0			7							~ 1				C I
	3								0						_	_	0	=	0		m,				_						=
	2 1				0				7			~		_	_	_	_		_		0		7						_ _	_	_
														Ŭ	7	_	_	_	_	0	_	_			_	· =	_		_ _	~	
	_								0							0	_	_								-1	_	_	_	_	_
	2								0						0	_	0	0		0				(L)		_	-		···.	_	_
	6	7	0	0	7	5	0	0	7	0	0	0	0	0	_	0	0	0			0		_	c		_	0			0	0
									0											0											
			4	_	0	С	0	C	0	S	С	C	-	_	=	C	ব	2	Ξ	0	0	=	=	=	=	=	=	=	C)	7	=
	9	0	0	3	co	_	0	S	0	0	0	0	0	0	0	0	0	m	_	۳,	cc,	0	0	=	C	0	-	7	C	=	С
	5	0	_	0	7	9	0	0	"	0	0	0	0	0	0	0	0	0	0		0	0	_	S	-	С	0	C	0	S	С
	4	0	0	0	0	-	7	c	_	0	0	0	0	0	0	0	0	0	0	4	m	0	7	_	0	0	-	-	С	7	=
	m	0	_	0	4	0	0	0	0	0	0	0	0	_	m	m	0	0	0	0	ω	0		0	0	ω.	0	0	C	· ^	0
	7	S	0	0	0	0	m	4	0	0	0	0	0	0	0	0	0	'n	0	0	0	7	0	0	_	0	0	0	4	<u> </u>	0
	-	0	0	0	33	0	7	0	0	_	0	0	0	7	0	4	m	7	0	0	0	0	4	0	0	ر ب	0	0	0	0	0
	Product	_	7	æ	7	'n	9	7	×	6	2	=	13	<u>~</u>	<u>寸</u>	5	_	7	rr,	7	S	Ç	7	×	S .	<u> </u>	= :	7	<u>~</u> :	- :	<u>_</u>
	1																														

																															ı
	30	2	0	0	3	0	7	0	0	0	0	0	0	0	0	0	C	٠,	· C	0	0	0	0	0	9	0	m	0	0	0	0
	29	0	0	4	0	0	9	0	0	0	7	0	0	0	0	0	C	0	· C	0	9	0	0		0	0	7	0	0	ĸ	0
	78	0	∞	0	0	0	0	0	0	m	0	0	0	0	_	0	C	0	· C	0	4	0	0	_	0	0	7	0	0	0	0
	27	0	7	0	0	0	0	0	т	0	0	0	-	9	0	0	c	: c	· ~	4 🗢	=	0	=	=	9	С	=	=	=	=	7
	56	0	0	0	0	9	0	0	0	0	4	7	0	0	0	0	4	· c	<u> </u>	0	0	С	С	'n	0	С		=	0	0	7
	25	_	0	0	0	7	0	0	4	7	0	0	0	0	ĸ	0	,	ı 0	C	0	'n	0	0	0	0	0	0	0	4		=
	54	_	_	0	0	0	0	4	0	0	0	0	4	7	0	0	0	0	C	0	0	7	_	0	0	0	0	7	0	0	7
	23	0	0	c	7	0	0	0	_	0	0	0	7	0	0	4	C	0	· c	0	0	4	0	0		5	7	0	0	0	0
	22	0	0	4	0	3	0	0	0	7	0	7	~	0	0	0	_	· C	_	2	7	æ	0	0	0	0	0	'n	0	C	0
	21	0	7	0	0	0	0	0	0	_	Ş	0	4	0	0	0	-	٠,٠٠	C	- C	0	rr,	С	С	С	=	С	0	ব		=
	20	0	0	0	0	С	0	0	-1	=	=	С	0	=	7	7		. =	10	. =	=	c	c	=	=	=	ε	Ξ	Ξ	=	Ξ
	19	_	7	_	_	0	0	0	0	0	0	0	_		0	С	=	: 0	_	: ~	0	c	=	=	=	7	=	ۍ	=	_	-
	18	0	0	0	0	0	0	0	0	0	7	0	ς.	7	0	-	=	· -	_	; m	0	C	0	0	0	7	0	c	'n	=	=
	17	2	0	0	0	7	0	0	0	0	0	0	0	0	0	0	0	·	· -	0	0	0	0	4	0	4	0	0	(۲,	С	0
	16	3	0	0	7	0	0	0	0	0	0	0	0	_	0	9	C	· C	_	0	~	3	0	7	0	0	0	_	0	0	3
þ	15	7	0	0	0	7	0	4	0	0	0	4	0	0	0	0	0	· c	(۱ —	0	0	0	0	0	5	0	0	4	0	0
Period	14	c	0	_	7	0	_	_	0	0	0	-2	0	0	0	0	0	· c	· c	0	c	7	С	=	_	С	Ξ	0	=	7	V.
	13	0	0	0	0	0	0	4	7	0	С	0	0	0	~1	ন	0	=	_	- cc.	=	Ξ	=	=	=	~ 1		17.	=	=	=
	12	_	7	0	0	0	7	0	3	7	0	0	7	0	0	0	c	· •	0	: c	0	0	4	С	С	0	7	S	=	0	=
	11	0		0	0	0	4	0	9	0	0	0	0	0	_	0	C	· 0	~	10	0	0	Ś	0	С	0	C	ব	_	C	=
	10	_		0	0	0	_	0	4	0	0	Ś	0	0	0	0	0	্ব	0	9	0	0	0	С	0	0	0	0	0	0	7
	6	0	0	0	0	0	0	0	7	0	0	0	0	7	0	m	0	, (r	· C	0	0	0	0	7	4	0	0	0	ίς,	0	0
	8	7	0	0	0	0	0	0	0	0	0	0	0	0	0	S	0	· (*)	_	0	0	0	_	0	0	0	0	4	0	4	٥
	7	0	0	7	_	0	7	0	0	y	_	c	0	=	=	=	7	. =	=	; cc.	=	_	=	=	_	=	Ξ	Ξ	=	=	=
	9	0	0	0	_	0	0	rc,	∞	c	c	=	-	=	=	=	^	1 -)	=	: =	=	=	=	=	_	=		7	=	Ξ	=
	5	0	0	0	2	0	0	0	0	7	0	۳,	0	0	'n	0	,	ı c	_	. 0	0	'n	С	0	С	С	0	0	0	۲۲,	2
	4	0	0	7	7	0	0	0	0	~	0	0	0	0	Ş	0	<u> </u>) 1		0	0	7	7	0	0	С	0	C	0	ব	_
	3	3	0	0	0	0	0	_	0	0	0	0	0	~	0	5	_) (C	۰, ۰,	, O	m	0	_	0	0	0	0	0	7	0	0
	7	0	0	0	0	0	6	7	0	0	0	_	0	0	0	0	_				0	Ŋ	0	0	0	0	m	0	0	0	
,	_								0						_		C	· c	,	2 2	0	0	7	9	0	0	0	0	0	0	0
																															Ì
	Product	_	7	m	4	5	9	7	œ	6	01	=	12	<u></u>	7	15	-		"	. च	171	Ç	7	×	6	2	=	<u></u>	<u></u>	<u> </u>	<u>C</u>

Table B.8 Demand data set 8: Large problem size, lumpy demand, high utilization

	30		_	4	0	0	0	_	5	0	0	5	0	_	0	0	<	>	0	0	<u>8</u>	0	0	0	0	0	0	С	С	0	0	0
	29	0	0	0	0	0	4	0	0	_	m	"	0	0	7	0	<)	_	0	0	0	۲۲,	7	0	0	7	0	0	9	0	7
	28	5	0	0	0	4	0	4	0	0	7	С	m	0	С	0	r	_	0	0	4	-	0	9	0	С	=	С	С	=	0	0
	27	0	4	_	7	-	Ş	0	0	0	0	0	'n	0	С	С	-	1	0	С	С	4	0	C	1	ব	=	C	С	=	∼ 1	C
	26	0	0	2	0	0	0	Ś	0	0	0	0	0	S	0	ĸ	r	n	0	С	0	0	С	_	0	0	0	0	0	9	च	ব
	25	0	-	0	×	0	0	_	0	7	0	0	0	0	0	_	r	7	0	0	9	0	0	0	0	0	0	0	4	0	0	S
	24	m	0	0	0	0	0	0	4	m	0	0	9	7	0	0	<	>	0	'n	_	0	0	7	0	4	0	_	0	С	0	0
	23	0	0	0	Ξ	0	0	0	0	0	0	0	С	7	0	0	r	r,	(ب)	9	0	0	_	0	С	7	0	0	0	0	4	C
	22	4	0	0	0	0	0	0	4	7	_	0	0	0	7	0	c	7	(ب)	0	m	0	-	0	Ś	С	4	0	0	С	0	0
	71	0	0	0	0	2	0	0	7	7	0	0	0	4	0	0	<	>	0	∞	0	9	0	0	0	7	0	0	7	0	0	=
	20	0	0	0	0	m	-	0	0	0	0	7	0	7	'n	0	<	=	С	7	0	0	С	0	ব	С	С	=	С	С	0	7
	9	0	0	0	0	0	ĸ	Š	0	m	'	0	7	0	0	0	<	> -	9	0	С	ĩ	С	С	=	С	С	С	=	0	0	=
	18	0	∞	0	0	0	9	0	0	0	7	7	0	0	0	0	C	>	0	S	0	0	7	О	С	0	0	×	-	C	0	7
	-	0	0	0	0	7	0	9	0	4	0	0	0	0	9	0	C	>	0	-	0	'n	=	r٠,	_	_	=	7	rr.	=	=	7
	91	0	0	0	0	0	0	0	0	0	4	0	9	(~)	0	Ś	-	7	С	С	7	С	ব		0	C	Ξ	Ξ	-	=	9	C
Period	15	0	0	0	0	0	0	0	0	0	0	œ	0	7	0	ľ	<	>		С	0	9	0	0	0	0	С	4	-	=	4	7
Pel	14	0	0	0	0	0	0	0	∞	0	0	0	10	0	0	0	<	>	7	7	0	0	ις,	0	4	0	0	'n	С	-	0	_
	13	9	0	7	3	0	0	0	0	0	Ś	-	0	-	0	0	7	9	0	'n	0	=	С	'n	С	=	Ξ	С	\sim 1	Ξ	0	=
	12	0	0	7	∞	0	0	0	-	0	0	0	4	0	7	-	c	>	0	0	0	9	О	0	0	0	_	0	0	0	9	1/1
	Ξ	5	7		7	0	0	0	7	7	0	7	0	С	0	7	<	>	0	_	0	С	9	С		0	0	cc,	=	c	0	7
	2	S	0	m	-	_	0	0	0	0	0	'n	0	C	_	7	C	>		0	С	9	9	0	С	0	=	C	=	10	0	=
	6	m	0	7	0	0	S	4	0		0	0	0	ĸ	0	0	<	>	0	0	7	С	0	0	×	_	0	С	C	7	0	0
	∞	0	4	0	'n	0	-	0	0	0	0	m	0	0	'n	0	-	1	'n	0	0	0	0	0	0	0	0	9	С	cr,	0	0
	7	7	0	Ś	0	0	0	0	0	0	0	-	-	0	0	4	<	>	0	0	7	0	0	0	4	7	Ś	0	0	0	0	0
	9	0	_	Ś	0	9	0	С	7	0	0	0	0	0	च	=	3	=	=	0	۲۲,	-	=	Ξ	=	=	=	7	7	=	=	Ξ
	5	01	0	9	0	0	0	0	С	0	0	0	С	С	7	0	5	>	C	-	С	-	C	'n	=	=	ব	С	' C'	=	=	7
	4	0	0	7	9	0	0	Ś	0	0	4	0		0	0	0	7	1	0	0	C	С	-	=	С	С	9	=	=	ici	~1	c
	3	0	0	0	0		0	4	9	در,		С	-	7	С	0	5	=	0	=	=	=	=	C	×	ĸ.	-1	=	=	=	0	rr.
i	7	4	0	0	0	0	0	9	С	0	0	С	'n	C	"	0	<	>	0	С	বা	С	=	C	C	ন	c	=	'n	=	'n	=
	-	0	0	0	7	0	7	0	0	0	7	0	0	0	0	7	r	7	0	0	0	0	-	0	0	0	50	~	С	7	9	0
	Product	_	2	ю	4	5	9	7	×	6	10	=	12	13	7	15	-	-	7	٣,	ব	'n	y	7	×	0	01	=	12	<u></u>	14	<u></u>

		ı																														
	30	0	0	0	7	0	0	0	0	4	0	0	0	0	7	0	(_	0	'n	7	0	7	0	0	0	0	0	0	0	С	0
	29	0	0	0	0	0	0	0	0	0	7	m	0	0	'n	Š	(>	0	0	4	4	m	0	0	0	0	5	0	0	7	0
	28	∞	0	0	0	0	0	0	0	Э	0	7	0	0	0	0	Ó	0	0	0	0	0	0	3	0	0	7	_	4	0	0	m
	27	0	0	0	0	c	0	0	0	9	Ś	0	7	0	7	0	(7	κ,	0	0	4	٣,	4	_	0	0	0	_	0	0	0
	56	0	0	۲۲,	0	"	0	0	9	0	c	0	0	4	7	=	•	~1	=	=	_	=	=	=	~ 1	_	=	=	C1	S	7	=
	25	0	0	0	0	7	0	0	0	0	0	0	4	'n	7	¢	,	~!	cr,	ব	c	0	rr,	=	=	0	=	\sim 1	⇒	=	=	=
	24	0	0	0	9	0	4	0	0	4	0	0	7	0	_	_	:	>	0	'n	0	=	(۲)	=	c	_	0	0	\sim	_	ㄱ	7
	23	-	5	0	0	0	0	0	'n	_	0	0	7	0	_	0	c	> -	0	0	9	0	7	С	0	4	С	С	_	Ś	0	0
	22	0	4		0	0	4	0	0	0	c	0	0	0	0	9	c	-	0	0	0	_	7	Ś	7	0	7	9	0	0	0	0
	21	0	0	0	0	0	9	∞	0	0	0	0	0	4	0	0	<	-	0	0	0	0	0	0	0	0	7	4	0	0	0	7
	20	0	0	4	0	0	0	0	7	0	0	7	0	0	0	0		7 '	0	0	0	0	0	0	9	0	Ç	7	0	7	7	0
	19	0	0	0	0	0	0	0	0	0	٠٠,	×	۳.	ا ت	0	0	١,	C)	=	=	=	ي	=	=	L-I	_	=	Ξ	=	7	=	Ξ
	18	0	∞	0	4	0	0	0	0	0	0	0	9	0	0	0		-	رب	7	Ś	С	0	С	С	4	ব	=	=	=	=	Ç
	17	5	_	0	4	7	0	0	0	0	0	9	0	0	0	0	-	7 (0	0	~	0	0	0	0	0	0	0	C	マ	7	9
	16		9	0	4	0	0	0	7	0	0	0	0	'n	0	0	r	_ ,	0	0	0	0	-	0	0	0		4	_	0	_	7
	15	0	0	0	0	0	7	0	0	0	0	0	0	∞	0	3		.	7	9	9	0	0	0		0	0	0	0	0	m	0
Period	4	0	0	7	0	0	0	0	5	0	5	0	0	9	0	0		.	-	0	0	0	9	7	0	0	5	0	0	0	0	0
	2			_					7								_	o (_	0	0	4	-	7	0	0	S	Ç	0	0	0	_
	2								C				S			=	_		=	_	50	÷	÷		=	er.	=	=	=	C I	re.	=
									0						0	_	1,	·	_	_	_	~		C	0	a	0	=	=	7		'n
	0								0							0			_		-						_				· =	'n
	9	0							0					~	٠.	_	_	- 	_	_	_	·	_	~					_ _	_	_	
														°	٠,	_	_		_	_	_	_	_	···	~,				_	7) (_
									0																							
									0																					_		
									7																					С		
	2								0																	rc,				Ξ		Ξ
	4	0	0	0	0	0	0		0	_	7	0	7	4	0	m	<	> c	~	_	0	0	9	ব	С	С	=	С	_	ব	0	=
	3	0	7	0	3	0	_	0	cc	9	0	0	0	0	0	C	C	> :	2	œ	0	С	0	0	С	0	0	С	C .	0	0	0
	7	7	0	0	'n	0	4	0	4	0	7	0	-	0	0	0	C	> <	0	0	m	0	0	7	S	0	-	_	4	0	7	0
	-[4	0	0	0		7	0	0	0	0	0	2	0	_	0	"/	n (>	0	"	0	0	0	0	0	0	0	r~,	0	0	7
	Product	_	7	3	4	Ś	9	7	8	6	10	Ξ	12	13	7	15	-	- (7	rr,	ঘ	'n	9	7	×	6	0	=	12	<u> </u>	<u> </u>	2

Period 12 13 14 15 16 17 18 19 20 21 22 23 24 2 0 0 0 0 0 0 4 0 7 0 0 0 0 0 0 0 0 0 0 0	30	2 2	0	0	0	4	0	0	0		0	9	0	0	'n	0	"	,	· c	, _	0	m	0	0	_	"	0	0	_	0	0
Period 9	20) 	9	0	0	0	7	0	0	0	0	0	0	S	0	0	-	· ·	, c	4	0	9	0	0	0	c,	0	0	С	0	0
Period 9	28		0	8	0	0	4	9	0	0	0	0	0	0	0	0	C	٠ -	· c	0	0	0	_	'n	9	0	0	0	0	4	0
Period 9	27	. ∞	0	0	0	_	0	0	0	0	7	0	0	7	0	0	0	· c	· '0	9	_	0	0	_	0	0	0	S	0	0	0
Period 9	92		0	0	9	0	0	5	0	0	0	0	Š	0	0	7	O	· c	· vn	∞	0	0	0	0	0	0	0	0	_	71	0
Period 9	25	4	9	0	0	0	0	0	(1)	0	0	0	m	7	0	С	0	· C	· C	ব	~1	9	=	cc,	٠٠.	Ξ	=	=	=	=	=
Period 9	24		0	0	0	0	0	0	m	0	4	0	7	9	7	_	C	· c	: [7	7	0	0	C	0	ίς,	С	"	0	0	0	7
Period 9	23		0	0	0	æ	0	0	4	0	0	0	9	_	0	4	"	, ("	. 0	0	0	0	C		0	0	0	7	С	"	_
Period 9	22	0	0	0	7	0	0	0	0	0	0	7	0	7	0	7	C	· C	. 7	0	0	0	۳,	0	"	در،	-	7	κ,	7	0
Period	21	0	0	9	∞	0	0	4	0	0	0	0	0	0	0	0	7		0	0	0	0	0	С	_	4	-	0	0	আ	7
Period 8 0 0 0 2 0 0 3 5 0 0 11 12 13 14 15 16 17 18 8 0 0 0 0 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0	20	0	0	3	0	0	0	0	0	0	7	0	'n	4	٣,		c	· C	0	5	0	7	0	0	С	7	۲۲,	cr,	С	۲۲,	c
Period Period 9	19	7	0	0	0	0	0	0	0	0	ις,	0	_	_	0	9	"	. =	rr,	9	Ç	Ξ	-	=	=	Ξ	Ξ	C-1	Ξ	=	=
Period 9	81	0	7	0	0	0	0	0	'n	ব	0	·^	С	0	С	7	C	ی	- C	0	=	=	С	=	=	~	=	=	Ś	cc.	~1
Period 9	17	4	_	0	3	0	4	S	0	0	0	0	0	0		0	0	· '^	7	0	0	0	0	0	m	0	0	0	С	0	"
Period 9	16	0	0	0	4	0		0	0	0	m	0	0	7	∞	0	0	· C	0	0	0	0	7	С	_	C	۲.	С	0	0	7
1 2 3 4 5 6 7 8 9 10 11 12 13 8 0 <td>15 ⁸⁴</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>9</td> <td>0</td> <td>0</td> <td>5</td> <td>Ś</td> <td>0</td> <td>7</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td>7</td> <td>9</td> <td>0</td> <td>0</td> <td>_</td> <td>7</td> <td>0</td> <td>0</td> <td>5</td> <td>7</td>	15 ⁸⁴	0	0	0	0	9	0	0	5	Ś	0	7	0	0	0	0	0	0	0	0	0	7	9	0	0	_	7	0	0	5	7
8 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Peric 14	0	0	7	0	0	_	0	0	3	0	4	33	0	0	0	7	0	7	0	0	0	0	0	С	0	4	C	v)	Ç	C
1 2 3 4 5 6 7 8 9 10 11 2 3 4 6 5 7 8 9 10 11 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	13	0	0	0	_	0	0	_	3	0	0	0	4	0	33	9	0	0	0	0	_	_	0	7	0	0	7	0	С	0	7
1 2 3 4 5 6 7 8 9 10 1	12	0	_	9	0	0	7	С	7	Ş	0	0	0	0	C	c	С	7	cc.	=	0	ır,	=	Ç	cc.	=	Ξ	_	Ξ	=	Ξ
1 2 3 4 5 6 7 8 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	Ξ	5	_	0	0	9	0	7	0	0	7	_	С	~	c		0	0	0	c		4		ব	=	С	×	=	=	=	0
1 2 3 4 5 6 7 8 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	10	0	0	7	0	0	0	0	0	4	0	0	0	0	_	9	0	00	"	0	0	ςς,	0	_	0	0	ι.,	0	0	0	С
1 2 3 4 5 6 7 7 8 8 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	6	0	0	9	4	0	0	0	0	0	œ	0	С	0	0	0	'n	0	С	0	m	С	' C'	0	C	=	7	C	۲۰,	c	=
1	∞	0	5	0	0	0	0	0	7	0	Ş	9	0	0	0	0	_		"	Ś	0	0	С	C	'n	0	0	cc,	=	=	С
1	7	0	33	S	0	7	0	_	0	0	0	0	0	7	0	0	0	0	0	۲۲,	0	_	'n	C	-	9	cr,	C	=	=	=
1	9	0	0	0	0	9	0	S	0	7	0	0	0	0	0	0	0	S	۳,	0	0	0	0	0	7	9	0	0	7	0	0
	5	7	0	0	0	ж	_	0	0	С	c	7	С	0	co,	50	c	0	С	Ξ	=	া	=	S	=	Ξ	v,	=	=	rr.	Ξ
1 8 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	4	0	7	0	0	0	0	0	0	4	Š	0	4	C	_	7	С	С	c	=	=	0	C	7	0		0	-1	\sim 1	ব	v.
800000000000000000000000000000000000	<i>.</i> س	0	0	7	0	3	7	0	33	0	0	0	۳,	0	0	0	0	4	0	m	0	0	0	9	7	_	0	0	0	0	0
	7	0	0		4	0	0	4	Ś	7	7	0	0	0	0	0	0	0	0	7		0	0	7	0	'n	0	9	С	0	7
Product 1 2 3 3 4 4 4 4 7 7 7 7 7 7 7 7 7 7 7 7 7 7		∞	0	9	0	0	0	0	0	co	0	0	0	0		0	9	4	0	0	7	0	0	0	0	0	-	=	9	0	C
	Product	-	7	က	4	S	9	7	œ	6	10	=	12	13	14	5	-	7	т	4	5	9	7	∞	6	10	_	12	<u>~</u>	1	15

	ای		_	~	_	_	_	_	_	_	_	۰,		_		~		_	_	_	_	_	_		_	_	_			_		_
	[]									0								د												0 0		2
	``	0	0	0	4	0	0	9	0	0	0	7	0	w	m	0	•	4	0	0	9	4	0	0	0	0	0	4	C 1	0 (0	=
	78	0	0	0	4	0	0	7	0	0	5	0	0	m	0	4	(9	0	0	c	7	7	0	_	0	ব	0	'))	0 1	^
	27	S	0	0	0	0	4	0	7	7	7	m	0	0	0	0	(9	0	4	0	0	4	3	0	0	_	0	0	0	o \	၁
	56	S	0	0	0	3	0		0	2	0	0	0	_	33	0	(9	0	0	n	0	4	0	9	0	0	0	S	0	0	>
	25	_	_	Ś	0	n	'n	0	0	_	0	0	0	7	0	0			0	9	0	0	0	С	ব	С	0	CI	=		च :	=
	24	0	0	0	0	0	0	n	0	'n	0	m	2	7	0	7		0	0	7	4	0	0	0	7	4	0	-	0	0	0 (=
	23	7	0	0	0	0	0	0	0	0	7	0	9	0	∞	0		0	0	0	0	_	0	'n	7	0	0	0	9	0	c (7
	22	0	0	9	7	0		4	0	0	0	0	0	0	0	0		0	0	0	4	0	_	4	0	0	7	0	7	0	C (-
	21	0	~	0	0	0	0	0	0	0	0	9	0	6	0	0	,	9		0	0	_	0	0	4	0	0	0	0	9	0 (0
	70	0	0	7	0	0	0	0	9	_	0	0	7	7	0	0		0	0	0	0	0	0	0	0	0	r	7	0	9	0 (~
	19	0	7	∞	_	0	4	0	0	0	0	0	0	0	0	ж		0	0	7	0	0	0	0	7	0	0	0	7	۳,	(n)	_
	18	0	0	7	0	0	0	0	۲۲,	0	_	C	7	0	'n	С		0	-1	0	0	-	С	Ξ	9	=	7	=	=	Ξ	=	=
	17	0		0	0	4	0	0	9	0	0	7	0	0	0	C		_	0	0	۲۲,	=	0	0	0	0	0	0	۲۰,	С	<u>ا</u>	=
	16	0	0	0	0	0	7	0	0	0	0	∞	7	0	9	0		0		0	0	0	0	С	Ś	4	0	0	c	_	7	=
Þ	15	0		0	0	0	0	0	0	0	7	0	9	0	0	4		0	4	0	0	0	7	9	0	_	m	0	0	7	0	0
Period	14	0	0	0	_	5	0	4	0	3	0	0	0	0	3	7		0		0	4	0	0	4	7	'n	0	7	0	0	0	0
	13	4	9	0	0	0	0	_	0	0	0	0	0	7	0	0		ω	0	Š	33	0	2	0	0	0	0	0	_	7	0	7
	2	0	0	4	3	0	5	0	0	0	S	0	0	0	0	_			0	0	0	0	7	9	0	4	0	0	0	0	0	0
	_	4	0	0	0	7	7	7	0	4	7	0	0	0	0	7		<u> </u>	'n	۲۰.	-	rr,	Ξ	=	=	Ξ	=	er.	7	Ξ	Ξ	=
	10									0	0	0	0	9	0	3					0							С	·	2	œ	<u> </u>
	9 1									0								0			7									0		
	5	۵,	_	<u> </u>	_	_	_	_		_	~	_	~	_	_	_		_		_					_		_		_		_	_
		2	_		- 1	_			3	_	~	_		_	_	_		_	7		_	_	0	0	_	~	_	٠ <u>٠</u>	_	_	_	_
	7									0																				4		
	9									0																				0		
	S	0	4	С	0	2	0	7	-	0			4	0	0	0		0	0	'n	0	2	0	0	0	0	0	0	0	0	0	ı.
	4	ις,	"	· C	0	С	0	া	'n	C	C	=	۲.	=	=	С		=	=	7		Ξ	=	Ξ	Ξ	=	Ξ	Ξ	"	Ξ	v.	
ued)	Э	0	_	0	C	. C.C.	î O	0	· C	0	'n	'n	0		. (4)	0		<u>_</u>	0	'	0	_	0	С	0	1		С	v,	=	_	=
ontin	7	4	0	0	ی د	· C	0	0	0	0	0	0	0	00	0	0		0	0	С	0	0	0	_	0	0	œ	7	0	0	0	7
)) 8	,	0	С	· C	· C	° C	0	· C	ی د	2	4	_	0	0	-	4		9	0	С	7	∞	0	7	0	0	0	0	0	0	0	0
Table B.8 (Continued)	Product	1	2	۰ ،	4	- v-	n v	,	· ∝	6	10	=	12	<u></u>	<u> </u>	15		_	2	۰, در	. 4	v	9	7	00	6	01	=	12	13	14	15
		i																														

		1																													ı
	30	0	0	7	0	ς,	7	0	0	S.	0	ĸ	0	0	0	0	0	0	~	۳,	0	_	0	0	×	0	ক	0	0	_	0
	29	9	0	7	0	0	0	0	c	-	7	0	9	0	4	0	0	Š	0	0	0	4	4	0	0	0	0	0	Ś	0	0
	28	0	4	0	0	7	т	0	0	0	0	4	0	_	4	0	C	0	0	7	_	0	0	0	0	n	-	7	0	4	٥
	27	3	0	0	0	ж	0	5	0	r	0	0	4	0	0	0	(*)	0	0	m	0	0	0	0	0	0	9	0	0	4	7
	26	0	0	-	0	0	0	0	7	m	0	4	0	0	7		0	'n	9	0	0	0	0	С	0	0	7	Ś	0	0	0
	25	0	7	0	0	Ś	0	0	0	0	7	4	0	0	0	0	С	0	0	0	0	0	С	0	0	С	=	9	'n	7	С
	24	4	0	0	0		5	0	0	0	9	0	С	0	=	7	0	ব	c	_	=	c	=	=	Ξ	=	=	=	rc.	v,	٧,
	23	0	0	0	0	0	0	0	0	0	9	0	6	ĸ	0	0	7	0	c	0	0	0	0	0	_	0	0	∞	ব	0	0
	22	4	0	0	4	0	0	0	5	0	0	0	0	0	0	5	0	0	~	-	0	ĸ	0	0	'n	0	0	S	0	0	3
	21	0	0	0	_	0	7	4	0	0	0	0	0	_	2	0	Ś	0	0	0	_	0	0	0	0	0	Ś	0	0	9	-
	20	0	7	0	0	0	0	0	7	0	7	0	9	ю	0	3	0	0	4	0	0	0	9	0	0	0	0	4	0	(1)	-
	19	0	0	0	0	0	5	7	9	0	0	0	0	0	0	0	4	0	0	0	0	0	0	0	0	7	7	0	Ş	0	٥
	18	0	m	4	7	0	0	0	0	0	-	ĸ	5	0	0	0	0	0	0	0	0	0	0	6	0	0	0	C	С	0	٥
	17	7	7	_	0	0	0	m	0	0	0	С	C	С	0	c	C	7	7	'n	=	0	9	cr,	c	=	=	=	=	=	=
	16	5	0	0	_	9	0	0	0	0	0	0	_	0	7	m	0	С	0	0	7	0	С	0	4	ব	9	0	0	0	7
Period	15	0	Ś	0	7	0	0	0	0	0	0	0	0	4	_	9	6	0	0	4	0	0	0	0	0	4	0	0		0	٥
Per	14	0	0	0	0	0	0	ĸ,	0	7	0	œ	'n	0	0	0	0	0	4	0	0	0	0	7	Ś	0	0	0	0	0	Ŋ
	13	0	0	0	0	0	0	0	0	0	7	'n	9	0	'n	0	0	-	0	т	0	0	m	0	m	0	0	7	-	0	Ş
	12	0	S	0	0	9	0	0	0	0	0	0	Ś	7	0	0	0	0	'n	7	0	Ś	0	0	0	0	С		Ś	0	٥
	11	-	0	9	0	0	9	0	'n	0	0	0	0	0	0	0	0	'n	0	7	٣,	0	_	0	Ś	∼ 1	0	С	0	0	٥
	10	0	0	0	0	m	_	'n	0	0	'n	-1	0	0	С	0		0	С	С	'n	=	7	=	~ 1	'n	=	=	=	C1	-
	6	0	0	0	0	0	0	_	0	_	×	0	0	∞	0	0		œ	~	0	7	-	С	0	m	0	0	0	0	С	0
	8	4	0	0	0	0	0	0	0	4	0	4	9	0	0	0	7	0	0	0	4	9	Ç	0	0	"	0	С	0	0	٥
	7	0	0	0	0	5	0	0	9	9	_	0	0	0	0	0	0	0	0	_	7	0	7	0	0	0	0	_	7	0	0
	9	0	0	0	0	0	0	7	4	0	0	0	0	7	ς	0	4	0	S	0	0	0	0	4	0	0	0	0	'n	0	7
	5	2	5	3	0	0	∞	0	0	0	0	0	0	0	0	0	0	0	0	7	7	œ	0	0	7	m	0	_	0	0	0
	4	0	0	7	9	0	0	4	_	0	0	_	0	0	0	4	0	0	7	0	9	9	0	0	C	7	_	=	0	_	۵
(pai	3	0	0	0	3	0	7	0	7	0	0	7	0	0	С	4	0	0	0	0	'n	0	۲۲,	C	cc,	_	=	Ξ	=	S	=
ntin	2	3	4		_	0	0	0	0	0	0	0	9	κ,	0	0	0	0	ς,	0	0	0	4	7	0	0	0	0	0	7	7
8 (Co	1	0	0	0	0	0	0	0	0	0	0	8	0	0	0	0	0	0	0	0	0	0	0	ব	0	0	'n	С	0	6	٥
Table B.8 (Continued)	Product		7	٣	4	'n	9	7	∞	6	10	=	13	13	14	15	_	2	۲.,	4	'n	9	7	∞	6	0.	=	15	<u>"</u>	7	5
		•																													•

Table B.9 Setup matrix used for small size problems

			To Pr	oduct			<u> </u>
From Product	_ 0	1	2	3	4	5	6
0	0	0	0	0	0	0	U
1	0	0	3	5	4	2	2
2	0	6	0	1	4	1	1
3	0	2	6	0	1	1	6
4	0	6	4	4	0	4	I
5	0	3	5	6	4	0	4
6	0	1	4	6	5	3	()

Table B.10 Setup matrix for large size problems

To Product 1 2 3 4 5 6 7 8 9
0 0 0 0 0 0
0 3 5 4 2 2 6 1
6 0 6 4 4 4 1 3
5 3 0 3 6 3 5 6
4 4 2 0 3 4 6 3
1 2 6 2 0 2 2
5 5 3 1 5 0 1
5 2 2 2 1 6 0
3 2 1 4 1 4 1
6 5 4 5 5 5 5
2 6 1 2 2 3 5
2 2 6 4 5 2 1
6 5 2 4 6 2 6
3 5 1 1 2 6 2
1 4 6 6 2 3 6
6 1 6 5 4 1 5

APPENDIX C OUTPUT GENERATED BY ALGORITHMS

Table C.1 Experimental results

			Fac	tors								Repli	cation			<u></u>	
Α	В	C	D	E	F	G	Н	1	2	3	4	5	6	7	8	9	10
1	1	1	l	1	l	1	1	221	229	194	219	178	199	199	188	202	210
1	1	1	1	1	1	I	2	208	209	191	215	178	210	191	173	225	186
1	1	1	1	1	l	2	1	196	223	177	224	178	197	214	220	191	203
1	1	1	1	l	1	2	2	196	199	177	164	178	197	220	220	191	203
1	1	1	1	1	2	1	1	442	481	498	540	502	465	482	545	469	482
1	1	1	1	1	2	1	2	506	457	463	523	542	493	518	489	486	540
1	1	1	1	1	2	2	1	529	464	453	545	579	507	493	511	512	466
1	1	1	l	1	2	2	2	550	470	468	579	615	564	529	475	531	514
1	1	1	I	2	l	1	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	l	1	1	2	1	I	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	l	1	I	2	l	2	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	1	I	I	2	l	2	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	l	1	1	2	2	1	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	1	1	l	2	2	l	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	1	1	l	2	2	2	l	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
l	1	l	ì	2	2	2	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	l	ì	2	1	1	l	1	139	139	120	112	116	122	122	105	151	109
l	l	l	2	1	l	1	2	114	119	120	112	116	114	122	107	151	113
1	l	1	2	l	I	2	l	116	119	104	111	116	117	114	105	129	107
1	1	l	2	1	1	2	2	116	119	104	111	116	117	114	105	129	110
1	l	1	2	l	2	1	l	375	347	342	344	364	445	342	347	398	380
1	1	1	2	l	2	1	2	383	432	292	367	428	431	388	328	374	430
i	j	l	2	l	2	2	l	436	379	334	334	364	361	354	347	410	389
1	J	Ì	2]	2	2	2	433	357	334	334	364	440	354	332	410	369
I	I	l	2	2	I	1	l	INF	131	98	98	105	106	128	INF	97	93
1	i	l	2	2	1	1	2	100	131	98	98	105	106	128	114	97	93
1	1	Ì	2	2	i	2	ì	INF	155	98	124	111	109	128	INF	109	93
1	l	l	2	2	l	2	2	109	155	98	124	111	109	128	126	109	93
1	1	l	2	2	2	1	1	INF	464	368	409	345	INF	470	INF	341	333
l	1	l	2	2	2	1	2	404	469	564	432	363	446	470	440	394	361

	10	333	333	726	890	827	770	187	194	319	281	NF.	NF NF	R.	NF NF	INF	NF NF	NF NF	NF NF	480	460	463	451	478	597	762	651	N.F	Ę	NF NF	NF.
		368																													
	8	INF	387	870	834	910	892	2217	2126	2230	2326	INF	INF	INF	IN.	INF	INF INF	INF	INF	491	487	505	500	1748	1683	1887	1828	INF	ΙŻ	IN	INF
	7	470	470	848	818	939	867	2021	2120	2273	2107	INF	INF	INF	Ŗ	IN.	Ŋ	INF	INF	543	516	552	535	1811	2054	1826	1895	INF	INF	IŅ.	Ķ
ation	9	379	514	848	818	988	962	1973	2165	2322	2228	Ŗ	N.	INF	Ŗ	Ę	N F	IN.	N.F.	96†	479	491	†X†	1706	1713	1815	1808	Z.	N N	Z.	N.
Replication	5	354	390	864	861	1055	284	2172	2297	2475	2446	K	N.	IN.	Ė	ĮŅ.	Ė	Ė	INF	493	472	909	467	1586	1833	1854	1818	INF	INF	INF	IN F
	4	427	427	867	968	882	803	2180	2375	2429	2191	Ŗ	Į,	ĮŅ.	IN F	IN F	INF	INF	INF	518	469	471	468	1635	1803	1841	1864	IN.	INF	INF	Ν̈́
	3	368	368	840	817	803	797	2019	2224	2292	2319	ΪŞ	IN.	ĮŅ.	IŅ.	INF	Ę	IŅ	IŅ.	509	522	528	208	1699	1701	1680	1632	ĮŅ.	ΡŅ	INF	INF
	2	503	509	816	809	952	196	2180	2332	2375	2421	INF T	INF	INF	INF	INF	INF	ΙΝΉ	INF	558	534	570	999	1754	1871	1800	1741	N N	N.	N.	<u>L</u>
	1	ΝΉ	413	833	829	885	856	2181	2216	2121	2201	ĮŅ.	Į.	ЫŖ	INF	ĮN.	Ŗ	Ŋ	IN.	494	494	498	484	1486	1598	1648	1738	INF	INF	INF	INF
	πļ	_	2	_	2	_	2	_	7	_	2	_	7	_	7	_	2	_	2	_	7	_	2		7	~	2	_	2	_	2
	ت	7	7	_	-	7	7	_		7	7	_	~	7	7	_	_	7	7	_	_	7	7		-	~	7		_	7	7
	Ĺ	7	7	_	_	-		7	7	7	7	_		_	_	7	7	7	7	_	_	-	_	7	℃ 1	~ 1	∼ 1	-	-	-	-
ntinued Factors	ш	7	7	_	_	_	_	_		_		7	7	7	7	7	7	7	~	-	_	_		-	_		-	0	~	C 1	7
ontii Fac		7	7	-	_	_	_		-	_	-	_	7	_	_	_	-	-	-	7	7	7	7	7	7	7	7	C 1	C 1	7	7
.1 (C	ပ		-	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
Table C.1 (Continued Factors	В	-	_	_	_	_	_	_		-		_	_	_	-	-	_		_	_	_		-	-	_	-		-	-	_	_
Tab	A	_	_	-		-	_	_	_	_	-	-	_	_	_	_		_	_	_		_	_	-	_		-	-	-		_

Table C.1 (Continued)

1 40	ic C.	. I (C			,												
				tors								Rep	lication				
A	В	C	D	E	F	G	H	1	2	3	4	5	6	7	8	_ 9	10
l	l	2	2	2	2	1	1	IN		INF	INF	INF	INF	INF	INF	INF	INF
1	1	2	2	2	2	1	2	IN	F INF	INF	INF	INF	INF	INF	INF	INF	INF
l	l	2	2	2	2	2	l	IN	F INF	INF	INF	INF	INF	INF	INF	INF	INF
l	1	2	2	2	2	2	2	IN	F INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	1	1	1	1	1	1	15	8 158	166	169	160	166	164	170	166	159
1	2	1	l	1	1	1	2	15	8 158	170	165	160	166	164	160	166	159
ì	2	l	l	1	1	2	1	15	8 158	166	164	160	160	164	160	166	159
l	2	1	1	1	1	2	2	15	8 158	166	164	160	160	164	160	166	159
1	2	1	1	1	2	1	1	55:	3 511	497	479	536	596	525	498	591	509
1	2	l	l	l	2	1	2	54	9 512	470	484	504	547	534	530	523	522
1	2	1	1	1	2	2	l	48	4 547	498	554	527	507	521	540	563	551
1	2	1	1	1	2	2	2	48-	4 543	498	554	527	507	521	539	563	551
1	2	1	1	2	1	1	1	IN:	f inf	INF	INF	INF	INF	INF	INF	INF	INF
l	2	1	l	2	1	1	2	IN	f inf	INF	INF	INF	INF	INF	INF	INF	INF
I	2	1	I	2	1	2	1	IN	f INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	1	l	2	1	2	2	IN.	f inf	INF	INF	INF	INF	INF	INF	INF	INF
1	2	1	1	2	2	1	1	IN	f inf	INF	INF	INF	INF	INF	INF	INF	INF
ì	2	l	1	2	2	1	2	IN	f inf	INF	INF	INF	INF	INF	INF	INF	INF
1	2	ì	l	2	2	2	1	IN	F INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	i	l	2	2	2	2	IN	f inf	INF	INF	INF	INF	INF	INF	INF	INF
j	2	l	2	1	1	1	I	93	92	90	86	111	106	94	98	112	94
1	2	ì	2	ì	l	l	2	93	92	90	86	111	106	94	98	112	94
1	2	1	2	1	1	2	1	93	92	90	86	111	102	94	98	112	94
1	2	1	2	1	1	2	2	93	92	90	86	111	102	94	98	112	94
Ī	2	Ì	2	ì	2	1	l	37	5 377	342	345	398	406	388	343	461	357
l	2	1	2]	2	ì	2	40	1 377	342	345	398	406	388	343	461	395
1	2	ì	2	1	2	2	l	40	1 377	338	345	398	409	340	343	473	357
1	2	1	2	l	2	2	2	40	1 377	7 338	345	398	409	340	343	473	376
1	2	1	2	2	1	1	l	10	1 143	88	98	88	110	130	INF	97	78
1	2	1	2	2	l	l	2	10	1 143	88	98	88	110	164	109	97	78

Table C.1 (Continued)

140	ic C.	1 (C	Fac	tors	,							Renli	cation				
Α	В	C	D	E	F	G	Н	1	2	3	4	5	6	7	8	9	10
1	2	1	2	2	1	2	1	107	146	88	117	88	110	139	INF	91	78
1	2	1	2	2	1	2	2	107	146	88	117	88	110	139	126	91	78
1	2	1	2	2	2	1	1	374	491	368	412	380	410	454	344	343	332
1	2	1	2	2	2	1	2	376	491	368	412	380	410	467	353	343	332
1	2	1	2	2	2	2	1	380	494	368	412	380	410	463	INF	325	332
1	2	1	2	2	2	2	2	385	494	368	412	380	410	488	398	325	332
1	2	2	l	1	1	1	1	690	709	711	723	800	794	647	736	702	732
1	2	2	1	1	1	1	2	690	709	711	723	821	803	647	736	702	732
1	2	2	1	1	1	2	1	711	733	745	712	1099	790	662	773	747	735
1	2	2	1	1	1	2	2	711	733	745	712	981	790	662	773	747	735
1	2	2	1	1	2	1	1	2199	2389	2198	2299	2333	2192	2217	2380	2274	2413
1	2	2	1	1	2	1	2	2171	2418	2283	2226	2476	2242	2193	2372	2163	2042
1	2	2	1	1	2	2	1	2245	2580	2439	2239	2712	2147	2152	2433	2697	2241
1	2	2	1	1	2	2	2	2245	2537	2439	2340	2741	2444	2208	2433	2697	2240
1	2	2	I	2	I	1	I	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	1	2	1	1	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	l	2	1	2	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
l	2	2	1	2	1	2	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
l	2	2	l	2	2	1	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
l	2	2	1	2	2	1	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	1	2	2	2	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
l	2	2	1	2	2	2	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
i	2	2	2	1	1	i	i	435	477	432	440	416	455	458	424	446	420
1	2	2	2	l	1	ì	2	435	477	432	440	416	455	458	424	446	420
1	2	2	2	1	1	2	I	435	477	432	440	416	455	458	432	446	420
1	2	2	2	i	1	2	2	435	477	432	440	416	455	458	432	446	420
1	2	2	2	1	2	1	1	1563	1811	1609	1633	1664	1634	1710	1608	1741	1622
1	2	2	2	ì	2	1	2	1623	1829	1619	1662	1616	1645	1728	1616	1756	1634
1	2	2	2	1	2	2	1	1620	1804	1687	1709	1613	1753	1696	1668	1764	1680
1	2	2	2	1	2	2	2	1623	1804	1725	1680	1608	1753	1696	1673	1824	1680

Table C.1 (Continued)

rau	ie C.	.1 (C		tors	,							Rep	lication				
Α	В	C	D	E	F	G	Н	1	2	3	4	5	6	7	8	9	10
1	2	2	2	2	ì	1	1	INI	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	2	2	1	I	2	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	2	2	1	2	1	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
I	2	2	2	2	1	2	2	INI	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	2	2	2	l	1	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	2	2	2	1	2	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	2	2	2	2	1	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
1	2	2	2	2	2	2	2	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	Ì	1	1	1	1	1	220	226	196	210	INF	207	190	212	223	199
2	I	l	1	1	1	1	2	214	226	225	217	272	216	210	217	220	203
2	1	1	l	1	1	2	1	227	242	INF	224	244	209	193	210	222	202
2	1	ì	1	1	1	2	2	237	242	240	224	244	234	205	230	222	202
2	1	l	1	1	2	1	1	491	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	l	i	l	2	l	2	539	602	482	487	557	588	480	582	549	523
2	1	1	1	1	2	2	l	524	INF	INF	442	INF	488	INF	542	INF	INF
2	l	1	1	1	2	2	2	584	681	616	623	674	677	598	608	647	683
2	1	l	1	2	1	1	1	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	l	1	2	1	l	2	340	348	312	334	320	345	358	280	324	282
2	1	1	1	2	1	2	1	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	1	1	2	l	2	2	500	396	435	488	503	527	475	566	339	467
2	1	1	1	2	2	1	1	INI	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	1	ì	2	2	l	2	719	599	707	693	729	632	642	693	713	841
2	l	1	1	2	2	2	1	IN	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	ì	ì	l	2	2	2	2	90-	1121	1038	1220	976	968	884	916	936	987
2	ì	1	2	l	i	1	1	14:	137	108	110	122	133	123	139	150	122
2	1	1	2	1	l	1	2	145	146	116	110	122	133	123	130	150	138
2	l	l	2	1	1	2	1	160	146	108	110	137	143	130	133	142	130
2	1	1	2	1	l	2	2	160	146	108	110	137	143	130	130	142	120
2	I	I	2	I	2	í		429	435	315	308	392	344	399	399	435	442
2	1	i	2	1	2	I	2	477	385	292	516	439	368	456	410	491	452

Table C.1 (Continued)

1 40	ic C.	. ı (C		tors	,							Don!:	antion				
Α	В	С	D	E	F	G	Н	I	2	3	4	Kepii 5	cation 6	7	o	0	10
$\frac{\Lambda}{2}$	1	1	2	1	2	2	1	INF		342	376				8	9	10
2	1	1	2		2				444			374	368	INF	413	418	440
	1	1		1		2	2	495	446	342	542	415	443	393	430	519	503
2	ı,	ŀ	2	2	1	1	1	117	160	INF	INF	INF	INF	INF	INF	123	INF
2	i	1	2	2	1	l	2	160	170	117	177	143	138	229	186	164	INF
2	1	l	2	2	1	2	1	126	183	INF	INF	INF	INF	INF	INF	156	INF
2	I	1	2	2	l	2	2	126	206	139	230	157	148	322	285	172	INF
2	l	1	2	2	2	1	1	INF	INF	INF	INF	INF	INF	INF	533	INF	INF
2	l	1	2	2	2	l	2	532	698	442	INF	463	494	437	481	336	485
2	l	i	2	2	2	2	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	l	2	2	2	2	2	813	738	429	716	654	1045	686	560	461	717
2	1	2	1	l	1	l	1	911	907	915	902	928	918	925	969	970	927
2	1	2	1	l	1	1	2	913	900	922	920	911	920	930	1006	935	897
2	ł	2	1	1	1	2	ì	1050	1115	INF	975	976	1054	1036	INF	INF	1066
2	1	2	l	1	1	2	2	1050	1033	1037	1039	998	1036	1054	1128	1029	1053
2	1	2	l	1	2	1	1	INF	INF	INF	INF	2177	INF	2283	INF	2349	INF
2	1	2	1	1	2	1	2	2194	2399	2592	2459	2342	2304	2460	2294	2472	2172
2	ı	2	1	1	2	2	I	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	i	2	l	1	2	2	2	2499	2663	2430	2753	2487	2559	2348	2556	2810	2762
2	1	2	1	2	i	1	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	2	1	2	l	1	2	2035	1851	INF	INF	1907	INF	INF	1944	2026	INF
2	1	2	1	2	1	2	ì	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	2	1	2	1	2	2	INF	INF	INF	INF	3 777	INF	INF	INF	INF	INF
2	1	2	1	2	2	i	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	2	l	2	2	1	2	3708	4079	3705	3855	3654	3660	3523	3886	4011	3809
2	1	2	l	2	2	2	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	1	2	1	2	2	2	2	5339	6259	5755	5320	5760	5713	6151	6285	5816	6353
2	1	2	2	1	1	1	1	555	604	573	527	576	581	617	535	629	559
2	1	5	2	ì	1	i	2	560	604	590	533	581	567	625	553	627	582
2	1	2	2	i	ì	2	1	545	594	641	552	619	571	621	591	603	544
2	1	2	2	1	1	2	2	550	615	640	563	622	572	618	593	603	563
_	-	-	_	-	•		-	2:2/0	0.0	0.10	2.07.7	022	214	010	27.7	003	.,0.,

Table C.1 (Continued)

1 40	ic C.	. 1 (C	Can		')							ъ	.•				
	D	_		tors		~	7.7	,	•	2		_	cation	_	_	_	
_ <u>A</u>	B	<u>C</u>	D	E	F	G	H	1	2	3	4	5	6	7	8	9	10
2	1	2	2	1	2	1	1	1697	1779	1931	1670	1966	1953	1894	1691	1952	1814
2	1	2	2	1	2	1	2	1677	2081	1871	1761	1859	1868	1920	1762	2012	1676
2	1	2	2	1	2	2	1	1779	1889	1846	1851	1964	INF	2060	1879	1981	1723
2	j	2	2	1	2	2	2	1772	1962	1881	1841	2066	2195	2074	1926	2062	1830
2	1	2	2	2	1	l	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	l	2	2	2	1	1	2	INF	INF	921	1198	INF	INF	INF	INF	INF	INF
2	1	2	2	2	1	2	1	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	l	2	2	2	1	2	2	2283	INF	INF	2025	INF	INF	INF	2922	INF	2572
2	1	2	2	2	2	1	l	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	l	2	2	2	2	1	2	2999	2863	3128	3066	2818	3286	2821	2771	2774	2901
2	i	2	2	2	2	2	i	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	i	2	2	2	2	2	2	5427	3266	3971	4146	4439	5821	4214	INF	5548	4135
2	2	1	1	1	1	1	1	169	172	170	149	160	177	157	167	166	166
2	2	1	1	1	I	l	2	169	172	170	149	160	177	157	167	166	166
2	2	1	1	l	1	2	1	177	170	168	161	160	177	157	167	178	165
2	2	1	1	1	1	2	2	177	170	168	161	160	177	157	167	178	165
2	2	ł	l	I	2	1	l	507	446	481	502	454	366	426	451	454	433
2	2	l	1	1	2	1	2	479	446	433	501	458	387	404	437	454	431
2	2	1	1	l	2	2	1	436	477	480	516	442	468	487	451	509	471
2	2	ì	1	ì	2	2	2	436	477	480	516	442	468	507	453	509	471
2	2	1	i	2	1	1	l	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	1	1	2	1	1	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	l	1	2	1	2	l	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	1	1	2	1	2	2	INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	1	i	2	2	l	1	INF	INF	INF	INF	INF	INF	INF	590	INF	INF
2	2	l	1	2	2	1	2	618	639	612	702	576	618	603	649	559	596
2	2	1	l	2	2	2	1	INF	672	INF	INF	INF	INF	629	INF	753	INF
2	2	1	1	2	2	2	2	INF	725	797	INF	808	INF	629	808	749	841
2	2	ĺ	2	i	ì	i	i	99	97	90	86	111	106	94	97	114	101
2	2	ì	2	1	1	I	2	99	97	90	86	111	106	94	94	114	95

	10	101	95	398	370	416	400	78	78	78	78	INF	385	INF	390	657	199	661	029	1801	1768	1928	1939	INF	INF	INF	INF	INF	INF	INF	INF
	6	114	114	472	472	434	434	24	26	91	91	365	369	378	378	089	089	879	819	1842	1845	1934	1934	INF	INF	INF	INF	Ŗ	INF	INF	ĮŅ.
	8	16	94	352	382	352	364	105	109	120	126	363	363	367	394	662	662	0.29	029	1915	1915	1961	1961	IN.	INF	INF	INF	INF	N.	INF	IN F
	7	94	75	315	319	354	346	130	164	139	139	IN F	522	INF	556	989	635	623	622	1841	1819	1925	9161	N F	N.	INF	INF	INF	N.	N.	IN.
ation	9	109	109	401	401	405	405	110	110	110	110	Ę	447	460	445	663	999	673	672	1897	1884	8161	8161	INF	Ė	INF	INF	IN:	N.	Ν̈́	INF
Replication	5	111	111	370	370	370	370	123	123	116	116	ΙΝΉ	410	Ŗ	486	682	682	289	289	1980	1943	2117	2156	INF	INF	INF	IN-	INF	INF	INF	INF
	4	98	. 98	309	309	309	309	86	86	117	117	IN.	448	ĮŅ.	485	699	699	673	673	2001	2022	2127	2122	IN F	N.	N.	N. F	N F	IN F	N.	N N
	3	06	90	326	326	326	326	88	88	88	88	363	400	391	391	643	643	649	649	1783	1783	2140	2114	ĮŅ.	INF	INF	IN F	INF	INF	N.	INF
	7	26	26	396	380	348	348	143	143	146	146	454	454	INF	457	625	625	631	631	1999	1981	2175	2175	ĮŅ.	INF	INF	INF	ΙΝ	INF	IN F	INF
	-	66	66	409	409	424	424	101	101	107	107	391	391	394	394	651	651	651	651	1851	1851	1993	1993	INF	ĮŅ.	INF	INF	ΙΝΉ	INF	ĮŅ.	IN.
	H	_	2		2	-	2	_	2	_	2	_	2	_	2	_	2	_	2		2	_	2	_	2	_	7		2	_	2
	5	7	7	_	_	7	7	_		7	7	_	_	7	7	_	_	7	7		_	7	7	_	_	7	7	_	_	CI	7
	ഥ	_	-	7	7	7	7	_	_	_	_	7	7	7	7	_	_	_	,	7	7	7	7	_	_	_	_	7	7	7	7
ued) ors	田	_		_	_	_	_	7	7	7	7	7	7	7	7	_	_	_	_	_	_	_	_	7	7	7	7	7	7	7	7
Table C.1 (Continued Factors	Δ	7	7	7	7	7	7	7	7	7	7	7	7	7	7	_	-	_	_	_	-	_	-			-	_	_	-		_
1 (C	ပ	_	-	_	-	-	_	_	_	_	7		_	-	_	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
e C.	В	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
Tab	٧	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	~	<i>~</i> 1	C 1	C 1	~	7	۲	~ 1	Cı

Tab	le C	.1 (C		nued	l)								D!:					
	_	_		tors	_	_			1	2	3	4	Replic 5	cation 6	7	8	9	10
<u>A</u>	В	<u>C</u>	D	E	F	G	<u>H</u>	_	1	2			413	442	439	425	454	413
2	2	2	2	1	1	l	1		431	474	426	432		442 442	439	425 425	454 454	413
2	2	2	2	l	1	1	2		431	474	426	432	413				454 454	413
2	2	2	2	1	1	2	l		431	474	434	432	413	442	439	425 425		413
2	2	2	2	1	1	2	2		431	474	434	432	413	442	439	425	454	413 1596
2	2	2	2	1	2	1	I		1565	1789	1426	1536	1543	1560	1701	1525	1621	
2	2	2	2	1	2	l	2		1442	1789	1441	1527	1548	1582	1669	1505	1630	1564
2	2	2	2	1	2	2	1		1557	1816	1466	1539	1539	1620	1658	1556	1648	1577
2	2	2	2	l	2	2	2		1498	1788	1451	1566	1566	1620	1694	1530	1648	1549
2	2	2	2	2	1	1	1		INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	2	2	2	1	ł	2		INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	2	2	2	1	2	I		INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	2	2	2	1	2	2		INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	2	2	2	2	1	1		INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	2	2	2	2	1	2		INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	2	2	2	2	2	1		INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
2	2	2	2	2	2	2	2		INF	INF	INF	INF	INF	INF	INF	INF	INF	INF
3	1	1	1	1	1	l	1		164	144	176	161	198	156	167	172	194	171
3	1	1	1	1	1	1	2		174	154	197	174	208	170	192	181	203	196
3	1	1	1	1	1	2	1		192	168	182	183	186	175	182	197	188	184
3	l	1	1	1	1	2	2		239	264	256	223	234	229	225	257	226	238
3	1	1	1	1	2	1	1		417	418	403	375	386	379	387	357	475	383
3	1	1	1	i	2	1	2		422	406	458	439	444	455	382	398	480	458
3	ì	1	1	1	2	2	1		432	495	544	365	410	466	427	435	515	386
3	ì	1	1	1	2	2	2		558	776	709	660	578	637	684	594	655	574
3	l	ì	1	2	1	1	1		230	207	217	233	198	213	230	INF	200	203
3	l	1	1	2	1	1	2		248	271	235	310	249	255	251	306	209	229
3	ı l	I	ı l	2	1	2	l		261	287	274	277	223	297	269	287	246	235
	_	1	1	2	1	2	2		605	544	521	468	412	420	549	448	443	412
3	1	; 1	1		_	2 1	4		393	INF	INF	INF	INF	INF	INF	INF	INF	INF
3	1	1	!	2	2	ı,	1					694	567	557	494	549	542	548
3	l	l	1	2	2	ł	2		709	630	514	094	207	331	474	347	342	240

	10	NF NF	756	111	81	149	79	244	343	339	378	66	170	144	305	IN.	343	291	478	006	1074	1007	1257	1858	1942	2082	7040	INF	1565	INF	2405
		INF																													
	8	INF	804	135	86	110	86	372	318	439	462	77	268	83	423	385	463	368	728	941	196	1101	1278	1983	2231	2153	2488	INF	1627	INF	2839
	7	ĮŅ.	855	93	114	108	108	251	405	240	326	6	139	108	211	Ŗ	352	INF	808	859	929	8101	1614	1983	2118	2366	2673	IN.	1675	INF.	2608
ation	9	ĮŅ.	841	82	79	109	93	306	288	330	519	Ľ	180	Ŗ	282	INF	479	IŅ.	747	839	1031	1112	1395	2104	2047	2267	2547	INF	1727	IN F	3115
Replication	5	448	871	106	104	106	104	220	251	402	430	121	144	151	86	INF	340	INF	546	905	1323	1072	1135	2087	2045	2283	2590	INF	1843	INF	2863
	4	IN.	891	107	91	131	109	308	273	344	402	119	119	143	143	IN.	909	Ŗ	443	833	863	296	1376	1928	1972	2144	2870	Ŗ	1631	INF	2222
	3	INF	988	80	99	102	20	250	304	304	334	104	274	140	133	351	329	389	724	216	1368	1048	1451	1905	2046	2323	2880	IN.	1562	N N	2710
	2	INF	867	61	82	75	167	207	294	308	490	207	180	Ŗ	211	IN F	390	IN F	510	844	1018	101	1260	1970	2122	2228	2789	INF	1802	<u>F</u>	3278
	I	IN.	1007	131	131	146	146	316	465	403	590	125	122	174	258	360	501	427	888	901	972	1077	1284	2125	2043	2289	2532	INF	1576	INF	3607
	Н	_	2	_	2	~	2	_	2	_	2	_	2	_	2	_	2	_	2	_	2	_	2		7		7	-	~ I	_	2
	Ŋ	7	7	-	_	7	7	_	-	7	7	_	_	7	7	_	_	7	7	_	_	7	7	_		7	7	-		C 1	C1
	F	2	7	_	-		_	7	7	7	7	_	_	_	_	7	7	7	7	_	_	_	_	7	7	7	7	-		_	
ontinued Factors	Ε	7	7	_	_		_	_	~	_	_	7	7	7	7	7	7	7	7		_	-	-	-	-	-	-	7	7	7	7
onti Fac	D	-	-	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	-	_	-		_		_	-		-	-	-
.1 (C	၁	-	-	_		-	-	_	~	_	_	-	_	_	_	-	_	_	-	7	7	7	7	7	7	7	7	7	7	7	7
Table C.1 (Continued Factors	В		-	-	-	-	_	_	-	-	-	_	-	-	_	_	-	_	_		_		_	_	-	-	-	-	_	_	
Tal	A	3	n	c	n	3	33	3	ć	n	æ	c	c	c	n	3	cc	c	3	ι	co	(C)	S.	cc	33	S	B	n	3	m	C

		l.	_		•						-	~	10		~		_		~1		~										
	10	岩	277	E E	5399	567	576	699	189	176	188	1888	213	Ę	1218	Ξ.	2005	Z.	297.	Ë	5138	73	73	67	67	319	300	245	245	89	89
	6	INF	3338	INF	4867	610	634	734	817	1739	1643	1852	2147	1083	1506	INF	1919	INF	2646	INF	3948	49	49	49	49	214	214	263	263	89	89
	8	Ę	3244	INF	5425	584	625	730	842	1485	1463	1728	1854	Ŗ	1195	IN.	1952	INF	2918	IĀ	5036	74	74	29	<i>L</i> 9	264	269	292	294	84	84
	7	INF	3194	IN.	4615	632	609	738	738	1921	1614	1936	2052	INF	1308	IŅ.	2031	INF	2542	INF	5133	59	59	57	57	238	238	223	223	87	87
ation	9	INF	2855	INF	4392	598	744	998	1097	1867	1739	2013	2071	INF	1355	NF NF	1811	N.	2638	INF	4786	7.1	71	92	92	269	269	240	249	×.	SC
Replication	5	INF	2972	IN.	6419	9/9	651	722	805	1667	1616	1763	2307	INF	1134	Ŗ	1948	IN.	2890	INF	4138	38	38	38	38	208	208	258	262	74	74
	4	INF	3215	ĮŅ.	5462	541	503	628	602	1696	1538	1924	2107	IN.	1273	IN	1810	IN F	2580	Ŗ	5175	72	72	69	69	279	254	258	258	100	100
	3	ĮŅ.	3352	Ę	5483	612	009	748	816	1629	1743	1667	1971	Ŗ	1358	ĮŅ.	2062	INF	2745	ĮŅ.	3870	65	65	58	58	231	252	215	235	17	7.1
	2	INF	3032	INF	5812	557	715	651	1001	1733	1525	1717	1893	INF	966	INF	1684	INF	2546	IN.	3583	50	30	46	46	275	297	376	420	98	98
	-	INF	2860	INF	4760	642	732	645	892	1652	1589	1713	1730	ΙΝΉ	1279	IN.	2387	INF	2451	IN.	4215	3 6	56	58	58	231	331	240	240	121	121
	. !																														
	Ξ		7		7	-	2		7	_	7	_	7	_	2	_	7	_	7		7	_	7		2	_	7		2	_	- 2
'	ان		-	2	2	_	_	7	2			; 2	; 2	_		7	- 2	_		2	2 2	_	_	- 2	-			2	<i>-</i> 2	_	_
_	[I,	2		7	2	_	_	_	_	-	_	7	7	_		2			2 2		7	_	_	_	_	_	-	_	_	7	~
ntinuec Factors	DE	-	7	1	-	7	7	7	7	7	7	7	7	7							7	_	_	_	_	_					_
(Cor	_ ပါ	7	7	7	7																7	_		,		_	_	_	_	_	_
C.1	m	_	_				_	_			_	_	_	_	_	_	_	_	_	_	_	7	7	7	7	7	7	7	7	7	7
ple	∢	3	B	3	3	က	ť	n	т	ю	Э	3	က	ю	т	3	က	3	က	က	т	m	m	m	'n	n	m	G	m	co	က

	10	77	11	374	290	432	407	49	35	49	35	202	198	236	204	58	58	<i>L</i> 9	<i>L</i> 9	185	661	230	230	354	349	362	357	1365	1368	1395	1386
	6	68	89	311	403	338	395	52	52	52	52	232	250	232	232	82	82	64	64	295	322	267	267	350	350	347	347	1441	1441	1446	9++1
	8	112	112	355	279	333	362	46	40	46	40	221	258	270	228	37	37	37	37	250	250	216	301	369	369	372	372	1394	1394	1414	1414
	7	114	114	302	311	343	335	55	55	55	55	126	126	135	135	73	73	73	73	247	247	283	283	364	355	342	333	1536	1491	1375	1374
ation	9	99	99	339	344	340	450	3 6	9 9	<u>3</u> 6	56	286	260	289	235	55	45	70	45	284	375	305	323	374	369	360	355	1533	1481	1467	1488
Replic	4 5 6	82	82	Ŋ.	401	338	382	99	90	<u> 3</u> 6	50	188	170	165	170	54	54	54	54	246	246	276	904	373	374	376	376	1419	1468	1417	1438
	4	83	83	258	281	375	405	49	49	49	49	691	169	691	169	42	42	42	42	159	159	159	159	376	376	371	371	1295	1276	1306	1293
	3	71	71	367	301	386	464	27	27	27	27	138	120	132	132	53	53	53	53	298	298	Ν̈́	369	390	390	398	398	1418	1418	1556	1556
	2	114	114	290	318	346	463	30	30	30	30	226	247	212	212	99	99	99	99	358	308	447	507	372	372	379	379	1339	1330	1299	1299
	-	130	130	347	346	452	489	53	53	53	53	383	383	569	269	50	20	55	55	256	256	293	293	370	370	357	357	1711	1711	1257	1271
	H	_	7		2	_	2	_	2	_	2	-	2	_	2	_	2	_	2	_	2	_	2		2		2		2	-	2
	0	7	7	_		7	7	_	_	7	7	_	_	7	7	_	_	7	7	_	-	7	7		_	7	7	~		7	7
	ı		-	7	7	7	7		_	_	_	7	7	7	7	_	_		_	7	7	7	7		_	-	_	7	C 1	<i>C</i> !	C 1
nued) ors	Ξ	7	7	7	7	7	7	_	-	_	_	_	_	_	_	7	7	7	7	7	7	7	7	~	_	-	_		_		
ontinuec Factors		_	-		-	_	-	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	-	_		_	~		-	_
Table C.1 (Continued Factors	ပ	_	~	_		_	~		-	_	_		_	-		_	_	—		_	_	_		7	~ 1	7	7	7	7	7	7
ē C.	m	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
Tab]	4	c.	m	3	m	m	c,	3	c	m	c	m	n	n	r	3	'n	c	n	n	m	m	m	m	m	m	m	m	m	(C)	m

	10	514	514	538	538	1878	9981	1920	1816	312	312	312	312	1191	1143	1174	1126	276	276	300	300	1303	1273	1380	1373	394	394	418	418	919	919
	6	487	487	513	513	1841	1821	2212	2064	283	283	284	284	1180	1192	1205	1205	284	284	276	276	INF	1111	1245	1242	386	386	1 13		979	626
	8	465	465	516	516	1853	1882	1974	1949	313	313	313	313	1124	1154	1189	1201	380	372	442	536	ĮŅ.	1408	1364	1595	459	459	483	483	624	624
	7	521	521	550	550	1653	1752	1826	1878	320	320	320	320	1121	1121	1131	1201	327	325	337	332	1360	1272	1521	1521	408	408	420	420	596	596
ation	9	909	909	542	542	1780	1754	1761	1812	336	336	336	336	1268	1267	1292	1278	306	290	314	290	1503	1363	INF	1319	412	412	130	130	607	607
Replication	5	545	545	591	591	1970	1932	2150	1938	313	313	313	313	1350	1347	1290	1240	330	330	339	339	INF	1195	INF	1637	388	388	90+	90+	209	209
	4	498	498	622	622	1721	6891	1736	1833	311	311	311	311	1236	1177	1249	1199	281	281	292	292	Ŗ	1138	INF	1136	387	387	414	+	620	620
	3	504	519	530	530	1773	1825	1936	1936	316	316	316	316	1257	1220	1258	1236	INF	438	401	401	1390	1388	1366	1486	426	426	453	453	909	909
	2	429	429	473	473	8081	6181	1894	1894	310	310	310	310	1121	1109	1146	1137	387	382	359	359	1308	1323	1245	1300	601	400	427	427	623	623
	1	489	497	483	483	1675	1705	1982	2231	295	295	295	295	1366	1367	1294	1326	325	325	324	324	1439	1413	1543	1544	390	390	807	807	614	614
	H	1	2	_	2	_	2	_	2	_	2	_	2	_	2		2	_	2	_	2	_	2	-	2	_	2	_	2		2
	Ŋ	1	_	7	7	1	_	7	7	_	-	7	7	_	_	7	7	_	_	7	7	_	_	7	7			7	2	_	_
	ודי	_	_	_	_	2	7	7	7	_	-		1	7	7	7	7	_	_	_	_	7	7	7	7	_	_	_	_	7	7
ued) ors	ш	2	7	7	7	7	7	7	7	_	-	_	_	_	_	_		7	7	7	7	~	7	7	C 1	_	_	_	_	_	
ontinued Factors	Q	1	_	_	_	_		_	_	7	7	7	2	7	7	7	7	7	7	7	7	7	7	7	7	_	_		_		-
Table C.1 (Continued Factors	ပ	2	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	_	_	_	_		_
e C.	В	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	-	-	-	_	_	_
Tabl	Y	3	n	m	m	r	٣	æ	c	m	w	m	n	c	m	3	3	n	c	n	'n	n	m	m	m	-+	-1	-1	च	-+	-1

	10	694	594	346	346	157	157	740	740	117	717	171	171	552	552	531	531	736	736	551	551	362	962	397	397	311	311	191	191	998	998
	6	713	713	306	306	474	474	610	610	871	871	406	406	454	454	602	602	671	67.1	501	501	864	864	733	733	1060	1060	2889	2889	2961	2961
	8	711	711	465	465	516	516	747	747	903	903	556	556	889	889	192	191	932	932	400	400	571	571	637	637	925	925	2776	2776	2839	2839
	7	647	647	284	284	413	413	746	746	899	899	542	542	587	587	873	873	096	096	638	889	956	956	840	840	1224	1224	2838	2838	2970	2970
ation	9	929	929	482	482	557	557	709	402	964	964	512	512	554	554	979	979	713	713	414	414	564	564	849	648	957	957	2522	2522	2627	2627
Replication	5	929	9/9	319	319	433	433	628	636	915	915	427	427	484	484	725	725	854	854	574	574	736	736	762	762	957	957	2978	2978	3068	3068
	4	701	701	477	477	531	531	588	588	813	813	489	489	519	519	822	822	912	912	403	401	662	662	633	633	912	912	2991	2991	3099	3099
	3	681	189	414	414	486	486	635	635	821	821	456	456	525	525	099	099	789	789	536	536	743	743	770	770	1049	1049	2759	2759	2858	2858
	2	695	695	432	432	477	477	638	638	842	842	424	424	454	454	594	594	657	657	460	460	541	541	119	611	890	890	2845	2845	2980	2980
	1	683	683	388	388	472	472	827	827	971	176	486	486	603	603	029	029	808	808	643	643	940	0+6	098	098	1388	1388	2729	2729	2795	2795
		ı																													
	H	1	7	_	7	_	7	-	7	_	7	_	7	-	2	_	7		7		7	_	2	-	7	_	7			_	
	G	2	7	-	-	7	7		_	2	2	_	-	7	2			2	2	_		7	7		_	7	7	_	_	7	7
(pa	F	7	7					7	7	7	7	_	_		_	7	7	- 2	_		-	2 1	2	2 2	2 2	2 2	2	_	_	_	_
ntinuec Factors	D E	1	_	7	7	7	7	1 2	1 2	7	1 2	7	7	7	7	7	2	2	7	2 2	2	2	2 2	2	2	2	2	_	_	_	_
(Cor	CI	1	_	_	_	_	_	_	_	_	_	_	_			_		_	_	_	_		_	_	_	_	_	7	7	2	2
C.1	В (_	_	_	_	_	_	_	_	_	-	_		_	_	_	_	_	_	_	_	_	_	_	_	_	_	_	_		_
Table C.1 (Continued) Factors	A I	4	4	4	4	4	4	4	4	ᡇ	7	7	4	4	4	4	4	4	4	4	ন	ㅋ	ব	7	-1	₹	7	.)	- †	-1	-1

	10	4903	903	164	164	838	838	503	503	207	207	895	895	295	295	754	754	423	423	822	822	697	569	636	989	518	518	296	296	94	94
		4	4	5	5	Ξ	Ä	7	ñ	ñ	ñ	m	ñ	ίť	ω.	'n	'n	4	4	4	4	ť	(C)	Ń	Ň	4	4	5	'n	_	_
	6	3915	3915	4212	4212	1691	1691	2753	2753	2940	2940	3825	3825	3096	3096	3564	3564	4474	4474	4777	4777	2573	2573	3548	3548	3578	3578	4619	4619	291	291
	∞	4648	4648	4816	4816	1738	1738	3310	3310	2972	2972	3833	3833	3170	3170	3566	3566	5167	5167	5668	5668	2973	2973	5106	5106	4174	4174	5668	\$668	185	185
	7	4011	4011	4260	4260	1701	1701	2475	2475	3025	3025	4342	4342	3085	3085	3559	3559	4607	4607	5087	5087	2212	2212	3334	3334	3454	3454	4360	4360	237	237
ation	9	3613	3613	3745	3745	1721	1721	2399	2399	3252	3252	3822	3822	3268	3268	3517	3517	4457	4457	4895	4895	2448	2448	3873	3873	3445	3445	4735	4735	330	330
Replica	5 6	3904	3904	4195	4195	1459	1459	2101	2101	3028	3028	3664	3664	2922	2922	3198	3198	4280	4280	4616	919†	2612	2612	4250	4250	3673	3673	959†	4636	611	611
	4	4191	4191	4437	4437	1531	1531	2902	2902	2857	2857	3607	3607	3010	3010	3625	3625	4661	4661	5150	5150	2613	2613	4071	4071	3493	3493	4333	4333	312	312
	3	4090	4090	4372	4372	1543	1535	2195	2195	2891	2891	3554	3554	2802	2802	3054	3054	4015	4015	4282	4282	3118	3118	\$266	5266	3779	3779	4895	4895	369	369
	2	5056	5056	5227	5227	1808	1798	2977	2977	3005	3005	3782	3782	3190	3190	3430	3430	4572	4572	4815	4815	2934	2932	5116	5116	3608	3608	166†	166†	135	135
	-	4438	4438	4624	4624	1661	1661	2498	2498	2747	2747	3731	3731	2991	2991	3558	3558	4512	4512	5073	5073	3277	3273	5517	5517	4356	4356	5934	5934	345	345
	Ì																														
	Ŧ	_	7	_	7	-	7	_	7	-	7	_	7	_	7	_	7	_	7	_	7	_	7	_	7		7	_	7		7
	٥	_	_	7	7	-	_	7	7	_	-	7	7	_		7	7	-	_	7	7	_	_	7	7	-	_	7	7	_	-
Э́,	1	7	7	7	7	-	_	_	-	7	7	7	7	_	_	_	_	7	7	7	7	_	_	_		2	2	7	7	_	-
ntinuec Factors	田	_	_		-	7	7	7	2	7	7	7	7	_	_	_	_	_	_		_	7	7	2	7	7	7	7	7		_
Cont Fa		_		_		-	_	_	-		_		_	7	7	7	7	7	7						C1	C 1	<u>~</u> 1	<u>~</u> 1	<u>.</u> .	_	
C.1 (7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	2	7	<i>C</i> 1	7	<u></u>	7		<u></u>	_ C1	_ C1	- 2	~	~
Table C.1 (ContinuedFactors	m	_		_	_	_	—	_	_	_	_	_	_	_	_	_		_	_	_			_	_	_		_	- -	-	C7	. 7 -+
Та	4	4	4	4	4	ব	4	4	4	ব	4	4	4	4	4	4	ব	4	4	4	য	ব	ব	7	ব	া	-ব'	4,	-11"	a.	1

	10	206	206	501	501	525	525	541	541	1090	1090	515	515	671	671	479	479	<i>LL</i> 9	<i>LL</i> 19	558	558	999	999	775	775	1570	1570	759	759	1218	1218
	6	321	321	557	557	587	287	109	601	1210	1210	597	597	864	864	437	437	584	584	629	629	718	718	738	738	1470	1470	765	765	1236	1236
	∞	194	194	609	609	651	159	554	554	1124	1124	597	597	864	864	345	345	516	516	648	648	792	792	560	999	1145	1145	620	620	998	998
	7	297	297	497	497	515	515	539	539	1088	1088	544	544	730	730	321	321	465	465	569	569	653	653	784	784	1468	1468	927	927	1503	1503
cation	9	396	396	601	601	625	625	539	531	1080	1080	569	995	905	905	307	307	439	439	819	819	699	699	601	601	1189	1189	754	754	1180	1180
Replication	5	119	119	473	473	497	497	580	580	1168	1168	919	919	874	874	319	319	466	99†	587	587	695	695	8+9	9+9	1312	1312	603	603	9+8	846
	4	357	357	516	516	546	546	520	518	1046	1046	562	562	992	992	292	292	397	397	527	527	563	563	553	553	1123	1123	577	577	S 	811
	3	456	456	509	509	539	539	298	596	1202	1202	879	628	868	868	369	369	507	507	099	099	756	756	558	558	1104	1104	622	622	0+6	0+6
	2	150	150	444	444	468	468	550	550	1108	1108	477	477	699	699	357	357	507	507	909	909	651	651	514	514	928	928	738	714	1095	1095
	-	408	408	533	533	554	554	565	565	1138	1138	582	582	831	831	404	404	809	809	663	663	822	822	786	786	1623	1623	836	828	1434	1434
	,	ı																													
	H	_	7	-	7		7	_	7	_	7	_	7		7	_	7	-	7		7	_	7		7	_	7	_	7	_	7
	۵	7	7	_	_	7	7		_	7	7	_	7	7	7	-		7	7		_	2	7		_	7	7	_	_	2	7
S	 F			7	7	7	7	-	-	_	-	7	2	7	7		_	_	_	- 2	7	7	7	_	2 1	-	~	7	2	7	2
Factors	Ξ	_	_	_	_	_	_	1	7	1	7	7	1 2	1	7	7	~	7	7	7	~	~	7		7			7	7	7	~
<u>H</u>	C	_		_	_	_		_	_		_	_		_	_	_			_	_	_	_	_	_	_		_	_	_	_	_
	m	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	۲	7	7	7	7	7	7	7	2
	4	4	4	4	4	4	ব	4	4	4	4	1	ব	4	বা	4	4	╗	ᢐ	ব	च	च	寸	-1	-1	-1	- 1	7		-+	-1

	10	2239	239	906	906	629	629	611	611	160	160	,603	,603	1027	1027	669	669;	858	858	203	203	338	338	968	968	152	152	1932	1932	922	922
		2509 2																													
	8	2424	2424	5265	5265	2521	2521	2644	2644	3746	3746	9071	9071	2076	2076	3546	3546	3470	3470	7628	7628	3363	3363	3993	3993	5380	5362	1264	1264	3918	3915
	7	2578	2578	5824	5824	2649	2649	2859	2859	3116	3116	7505	7505	1890	1890	2658	2658	2831	2831	5789	5789	2930	2930	3563	3563	5278	5278	12784	12784	2838	2838
ntion	9	2641	2641	5785	5785	2564	2564	2708	2708	3043	3043	7375	7375	1928	1928	2501	2501	2765	2765	5951	5951	2813	2813	3203	3203	4793	4793	11405	11405	3181	3181
Replication	5	2610	2610	5901	5901	2558	2558	2684	2684	3061	3061	7411	7411	1708	1708	2077	2077	2472	2470	5326	5326	2509	2509	2947	2947	5230	5214	12465	12465	3128	3128
	4	2335	2331	5262	5262	2651	2651	2810	2810	3649	3649	8932	8932	1836	1828	2992	2992	3380	3380	6953	6953	3055	3055	3631	3631	4785	4785	11427	11427	2796	2796
	3	2707	2705	6212	6212	2514	2514	2664	2664	3066	3066	7413	7413	1974	1974	2577	2577	3103	3099	6558	6558	3042	3042	3510	3510	5351	5337	12513	12513	3287	3287
	2	2053	2039	4307	4307	2473	2473	2626	2626	3579	3575	8729	8729	1912	1912	2824	2824	2583	2565	5250	5250	3134	3134	3500	3500	5498	5482	13009	13009	3387	3387
	-	9861	1972	4189	4189	2436	2436	2514	2514	3619	3619	8827	8827	2045	2085	3540	3540	2972	2962	2099	2099	3008	890€	3812	3812	5346	5314	12457	12457	3481	3481
	í																														
	H	_	7	-	2	-	2	_	7	-	7	-	7		7	-	7	_	7	-	7	_	7		7		7	_	7	_	7
	Ð,	П	_	7	7	_	_	7	. 2	-	_	7	2	_	_	. 2	2	_	_	2	2	_	_		. 2	_		2	2	_	_
sg (pa	EF			_	_	- 2	_ 2	- 2	- 2	-	7	7	2	2	7	2	7	_	_	_	_	7	- 2	- 2	1 2	7	-	7	7	2	2
ntinuec Factors	D			_		_	_		_	7	7	_	-	-	_	_	_	7	7	7	7	7	7	7	7	7	7	7	7	7	7
O) H	ာ	7	2	2	2	7	7	2	7	2	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	2	7	~ 1	~ 1	7
c.1	В	7	7	7	7	7	7	7	7	7	7	2	7	7	7	2	7	7	7	7	7	7	7	~	7	7	7	7	~ 1	CI	7
Table C.1 (Continued Factors	V	4	4	4	4	4	4	4	4	寸	7	7	7	ব	7	4	4	-	ব	ব	7	7	7	+	-1	+	7	7	+	-	-1

	10	7405	7405	427	427	562	562	475	475	610	610	736	736	1261	1261	784	784	1309	1309	476	476	629	629	524	524	707	707	875	875	1538	1538
	6	4999	4999	442	442	592	592	490	490	640	640	700	200	1192	1192	748	748	1240	1240	427	427	562	562	475	475	610	019	743	743	1274	1274
	8	5161	5161	433	433	574	574	481	481	622	622	629	619	1150	1150	727	727	1198	1198	136	436	580	580	484	184	628	628	717	717	1227	1227
	7	5229	5229	400	400	208	508	448	448	556	556	694	694	1180	1180	742	742	1228	1228	486	486	675	675	534	534	723	723	805	805	1402	1402
ation	9	5146	5146	415	415	538	538	463	463	286	586	742	742	1273	1273	790	790	1321	1321	407	407	521	521	455	455	569	569	683	683	1160	1160
Replication	5	5807	5807	412	412	532	532	460	460	580	580	733	733	1258	1258	781	781	1306	1306	500	500	707	707	548	548	755	755	979	979	1040	1040
	4	4752	4752	427	427	562	562	475	475	019	019	200	200	1192	1192	248	748	1240	1240	167	167	889	889	515	515	989	989	693	693	1173	1173
	3	5744	5744	436	436	580	580	484	484	628	628	721	721	1234	1234	692	692	1282	1282	476	476	659	659	524	524	707	707	568	568	928	928
	2	6240	6240	415	415	538	538	463	463	586	586	692	692	1172	1172	740	740	1220	1220	388	388	484	484	436	436	532	532	819	819	1029	1029
	7	6046	6046	419	419	545	545	467	467	593	593	703	703	1195	1195	751	751	1243	1243	496	496	700	700	544	544	748	748	927	927	1647	1647
	Н	_	2	_	2		2	_	2	_	2	_	2	_	2	_	2		2		2		2	_	2		2	_	2		2
	G	7	7	_	_	7	7	_	_	7	7	_	_	7	7		_	2	7	_	_	7	2	_	_	7	7	_	_	7	2
_	ഥ	7	7	_	_	_	_	7	7	2	7			_	_	7	7	7	7	_	_		_	7	7	7	7	_	_		_
nued) ors	Ш	7	2			-				_		7	7	7	7	7	7	7	7	_		_	_	_	_	_	_	7	7	7	2
ontinue Factors	Ω	2	7	-	_	_	_	_	_	_	_	_	_	-	_	_	_	_	_	7	7	7	7	7	7	7	7	7	7	2	7
Table C.1 (Continued Factors	C	2	7	_	_	_	_	-	_	_	_	_	_	_	_	-	_	_	_	_	_	-	_	_	_	_	_		_	_	-
اد د	В	2	7	_	_			-	-	_	_	_	_	-	-	-	-	-	_	_	_	_	-	_		-	_	-	-		-
Tab	A	4	4	S	'n	Ŝ	Ś	Ş	'n	5	Ċ	'n	'n	'n	'n	Ċ	'n	'n	'n	'n	'n	iCi	'n	10	ır,	'n	'n	·C	ır.	ıc.	ır.

		ı																													
	10	923	923	1586	1586	4033	4033	5518	5518	4165	4165	5650	5650	6474	6474	11175	11175	9099	9099	11307	11307	4239	4239	5925	5925	4371	4371	6057	6057	6832	6832
	6	791	791	1322	1322	4070	4070	5591	5591	4202	4202	5723	5723	6409	6409	11041	11041	6541	6541	11173	111173	4005	4005	5460	5460	4137	4137	5592	5592	6541	6541
	8	765	765	1275	1275	3985	3985	5422	5422	4117	4117	5554	5554	6620	6620	11474	11474	6752	6752	11606	11606	4486	4486	6421	6421	4618	4618	6553	6553	6969	6969
	7	853	853	1450	1450	3950	3950	5354	5354	4082	4082	5486	5486	6199	6199	11467	11467	6751	6751	11599	11599	4216	4216	5887	5887	4348	4348	6109	6109	6367	6367
ıtion	9	731	731	1208	1208	4000	4000	5437	5437	4132	4132	5569	5569	6310	6310	10852	10852	6442	6442	10984	10984	3996	3996	5442	5442	4128	4128	5574	5574	6237	6237
Replication	5	674	674	1088	1088	3956	3956	5366	5366	4088	4088	5498	5498	6568	6568	11362	11362	00/2	0029	11494	11494	4120	4120	5695	5695	4252	4252	5827	5827	6187	6187
	4	741	741	1221	1221	4094	4094	5639	5639	4226	4226	5771	5771	6480	6480	11190	11190	6612	6612	11322	11322	1044	1044	5541	5541	1176	1176	5673	5673	6473	6473
	3	919	919	926	926	4011	4011	5481	5481	4143	4143	5613	5613	6454	6454	11134	11134	9859	9859	11266	11266	3919	3919	5281	5281	1051	4051	5413	5413	8189	8189
	2	999	999	1077	1077	4057	4057	5563	5563	4189	4189	5695	5695	6498	6498	11226	11226	6630	6630	11358	11358	3888	3888	5226	5226	4020	4020	5358	5358	5907	5907
	1	975	975	1695	1695	3989	3989	5429	5429	4121	4121	5561	5561	6538	6538	11293	11293	0299	0299	11425	11425	4268	4268	5993	5993	4400	4400	6125	6125	6604	6604
	i																														
	=	_	7	-	7	7	7	-	7	_	7	_	7	-	7	-	7	-	7		7		7		7	_	7		7	_	7
	미	_	_	7	7	-	_	7	7		_	7	7	-		7	7	_	-	7	7	-	_	7	7		-	7	C 1	_	-
_	ഥ	7	7	7	7	-	_	_	_	7	7	7	7	-	-	_		7	7	7	7	-		_	-	7	7	7	7	_	
ontinued Factors	Ш	7	7	7	7	~	-	-	_	_		—	-	7	7	7	7	7	7	7	7	-	-	-	-	_	_	_	_	7	7
Conti Fac		7	7	7	7	~	_	_	-	_	_		_	-		_	_	_	_	_	_	7	7	7	7	7	7	7	7	7	7
) [:	ပ	—	-	-	_	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
Table C.1 (Continued Factors	m	_	_	_	_	~	_	-	_	_	-	-		-	_	_	_		_	_	-	-	-		-	_	_	_	_	_	_
Tat	<	S	'n	S	'n	S	'n	'n	S	'n	'n	'n	ı,	S	'n	'n	'n	IC.	'n	'n	v.	' C	v.	v.	ıC.	ır,	r,	ir.	ır.	ic.	r.

	10	11902	11902	6964	6964	12034	12034	427	427	562	562	475	475	610	019	736	736	1261	1261	784	784	1309	1309	476	476	659	659	524	524	707	707
	6	11293	11293	6673	6673	11425	11425	442	442	592	592	490	490	640	640	700	700	1192	1192	748	748	1240	1240	427	427	562	562	475	475	610	019
	∞	12159	12159	7101	7101	12291	12291	433	433	574	574	481	481	622	622	619	619	1150	1150	727	727	1198	1198	436	436	580	580	484	484	628	628
	7	10951	10951	6499	6499	11083	11083	400	400	508	508	448	448	556	556	694	694	1180	1180	742	742	1228	1228	981	180	675	675	534	534	723	723
ation	9	10689	68901	6369	6369	10821	10821	415	415	538	538	463	463	586	586	742	742	1273	1273	790	790	1321	1321	407	407	521	521	455	455	569	569
Replic	5 6	10597	10597	6319	6319	10729	10729	412	412	532	532	460	460	580	580	733	733	1258	1258	781	781	1306	1306	500	500	707	707	548	548	755	755
	4	11177	111177	6605	9099	11309	11309	427	427	562	562	475	475	610	610	200	200	1192	1192	748	748	1240	1240	467	467	638	638	515	515	989	989
	3	10857	10857	6450	6450	10989	10989	436	436	580	280	484	484	628	879	721	721	1234	1234	692	692	1282	1282	476	476	659	659	524	524	707	707
	2	10044	10044	6039	6039	10176	10176	415	415	538	538	463	463	989	586	692	692	1172	1172	740	740	1220	1220	388	388	484	† 8†	136	436	532	532
	1	11440	11440	6736	6736	11572	11572	419	419	545	545	467	467	593	593	703	703	1195	1195	751	751	1243	1243	496	496	700	700	544	544	748	748
	,	ı																													
	Н	-	7	_	7	-	2	_	2	-	2	_	7	~	7	_	2	_	7	_	2	_	2	_	7	_	7	_	2	_	7
		2	7	_		. 5	2	_		7	7			2	2	_	_	2	7	_		7	7	_	_	_	- 2	_	-	2	7
(pg s	, F	1		2		7	7			_		7	7	7						7	7	2	7	_	_	_	_	_	-	-	-
ntinuec Factors) E	2 2	7	2	7	2	2	_	_	_	_	_	_	_	_	- 2	- 2	_	7	7	_	-	_	~	_	7	~	_	7	7	
(Con	C D	2 2	7	2	7		,,	_		_	_		_		_		_	_	_	_	_	_	_	_	_	_	_	_	_	_	_
C.1	B (_			2	7	2	7	5	7	7	7	7	2	2	2	2	2	7	7	7	7	7	7	7	7	7	7
Table C.1 (Continued Factors	A	ĸ	Ŋ	Ś	5	S	S	Ś	Ś	'n						'n					'n				'n	'n	S	S	'n	'n	'n

	10	875	875	1538	1538	923	923	1586	1586	4033	4033	5518	5518	4165	4165	5650	5650	6474	6474	11175	11175	9099	9099	11307	11307	4239	4239	5925	5925	4371	4371
	6	743	743	1274	1274	791	791	1322	1322	4070	4070	5591	5591	4202	4202	5723	5723	6409	6409	11041	11041	6541	6541	11173	11173	4005	4005	5460	5460	4137	4137
	8	717	717	1227	1227	765	765	1275	1275	3985	3985	5422	5422	4117	4117	5554	5554	6620	6620	11474	11474	6752	6752	11606	11606	4486	4486	6421	6421	4618	4618
	7	805	805	1402	1402	853	853	1450	1450	3950	3950	5354	5354	4082	4082	5486	5486	6619	6199	11467	11467	6751	6751	11599	11599	4216	4216	5887	5887	1348	1348
ation	9	683	683	1160	1160	731	731	1208	1208	4000	4000	5437	5437	4132	4132	5569	5569	6310	6310	10852	10852	6442	6442	10984	10984	3996	3996	5442	5442	4128	4128
Replication	5	979	979	1040	1040	674	674	1088	1088	3956	3956	5366	5366	4088	4088	5498	5498	6568	8959	11362	11362	0029	0029	11494	11494	4120	4120	5695	5695	4252	4252
	4	693	693	1173	1173	741	741	1221	1221	4094	4094	5639	5639	4226	4226	5771	5771	6480	6480	11190	11190	6612	6612	11322	11322	4044	4044	5541	5541	4176	4176
	3	268	268	928	928	919	919	926	926	4011	4011	5481	5481	4143	4143	5613	5613	6454	6454	11134	11134	9859	9859	11266	11266	3919	3919	5281	5281	1021	1051
	2	618	819	1029	1029	999	999	1077	1077	4057	4057	5563	5563	4189	4189	5695	5695	6498	6498	11226	11226	0630	6630	11358	11358	3888	3888	\$226	5226	4020	4020
	-	927	927	1647	1647	975	975	1695	1695	3989	3989	5429	5429	4121	4121	5561	5561	6538	6538	11293	11293	0299	0299	11425	11425	4268	4268	5993	5993	4400	4400
	Ξ	_	2	_	2	_	2	_	2	_	2	_	2	_	2	_	2	_	2	_	2	_	2	_	7	_	7	_	7	_	7
	g	_		7	7	_	_	7	7	_		7	7	_	_	7	7	_	_	7	7	_	_	7	C 1	_	_	~ 1	CI	_	_
	ıı	_	-		_	7	7	7	7	_		-	_	7	7	7	7	_	_		-	7	7	C 1	7	_	_		_	7	7
nued) ors	田	7	7	7	7	7	7	7	7		_		_	_	_	_		7	7	7	7	7	7	7	7	_	_	_	_	_	_
Table C.1 (Continued Factors		7	7	7	7	7	7	7	7	_		-	_	_	_			_	-		-		-	_	_	7	7	7	7	7	7
1 (C	ပ	_		_	-	_		_	_	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	C1
e. C.	m	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
Tabl	A	2	Ç	5	2	5	S	'n	S	'n	S	S	'n	'n	S	Ś	5	S	S	S	'n	S	S	Ŋ	5	Ċ	S	'n	'n	'n	'n

able C.1 (Continued) Factors	nued) ctors	nued) ctors	(Replic	ation				
B	ပ က	Ω	ы	ഥ	ß	н		2	3	4	5		7	8	6	10
2	2	2	_	2	2	1	6125	5358	5413	5673	5827	5574	6109	6553	5592	6057
7	7	7	~	7	7	2	6125	5358	5413	5673	5827		6019	6553	5592	6057
7	7	7	7		-		6604	5907	6318	6473	6187		6367	6969	6541	6832
7	7	7	7	_	_	2	6604	5907	6318	6473	6187		6367	6969	6541	6832
2	7	7	7	_	7		11440	10044	10857	11177	10597		10951	12159	11293	11902
7	7	7	7	_	7	2	11440	10044	10857	11177	10597		10951	12159	11293	11902
7	7	7	7	7	-	-	6736	6039	6450	9999	6319		6499	7101	6673	6964
7	2	7	7	7	_	2	6736	6039	6450	6605	6319		6499	7101	6673	6964
7	7	7	7	7	7	_	11572	10176	68601	11309	10729		11083	12291	11425	12034
2	2	2	2	2	2	2	11572	10176	10989	11309	10729		11083	12291	11425	12034

APPENDIX D RESULTS OF TUKEY TESTS FOR SIGNIFICANCE

c=1; d=1; e=1; f=1; g=1; h=1.

Alpha= 0.05 df= 89 MSE= 1.278904 Critical Value of Studentized Range= 4.590 Minimum Significant Difference= 1.6504 WARNING: Cell sizes are not equal. Harmonic Mean of cell sizes= 9.89011

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	7.2610	10	9
Α	7.2610	10	10
Α	6.9480	10	7
В	4.1770	10	8
В	3.4940	10	1
В	3.4078	9	3
В	2.9620	10	5
В	2.8430	10	4
В	2.8080	10	2
С	1.0000	10	6

c=1; d=1; e=1; f=1; g=1; h=2.

Alpha= 0.05 df= 90 MSE= 1.400902

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 1.7173

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	7.2610	10	9
Α	7.2610	10	10
Α	6.9480	10	7
В	4.1770	10	8
В	3.8770	10	3
В	3.4180	10	I
В	3.2020	10	5
В	2.8430	10	4
В	2.7950	10	2
С	1.0000	10	6

c=1; d=1; e=1; f=1; g=2; h=1.

Alpha= 0.05 df= 89 MSE= 2.11628

Critical Value of Studentized Range= 4.590

Minimum Significant Difference= 2.1231

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.89011

Tukey	Grouping	Mean	Sample Size	Solution Approach
	Α	9.7040	10	9
	Α	9.7040	10	10
	В	7.4720	10	7
	C	4.8480	10	8
	C	3.9078	9	3
	C	3.5310	10	l
	С	3.2260	10	5
D	C	2.9440	10	4
D	C	2.8370	10	2
	D	1.0000	10	6

c=1; d=1; e=1; f=1; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 2.134932

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 2.1201

Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	9.7040	10	9
	A	9.7040	10	10
	В	7.4720	10	7
	С	4.8480	10	8
	С	4.2100	10	5
	С	4.0270	10	3
	С	3.4030	10	l
D	С	2.9440	10	4
D	С	2.8370	10	2
	D	1.0000	10	6

c=1; d=1; e=1; f=2; g=1; h=1.

Alpha= 0.05 df= 81 MSE= 0.08294

Critical Value of Studentized Range= 4.507

Minimum Significant Difference= 0.4105

Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	2.4670	10	7
В	Α	2.1380	10	2
В	Α	2.1040	10	8
В	С	1.9690	10	1
В	C	1.8910	10	10
В	С	1.8910	10	9
В	С	1.8210	10	4
	C	1.6080	10	5
	D	1.0000	10	6

c=1; d=1; e=1; f=2; g=1; h=2.

Alpha= 0.05 df= 90 MSE= 0.087763

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.4298

Tuke	ey Grouping	Mean	Sample Size	Solution Approach
	Α .	2.3770	10	7
В	Α	2.0850	10	3
В	Α	2.0270	10	8
В	Α	2.0000	10	2
В	Α	1.9480	10	1
	В	1.8230	10	10
	В	1.8230	10	9
	В	1.7160	10	4
	В	1.6870	10	5
	С	1.0000	10	6

c=1; d=1; e=1; f=2; g=2; h=1.

Alpha= 0.05 df= 81 MSE= 0.095523

Critical Value of Studentized Range= 4.507

Minimum Significant Difference= 0.4405

Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	2.6790	10	7
В	Α	2.3450	10	10
В	Α	2.3450	10	9
В	С	2.1530	10	8
В	С	2.0600	10	2
В	С	1.9740	10	1
	С	1.8490	10	4
	С	1.7460	10	5
	D	1.0000	10	6

c=1; d=1; e=1; f=2; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 0.114818

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.4917

Means with the same letter are not significantly different.

	Tukey G	rouping	Mean	Sample Size	Solution Approach
		Α	2.6270	10	7
	В	Α	2.4450	10	5
	В	Α	2.4370	10	3
В	Α	C	2.2990	10	10
В	Α	C	2.2990	10	9
	В	C	2.1130	10	8
	В	C	2.0370	10	i
	В	C	2.0190	10	2
		C	1.8240	10	4
		D	1.0000	10	6

c=1; d=1; e=2; f=1; g=1; h=1.

Alpha= 0.05 df= 53 MSE= 2.258074

Critical Value of Studentized Range= 4.181

Minimum Significant Difference= 2.0052

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.818182

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	9.0880	10	9
Α	9.0880	10	10
Α	7.1420	10	8
В	4.9840	10	7
С	2.7356	9	5
C	1.0000	10	6

c=1; d=1; e=2; f=1; g=1; h=2.

Alpha= 0.05 df= 63 MSE= 2.016383

Critical Value of Studentized Range= 4.307

Minimum Significant Difference= 1.9341

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	9.0880	10	10
Α	9.0880	10	9
В	7.1240	10	8
С	4.9840	10	7
С	4.1210	10	3
С	3.2340	10	5
D	1.0000	10	6

c=1; d=1; e=2; f=1; g=2; h=1.

Alpha= 0.05 df= 54 MSE= 6.008689

Critical Value of Studentized Range= 4.178

Minimum Significant Difference= 3.2388

Means with the same letter are not significantly different.

Tukey	y Grouping	Mean	Sample Size	Solution Approach
	Α	13.623	10	9
	Α	13.623	10	10
	Α	12.594	10	8
	В	5.428	10	7
С	В	2.968	10	5
	С	1.000	10	6

c=1; d=1; e=2; f=1; g=2; h=2.

Alpha= 0.05 df= 63 MSE= 5.493531

Critical Value of Studentized Range= 4.307

Minimum Significant Difference= 3.1924

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	13.623	10	10
Α	13.623	10	9
Α	12.594	10	8
В	5.428	10	7
В	5.293	10	5
В	5.253	10	3
C	1.000	10	6

c=1; d=1; e=2; f=2; g=1; h=1.

Alpha= 0.05 df= 44 MSE= 0.129235

Critical Value of Studentized Range= 4.022

Minimum Significant Difference= 0.4623

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.782609

Tuk	ey Grouping	Mean	Sample Size	Solution Approach
	Α	2.2330	10	10
	Α	2.2330	10	9
В	Α	2.0210	10	7
	В	1.6670	10	8
	С	1.0000	9	6

c=1; d=1; e=2; f=2; g=1; h=2.

Alpha= 0.05 df= 72 MSE= 0.093456

Critical Value of Studentized Range= 4.415

Minimum Significant Difference= 0.4268

Means with the same letter are not significantly different.

Tuke	ey Grouping	Mean	Sample Size	Solution Approach
	Α	2.3520	10	9
	Α	2.3520	10	10
В	Α	2.1650	10	3
В	Α	2.1390	10	7
В	Α	1.9290	10	4
	В	1.8030	10	5
	В	1.7610	10	8
	С	1.0000	10	6

c=1; d=1; e=2; f=2; g=2; h=1.

Alpha= 0.05 df= 45 MSE= 0.096517

Critical Value of Studentized Range= 4.018

Minimum Significant Difference= 0.3948

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
A	3.4540	10	10
Α	3.4540	10	9
В	2.4460	10	7
В	2.2220	10	8
С	1.0000	10	6

c=1; d=1; e=2; f=2; g=2; h=2.

Alpha= 0.05 df= 69 MSE= 0.080494

Critical Value of Studentized Range= 4.421

Minimum Significant Difference= 0.4071

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.491525

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	3.0690	10	9
	Α	3.0690	10	10
	В	2.4190	10	3
С	В	2.1760	01	7
С	В	2.0860	10	5
	С	1.9680	10	8
	С	1.9271	7	4
	D	1.0000	10	6

c=1; d=2; e=1; f=1; g=1; h=1.

Alpha= 0.05 df= 90 MSE= 3.688227 Critical Value of Studentized Range= 4.588 Minimum Significant Difference= 2.7865

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	10.6290	10	7
Α	10,1890	10	10
Α	10.1890	10	9
Α	8.1850	10	8
В	2.8740	10	3
В	2.7850	10	1
В	2.2130	10	4
В	2.1690	10	2
В	2.1380	10	5
В	1.0000	10	6

c=1; d=2; e=1; f=1; g=1; h=2.

Alpha= 0.05 df= 90 MSE= 4.113345

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 2.9427

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
A	11.2870	10	7
Α	10.8270	10	10
Α	10.8270	10	9
Α	8.7560	10	8
В	3,1280	10	3
В	2.8230	10	1
В	2.3260	10	4
В	2.3020	10	2
В	2.1670	10	5
В	1.0000	10	6

c=1; d=2; e=1; f=1; g=2; h=1.

Alpha= 0.05 df= 90 MSE= 6.275634

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 3.6348

Tukey Grouping	Mean	Sample Size	Solution Approach
A	13.783	10	9
A	13.783	10	10
Α	12.070	10	7
Α	11.613	10	8
В	2.976	10	3
В	2.545	10	1
В	2.435	10	5
В	2.219	10	4
В	2.162	10	2
В	1.000	10	6

c=1; d=2; e=1; f=1; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 7.390149

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 3.9444

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	14.662	10	9
Α	14.662	10	10
Α	12.848	10	7
Α	12.433	10	8
В	3.119	10	3
В	2.700	10	1
В	2.583	10	5
В	2.332	10	4
В	2.295	10	2
В	1.000	10	6

c=1; d=2; e=1; f=2; g=1; h=1.

Alpha= 0.05 df= 90 MSE= 0.562097

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 1.0878

Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	A	3.6790	10	7
	Α	3.1350	10	8
В	Α	2.6250	10	9
В	Α	2.6250	10	10
В	C	1.9900	10	3
В	C	1.9460	10	2
В	С	1.8850	10	4
В	C	1.8770	10	l
	С	1.4100	10	5
	С	1.0300	10	6

c=1; d=2; e=1; f=2; g=1; h=1.

Alpha= 0.05 df= 90 MSE= 0.844415

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 1.3333

	Tukey Grouping		Mean	Sample Size	Solution Approach
		Α	3,6680	10	7
	В	Α	3.1200	10	8
В	Α	С	2.6250	10	9
В	Α	С	2.6250	10	10
В	D	C	2.1740	10	3
В	D	C	1.9610	10	2
В	D	C	1.9550	10	1
В	D	С	1.8650	10	4
	D	С	1.6440	10	5
		D	1.0000	10	6

c=1; d=2; e=1; f=2; g=2; h=1.

Alpha= 0.05 df= 88 MSE= 0.807384

Critical Value of Studentized Range= 4.591

Minimum Significant Difference= 1.3207

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.756098

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	4.1700	10	7
Α	3.5390	10	8
Α	3.4580	10	9
Α	3.4580	10	10
В	1.9537	8	3
В	1.9040	10	2
В	1.8710	10	1
В	1.8710	10	4
В	1.7100	10	5
В	1.0000	10	6

c=1; d=2; e=1; f=2; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 0.646059

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 1.1662

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	4.3230	10	7
Α	3.6790	10	8
Α	3.5780	10	9
Α	3.5780	10	10
В	2.3580	10	3
В	2.2020	10	5
С В	1.9850	10	2
С В	1.9470	10	1
C B	1.9410	10	4
С	1.0000	10	6

c=1; d=2; e=2; f=1; g=1; h=1.

Alpha= 0.05 df= 77 MSE= 4.184745

Critical Value of Studentized Range= 4.514

Minimum Significant Difference= 2.9956

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.501466 Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	13.5370	10	10
	A	13.5370	10	9
В	Α	11.9770	10	8
	В	9.4100	10	7
	C	2.1956	9	5
	С	1.9980	10	4
	С	1.8650	8	1
	C	1.8322	9	2
	C	1.0000	10	6

c=1; d=2; e=2; f=1; g=1; h=2.

Alpha= 0.05 df= 89 MSE= 3.954504 Critical Value of Studentized Range= 4.590

Minimum Significant Difference= 2.9022

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.89011

Means with the same letter are not significantly different.

Tuk	ey Grouping	Mean	Sample Size	Solution Approach
	Α	13.8130	10	9
	A	13.8130	10	10
В	Α	12.2160	10	8
	В	9.5720	10	7
	С	3.3900	10	5
	С	3.1722	9	3
	С	2.1000	10	4
	С	2.0430	10	l
	C	2.0350	10	2
	С	1.0000	10	6

c=1; d=2; e=2; f=1; g=2; h=1.

Alpha= 0.05 df= 76 MSE= 11.81509

Critical Value of Studentized Range= 4.515

Minimum Significant Difference= 5.0721

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.364162

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	23.240	10	8
Α	22.484	10	9
Α	22.484	10	10
В	13.461	10	7
С	2.456	8	5
С	2.045	10	4
С	2.004	8	l
С	1.854	9	2
С	1.000	10	6

c=1; d=2; e=2; f=1; g=2; h=2.

Alpha= 0.05 df= 89 MSE= 9.685818

Critical Value of Studentized Range= 4.590

Minimum Significant Difference= 4.542

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.89011

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	24.183	10	8
Α	23.405	10	9
Α	23.405	10	10
В	13.908	10	7
С	4.338	10	5
С	3.897	9	3
С	2.228	10	1
C	2.149	10	4
С	2.097	10	2
С	1.000	10	6

c=1; d=2; e=2; f=2; g=1; h=1.

Alpha= 0.05 df= 64 MSE= 0.544886

Critical Value of Studentized Range= 4.540

Minimum Significant Difference= 1.5571

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 4.632353

Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	3.1890	10	10
	Α	3.1890	10	9
В	A	3.0290	10	7
В	Α	2.9070	10	8
В	C	1.6229	7	l
В	С	1.5800	10	2
В	С	1.5400	1	5
	С	1.3420	5	4
	С	1.0000	10	6

c=1; d=2; e=2; f=2; g=1; h=2.

Alpha= 0.05 df= 89 MSE= 0.461552

Critical Value of Studentized Range= 4.590

Minimum Significant Difference= 0.9915

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.89011

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	3.1000	10	9
Α	3.1000	10	10
Α	2.9470	10	7
Α	2.8150	10	8
В	1.8000	9	3
В	1.7070	10	1
В	1.6660	10	4
В	1.6220	10	5
В	1.5550	10	2
В	1.0000	10	6

c=1; d=2; e=2; f=2; g=2; h=1.

Alpha= 0.05 df= 66 MSE= 1.234238

Critical Value of Studentized Range= 4.535

Minimum Significant Difference= 1.8377

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 7.517401

TIOCHIS TITLES CALL SCATTLE TOLLE		5	• • • • • • • • • • • • • • • • • • • •
Tukey Grouping	Mean	Sample Size	Solution Approach
Α	4.9290	10	10
Α	4.9290	10	9
Α	4.1180	10	8
Α	4.0210	10	7
В	1.4787	8	1
В	1.4467	9	2
В	1.4060	5	4
В	1.3725	4	5
В	1.0000	9	6

c=1; d=2; e=2; f=2; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 1.213862 Critical Value of Studentized Range= 4.588 Minimum Significant Difference= 1.5986

Means with the same letter are not significantly different.

Tuk	ey Grouping	Mean	Sample Size	Solution Approach
	A	4.6280	10	9
	Α	4.6280	10	10
В	Α	3.8940	10	8
В	Α	3.7830	10	7
В	С	2.4140	10	3
	С	2.1690	10	5
	С	1.5500	10	4
	C	1.4610	10	1
	С	1.3950	10	2
	C	1.0180	10	6

c=2; d=1; e=1; f=1; g=1; h=1.

Alpha= 0.05 df= 90 MSE= 0.099806

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.4584

Means with the same letter are not significantly different.

Tuk	key Grouping	Mean	Sample Size	Solution Approach
	Α	10.8840	10	9
	Α	10.8840	10	10
	В	7.6160	10	7
	С	6.5240	10	8
	D	2.5150	10	3
Ε	D	2.3820	10	5
E	D	2.3220	10	1
Ε	F	1.9620	10	2
	F	1.7810	10	4
	G	1.0000	10	6

c=2; d=1; e=1; f=1; g=1; h=2.

Alpha= 0.05 df= 90 MSE= 0.124711

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.5124

Tukey	Grouping	Mean	Sample Size	Solution Approach
	Α	10,9400	10	9
	Α	10.9400	10	10
	В	7.6530	10	7
	C	6.5510	10	8
	D	2.8550	10	5
Е	D	2.5220	10	3
E	F	2.2800	10	1
	F	1.9810	10	2
	F	1.7920	10	4
	G	1.0000	10	6

c=2; d=1; e=1; f=1; g=2; h=1.

Alpha= 0.05 df= 87 MSE= 0.528572

Critical Value of Studentized Range= 4.592

Minimum Significant Difference= 1.0782

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.589041

Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	14.9810	10	9
	Α	14,9810	10	10
	Α	14.5760	10	8
	В	7.9440	10	7
	С	2.8586	7	3
	С	2.8370	10	5
	С	2.4410	10	l
	С	2.1020	10	2
D	С	1.8020	10	4
	D	1.0000	10	6

c=2; d=1; e=1; f=1; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 0.584392

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 1.1092

Means with the same letter are not significantly different.

Tukey	Grouping	Mean	Sample Size	Solution Approach
	A	15.0680	10	9
	Α	15.0680	10	10
	A	14.6640	10	8
	В	7.9890	10	7
	C	3.7210	10	5
D	C	2.8770	10	3
	D	2.3440	10	l
D	E	2.0830	10	2
D	Е	1.8140	10	4
	E	1.0000	10	6

c=2; d=1; e=1; f=2; g=1; h=1.

Alpha= 0.05 df= 83 MSE= 0.049005

Critical Value of Studentized Range= 4.598

Minimum Significant Difference= 0.3575

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 8.108108

vicans (vitil the same is	etter are not sig	simileantly unite	CIII.
Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	2.9850	10	7
	Α	2.8880	10	10
	Α	2.8880	10	9
	В	1.7890	10	8
С	В	1.5970	10	2
C	В	1.5500	3	3
С	В	1.4750	10	1
	С	1.3760	10	5
C	D	1.3190	10	4
	D	1.0000	10	6

c=2; d=1; e=1; f=2; g=1; h=2.

Alpha= 0.05 df= 90 MSE= 0.048486 Critical Value of Studentized Range= 4.588 Minimum Significant Difference= 0.3195

Means with the same letter are not significantly different.

	Tuke	y Grouping	Mean	Sample Size	Solution Approach
		A	2.99700	10	7
		Α	2.90100	10	10
		Α	2.90100	10	9
		В	1.79800	10	8
	C	В	1.66100	10	3
C	В	D	1.58000	10	2
C	В	D	1.56700	10	l
	С	D	1.44700	10	5
	E	D	1.31600	10	4
		Е	1.00000	10	6

c=2; d=1; e=1; f=2; g=2; h=1.

Alpha= 0.05 df= 81 MSE= 0.051454

Critical Value of Studentized Range= 4.507

Minimum Significant Difference= 0.3233

Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	4.0440	10	10
	Α	4.0440	10	9
	В	3.2540	10	7
	С	1.9510	10	8
D	С	1.7200	10	2
D	С	1.6680	10	l
	D	1.5930	10	5
	D	1.4580	10	4
	Е	1.0000	10	6

c=2; d=1; e=1; f=2; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 0.052913

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.3338

Tukey	Grouping	Mean	Sample Size	Solution Approach
	Α	4.0350	10	9
	Α	4.0350	10	10
	В	3.2490	10	7
	C	1.9480	10	8
	С	1.8930	10	5
	С	1.8610	10	3
D	С	1.7470	10	2
D	С	1.6290	10	1
	D	1.4550	10	4
	E	1.0000	10	6

c=2; d=1; e=2; f=1; g=1; h=1.

Alpha= 0.05 df= 45 MSE= 0.55786

Critical Value of Studentized Range= 4.018

Minimum Significant Difference= 0.9491

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	13.1560	10	10
Α	13.1560	10	9
В	6.8230	10	8
C	3.3870	10	7
D	1.0000	10	6

c=2; d=1; e=2; f=1; g=1; h=2.

Alpha= 0.05 df= 58 MSE= 0.470839

Critical Value of Studentized Range= 4.319

Minimum Significant Difference= 1.0019

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 8.75

Means with the same letter are not significantly different.

Tukey Grouping	Mean San	iple Size	Solution Approach
Α	13.0970	10	10
Α	13.0970	10	9
В	6.7930	10	8
С	4.0480	5	.3
С	3.3690	10	7
С	3.3510	10	5
D	1.0000	10	6

c=2; d=1; e=2; f=1; g=2; h=1.

Alpha= 0.05 df= 45 MSE= 2.380181

Critical Value of Studentized Range= 4.018

Minimum Significant Difference= 1.9605

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	21.0740	10	10
A	21.0740	10	9
В	15,3450	10	8
С	4.9370	10	7
D	1.0000	10	6

c=2; d=1; e=2; f=1; g=2; h=2.

Alpha= 0.05 df= 54 MSE= 2.202189

Critical Value of Studentized Range= 4.178

Minimum Significant Difference= 1.9608

Tukey Grouping	Mean Sar	nple Size	Solution Approach
Α	21.0740	10	9
Α	21.0740	10	10
В	15.3450	10	8
С	5.3650	10	5
С	4.9370	10	7
D	1.0000	10	6

c=2; d=1; e=2; f=2; g=1; h=1.

Alpha= 0.05 df= 45 MSE= 0.017622

Critical Value of Studentized Range= 4.018

Minimum Significant Difference= 0.1687

Means with the same letter are not significantly different.

Tukey Grouping	Mean Sa	mple Size	Solution Approach
Α	3.75300	10	10
Α	3.75300	10	9
В	1.68200	10	7
С	1.08800	10	8
С	1.01500	10	6

c=2; d=1; e=2; f=2; g=1; h=2.

Alpha= 0.05 df= 63 MSE= 0.012254

Critical Value of Studentized Range= 4.307

Minimum Significant Difference= 0.1508

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	3.72300	10	10
Α	3.72300	10	9
В	2.12600	10	3
С	1.73100	10	5
C	1.66800	10	7
D	1.08100	10	8
ח	1.01300	10	6

c=2; d=1; e=2; f=2; g=2; h=1.

Alpha= 0.05 df= 45 MSE= 0.093108

Critical Value of Studentized Range= 4.018

Minimum Significant Difference= 0.3877

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	5.9040	10	10
Α	5.9040	10	9
В	1.9810	10	7
С	1.4540	10	8
D	1.0040	10	6

c=2; d=1; e=2; f=2; g=2; h=2.

Alpha= 0.05 df= 63 MSE= 0.08188

Critical Value of Studentized Range= 4.307

Minimum Significant Difference= 0.3897

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	5.8880	10	10
Α	5.8880	10	9
В	3.0500	10	3
В	2.7310	10	5
С	1.9750	10	7
D	1.4420	10	8
Е	1.0000	10	6

c=2; d=2; e=1; f=1; g=1; h=1.

Alpha= 0.05 df= 90 MSE= 0.314511

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.8137

Means with the same letter are not significantly different.

Tukey C	Grouping	Mean	Sample Size	Solution Approach
	Α	13.271	0 10	9
	A	13.271	0 10	10
	В	9.9320	10	7
	В	9.3430	10	8
	C	1.9430	10	5
	C	1.8550	10	3
D	C	1.6450	10	1
D	C	1.4180	10	2
D	C	1.4020	10	4
	D	1 0000	10	6

c=2; d=2; e=1; f=1; g=1; h=2.

Alpha= 0.05 df= 90 MSE= 0.319858

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.8206

Means with the same letter are not significantly different.

Tuke	y Grouping	Mean	Sample Size	Solution Approach
	Α	13.2710	10	9
	Α	13.2710	10	10
	В	9.9320	10	7
	В	9.3320	10	8
	С	2.0590	10	5
	C	1.8790	10	3
D	С	1.6040	10	1
D	С	1.4180	10	2
D	С	1.4020	10	4
	D	1.0000	10	6

c=2; d=2; e=1; f=1; g=2; h=1.

Alpha= 0.05 df= 90 MSE= 1.181922

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 1.5774

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	19.8430	10	8
Α	18.3230	10	9
Α	18.3230	10	10
В	11.2220	10	7
C	2.2910	10	5
С	1.8940	10	3
С	1.6400	10	1
C	1.4200	10	2
C	1.4040	10	4
С	1.0000	10	6

c=2; d=2; e=1; f=1; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 1.197751 Critical Value of Studentized Range= 4.588 Minimum Significant Difference= 1.588

Means with the same letter are not significantly different.

Tul	cey Grouping	Mean	Sample Size	Solution Approach
	Α	19.8430	10	8
	Α	18.3230	10	9
	Α	18.3230	10	10
	В	11.2220	10	7
	С	2.6660	10	5
D	C	1.9110	10	3
D	С	1.6030	10	1
D	C	1.4200	10	2
D	С	1.4040	10	4
	D	1.0000	10	6

c=2; d=2; e=1; f=2; g=1; h=1.

Alpha= 0.05 df= 90 MSE= 0.065586

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.3716

Means with the same letter are not significantly different.

Tuke	ey Grouping	Mean	Sample Size	Solution Approach
	Α	3.7230	10	7
	Α	3.4990	10	10
	Α	3.4990	10	9
	В	2.5330	10	8
	С	1.5080	10	3
	C	1.4110	10	5
D	С	1.3680	10	2
D	C	1.3580	10	1
D	C	1.3080	10	4
	D	1.0000	10	6

c=2; d=2; e=1; f=2; g=1; h=2.

Alpha= 0.05 df= 90 MSE= 0.062049

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.3614

Tukey	Grouping	Mean	Sample Size	Solution Approach
	Α	3.7580	10	7
	Α	3.5300	10	10
	Α	3.5300	10	9
	В	2.5560	10	8
	C	1.5390	10	3
	С	1.4650	10	1
	C	1.3920	10	2
D	C	1.3590	10	5
D	C	1.3070	10	4
	D	1.0000	10	6

c=2; d=2; e=1; f=2; g=2; h=1.

Alpha= 0.05 df= 89 MSE= 0.073258

Critical Value of Studentized Range= 4.590

Minimum Significant Difference= 0.395

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.89011

Means with the same letter are not significantly different.

Tukey	Grouping	Mean	Sample Size	Solution Approach
•	Α	4.7710	01	9
	Α	4.7710	10	10
	В	4.0350	10	7
	C	2.9670	10	8
	D	1.5556	9	3
	D	1.4930	10	5
	D	1.4680	10	1
E	D	1.3930	10	2
E	D	1.3110	10	4
	Е	1.0000	10	6

c=2; d=2; e=1; f=2; g=2; h=2.

Alpha= 0.05 df= 90 MSE= 0.062163

Critical Value of Studentized Range= 4.588

Minimum Significant Difference= 0.3618

Means with the same letter are not significantly different.

Tukey Grou	iping	Mean	Sample Size	Solution Approach
Α		4.7990	10	9
Α		4.7990	10	10
В		4.0570	01	7
C		2.9840	10	8
D		1.6720	10	5
D		1.6190	10	3
D		1.4680	10	1
D		1.4080	10	2
E D		1.3140	10	4
Е		1.0000	10	6

c=2; d=2; e=2; f=1; g=1; h=1.

Alpha= 0.05 df= 44 MSE= 23.43193

Critical Value of Studentized Range= 4.022

Minimum Significant Difference= 6.225

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.782609

Tukey Grouping	Mean	Sample Size	Solution Approach
A	18.537	10	10
Α	18.537	10	9
A	14.926	10	8
В	7.936	10	7
С	1.000	9	6

c=2; d=2; e=2; f=1; g=1; h=2.

Alpha= 0.05 df= 54 MSE= 4.875797

Critical Value of Studentized Range= 4.178

Minimum Significant Difference= 2.9176

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	19,9600	10	9
Α	19.9600	10	10
В	16.0920	10	8
С	8.6230	10	7
D	3.9230	10	5
E	1.0000	10	6

c=2; d=2; e=2; f=1; g=2; h=1.

Alpha= 0.05 df= 45 MSE= 17.01174

Critical Value of Studentized Range= 4.018

Minimum Significant Difference= 5.2412

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	37.231	10	8
Α	33.454	10	9
Α	33.454	10	10
В	13.631	10	7
C	1 000	10	6

c=2; d=2; e=2; f=1; g=2; h=2.

Alpha= 0.05 df= 54 MSE= 20.09254

Critical Value of Studentized Range= 4.178

Minimum Significant Difference= 5.9226

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	37.088	10	8
Α	33.301	10	9
Α	33.301	10	10
В	13.547	10	7
С	5.880	10	5
С	1.000	10	6

c=2; d=2; e=2; f=2; g=1; h=1.

Alpha= 0.05 df= 41 MSE= 1.055287

Critical Value of Studentized Range= 4.035

Minimum Significant Difference= 1.3953

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 8.823529

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	3.7220	10	10
Α	3.7220	10	9
В	2.1780	10	7
В	1.8590	10	8
В	1.0000	6	6

c=2; d=2; e=2; f=2; g=1; h=2.

Alpha= 0.05 df= 63 MSE= 0.086889

Critical Value of Studentized Range= 4.307

Minimum Significant Difference= 0.4015

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	5.0080	10	10
Α	5.0080	10	9
В	2.8960	10	7
С	2.4410	10	8
С	2.2420	10	3
C	2.0530	10	5
D	1.0000	10	6

c=2; d=2; e=2; f=2; g=2; h=1.

Alpha= 0.05 df= 42 MSE= 4.570735

Critical Value of Studentized Range= 4.030

Minimum Significant Difference= 2.8391

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.210526

Means with the same letter are not significantly different.

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	6.5120	10	10
Α	6.5120	10	9
В	3.3180	10	8
В	2.9500	10	7
В	1.0000	7	6

c=2; d=2; e=2; f=2; g=2; h=2.

Alpha= 0.05 df= 62 MSE= 0.519292

Critical Value of Studentized Range= 4.309

Minimum Significant Difference= 0.9898

WARNING: Cell sizes are not equal.

Harmonic Mean of cell sizes= 9.84375

Tukey Grouping	Mean	Sample Size	Solution Approach
Α	8.0390	10	10
Α	8.0390	10	9
В	4.0310	10	8
В	3.5690	10	7
В	3.3011	9	3
В	3.2260	10	5
С	1.0000	10	6

AUTOBIOGRAPHICAL STATEMENT

Padmanabhan Soundar was born on March 31, 1968 in Madras, India. He received a Bachelor of Technology in Mechanical Engineering from the Indian Institute of Technology at Madras in 1989 and a Master of Science in Industrial Engineering from the University of Missouri at Columbia in 1991.